

# LOW COST ACCESS TO NEAR SPACE (LCANS09): BRIDGING THE GAP..

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Eliot Young  
*Southwest Research Institute*  
Nov. 11, 2009

# **LOW COST ACCESS TO NEAR SPACE (LCANS09): Why Another Workshop?**

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- Goal: Hubble-like performance from the stratosphere. Develop the vis/UV capabilities for after HST.
- Goal: An observing facility in the stratosphere. Develop a pointed platform; let users attach their own detectors.
- Goal: Generate ideas for long duration missions (~100 days) made possible by airships or super-pressure balloons.
- Goal: Share expertise – most of the technology needed to fly diffraction-limited balloon-borne telescopes is mature.
- Workshop organizers: Eliot Young (SwRI), Robert Fesen (Dartmouth) and Qian Wu (NCAR).

# The LCANS09 Program: Highlights from 14 Talks

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## DAY ONE: MONDAY OCTOBER 26, 2009

### Session 1: Suborbital Science with High Altitude Balloons

- 8:40 am Welcome: Eliot Young
- 8:45 am Keynote Address: The Promise of LTA Science: Alan Stern (SwRI)
- 9:00 am The 2007 Toronto Workshop On Suborbital Science: Kimberly Strong (Univ. of Toronto)
- 9:30 am Capabilities of Zero-Pressure and Super-Pressure Balloons: Mike Smith (Aerostar)
- 10:00 am The BLAST Astrophysical Balloon Mission: Mark Devlin (Univ. of Pennsylvania)

### Session 2: Existing and Proposed Long-Duration LTA Platforms

- 11:00 am NASA's Super Pressure Balloon Program: David Pierce (NASA, Wallops Flight Facility)
- 11:30 am HiSentinel: A High Altitude, LTA Airship for MDC/ARSTRAT: Steve Smith (SwRI)
- 12:00 pm Hale-D and ISIS - DARPA's High Altitude Airships: Scott Hovarter (Lockheed Martin)
- 12:30 pm: Airship, Platforms, & High Racks; A Look at JPA Vehicles: John Powell (JP Aerospace)

### Session 3: Lightweight Sensors and High Altitude Imaging

- 2:00 pm Lightweight Optical Imaging Systems: Steve Kendrick (Ball Aerospace)
- 2:30 pm Lightweight Optical Elements: Charles Kirk (ITT)
- 3:00 pm Imaging Quality as a Function of Altitude: Wes Traub (JPL)

### Session 4: Platform/Sensor Stabilization and Communication Systems

- 4:00 pm High-Resolution Imaging from Balloon-Borne Telescopes: Pietro Bernasconi (APL, Johns Hopkins)
- 4:25 pm A Low-Cost Star Tracker and Telescope Pointing System: Jeff Percival (Univ. of Wisconsin)
- 4:50 pm Stabilization of Balloon-Borne Telescopes: Larry Germann (Left Hand Design Corp)
- 5:15 pm Motion Correcting Imaging Detectors: Barry Burke (Lincoln Labs)

## DAY TWO: TUESDAY OCTOBER 27, 2009

### Session 5: Lightweight Instrumentation and Vehicle Communications

- 9:00 am Micro-Instrumentation for Lightweight Ballooning: Dwayne Orr (Columbia Science Balloon Facility)
- 9:25 am Lightweight Communication Systems: Kevin Shoemaker (Shoemaker Labs)
- 9:50 am Global Platform Communication: Tim Maclay (OrbComm)
- 10:15 am Small Balloon Payloads: Tim Lachenmeier (Near Space Corp.)

### Session 6: Astrophysics using High Altitude Science Platforms

- 11:10 am An Exoplanet Coronagraph on a Stratospheric Science Platform: Wes Traub (JPL)
- 11:35 am Interferometry at Altitude: Galaxies, Stars, & Exoplanets: Stephen Rinehart (NASA, GSFC)
- 12:00 pm HALO: A High Altitude Balloon-Borne Cosmology Mission: Jason Rhodes (JPL)
- 12:20 pm Optical Systems Using Polymer Membranes: Dan Marker (AFRL)

### Session 7: Solar and Planetary Stratospheric Telescopes

- 2:00 pm SUNRISE: A High Altitude Solar Telescope: Alice Lecinski (HAO, NCAR)
- 2:25 pm SCRIBE: A Low Cost Balloon-Borne Solar Observatory: Craig DeForest (SwRI)
- 2:50 pm Balloon-Borne Planetary Missions: Karl Hibbitts (JHU/APL)

### Session 8: Stratospheric Science Using High Altitude Vehicles

- 3:45 pm High Altitude Winds & Chemistry Studies using High Altitude Platforms: William Randel (NCAR)
- 4:10 pm F-P Interferometer Imagery for Cloud and Trace Gas Studies: Sam Yee (APL, Johns Hopkins)
- 4:35 pm High Altitude Driftsonde Ballooning Operations: Terry Hock (NCAR)
- 4:55 pm Balloon Applications for Spaceweather and Thermosphere Dynamics: Qian Wu (NCAR)



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# TALK OVERVIEWS: David Pierce (CSBF)

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- NASA Conducts 3 U.S. Campaigns (New Mexico, Texas) per year, plus
- Antarctica LDB Campaign, and either a Northern Hemisphere LDB (Sweden), or
- A mid-latitude LDB (Australia) campaign each year
- NASA's established Launch Sites and typical mission durations:

- Ft. Sumner, New Mexico ~2 days
- Sweden (66 degs N lat) ~5-7 days
- Australia (23 degs S lat) ~10-20 days
- Antarctica (77 degs S lat) ~40-50 days

	JAN	FEB	MAR	APR	MAY	JUN	JUL	AUG	SEP	OCT	NOV	DEC
Antarctica	■	■										■
New Mexico				■	■	■						
Texas							■	■				
Sweden		■	■		■	■						
New Mexico								■	■	■		
Australia				■	■	■					■	■

# TALK OVERVIEWS: David Pierce (CSBF)

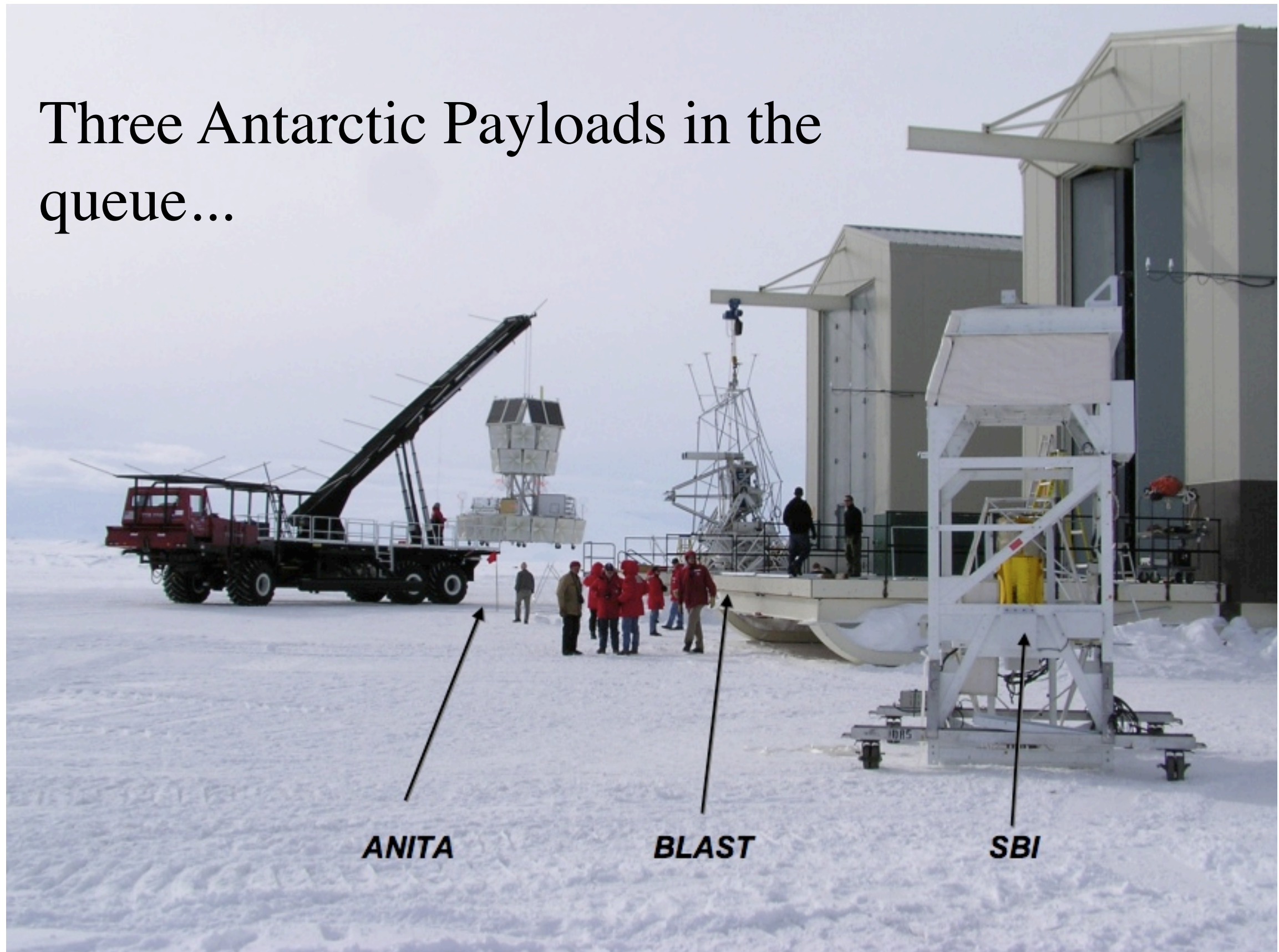
	<b>Conventional</b>	<b>LDB</b>	<b>ULDB*</b>
<b>Duration</b>	~ 2 days	40+ days	Up to 100 days
<b>Flight Opportunities</b>	~16 per year	3-6 per year	1 per year
<b>Suspended Capacity</b>	1650-8000 lbs		6000 lbs
<b>Float Altitude</b>	Up to 160,000 ft		Up to 110,000 ft
<b>Flight Support Systems</b>  <b>All NASA Flight Support Systems are highly reliable proven systems</b>	<b>CIP</b> •Line of Sight •300 kbps direct return	<b>SIP</b> •Over the Horizon •100 kbps TDRSS downlink	<b>CDM/SIP</b> •Over the Horizon •100 kbps TDRSS downlink
<b>Launch Locations</b>  <b>Operations Costs per flight, excluding Instrument</b>	Fort Sumner, NM; Palestine, Texas; Alice Springs, Australia  ROM \$ 100-250 K	Antarctica; Kiruna, Sweden; Alice Springs, Australia;  ROM \$ 250- 500 K	ROM \$ 500- 1000 K

\* Current development project ; 2MCF and 7MCF is considered qualified for flight



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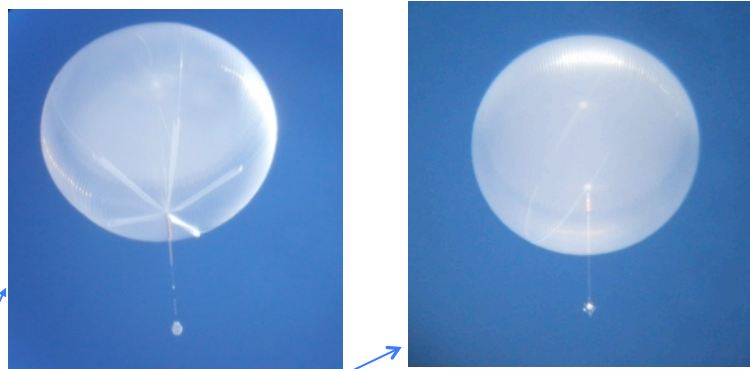
Three Antarctic Payloads in the queue...



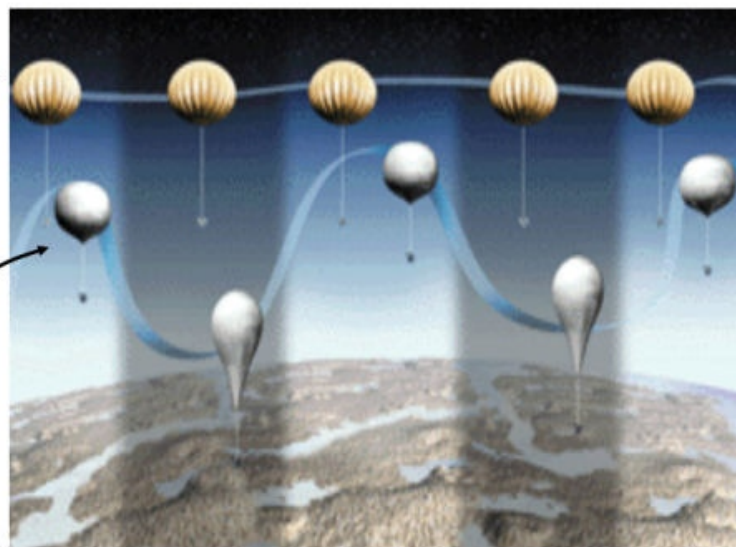


# TALK OVERVIEWS: David Pierce (CSBF)

## Advantages of Super-Pressure Balloons



Super-Pressure: Ultra Long Duration Balloon (ULDB)  
“Pumpkin”



Zero-Pressure Balloon

Zero-pressure balloons are vented at bottom,  $P_{\text{internal}} = P_{\text{external}}$

Expand and contract with sunlight, gas leaks out

Must drop ballast to maintain height

→ flight duration limited to 5–6 days in mid-latitudes

**Long flights only possible in polar summers**

Super-pressure balloons:  $P_{\text{in}} > P_{\text{out}}$   
~ 150 – 200 Pa typically

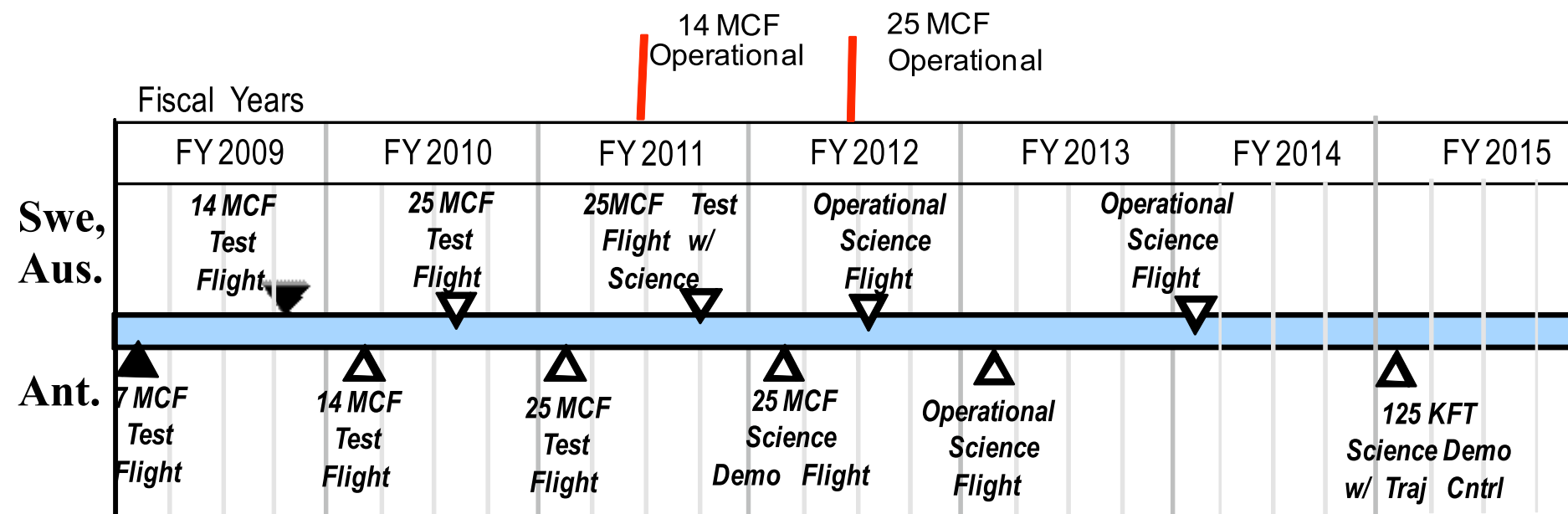
Maintain nearly constant volume and height (and shape) in day/night cycle  
Constant density volume is achieved allowing stable bobbing at a constant density altitude

No ballast needed, no loss of gas

**Can have long flights at ANY latitude**

# TALK OVERVIEWS: David Pierce (CSBF)

## ULDB Flight Development Schedule

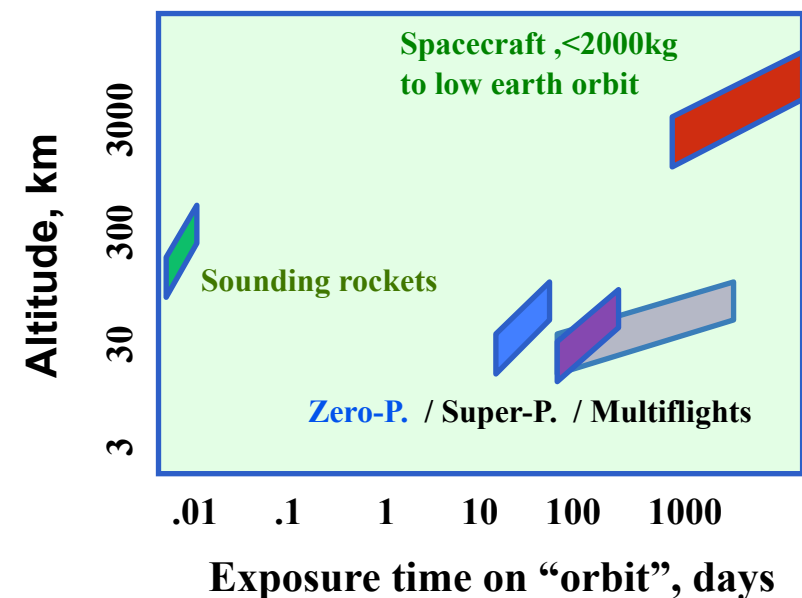
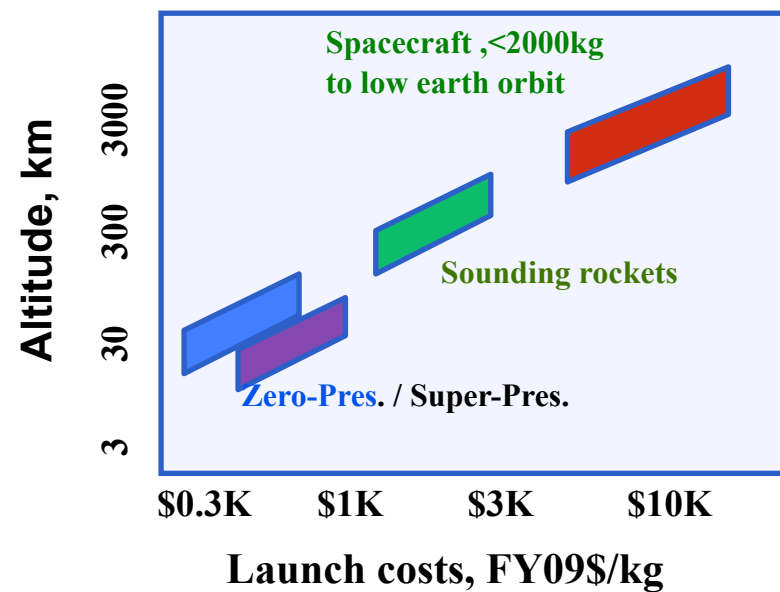


### Super Pressure Balloon Capability

Volume	2 MCF	7 MCF	14 MCF	25 MCF
Altitude	100 KFT	110 KFT	110 KFT	116 KFT
Science Payload	50 Lbs	500 Lbs	1000 Lbs	2200 Lbs*

# TALK OVERVIEWS: David Pierce (CSBF)

## ULDB Balloons: Low Cost & Short Deployment Cycle



- **LDB/ULDB: NASA's lowest cost access to space ( $\geq$  stratosphere)**
- **Super Pressure Promises an order of magnitude increase in capability**
  - spacecraft-scale payloads (1000-2000 kg)
  - exposures comparable to short-duration spacecraft
  - recoverable & re-usable payloads: increased exposure at low cost
- **Rapid response to new phenomena**



# Eliot's Comments (or why Dave's talk is important)

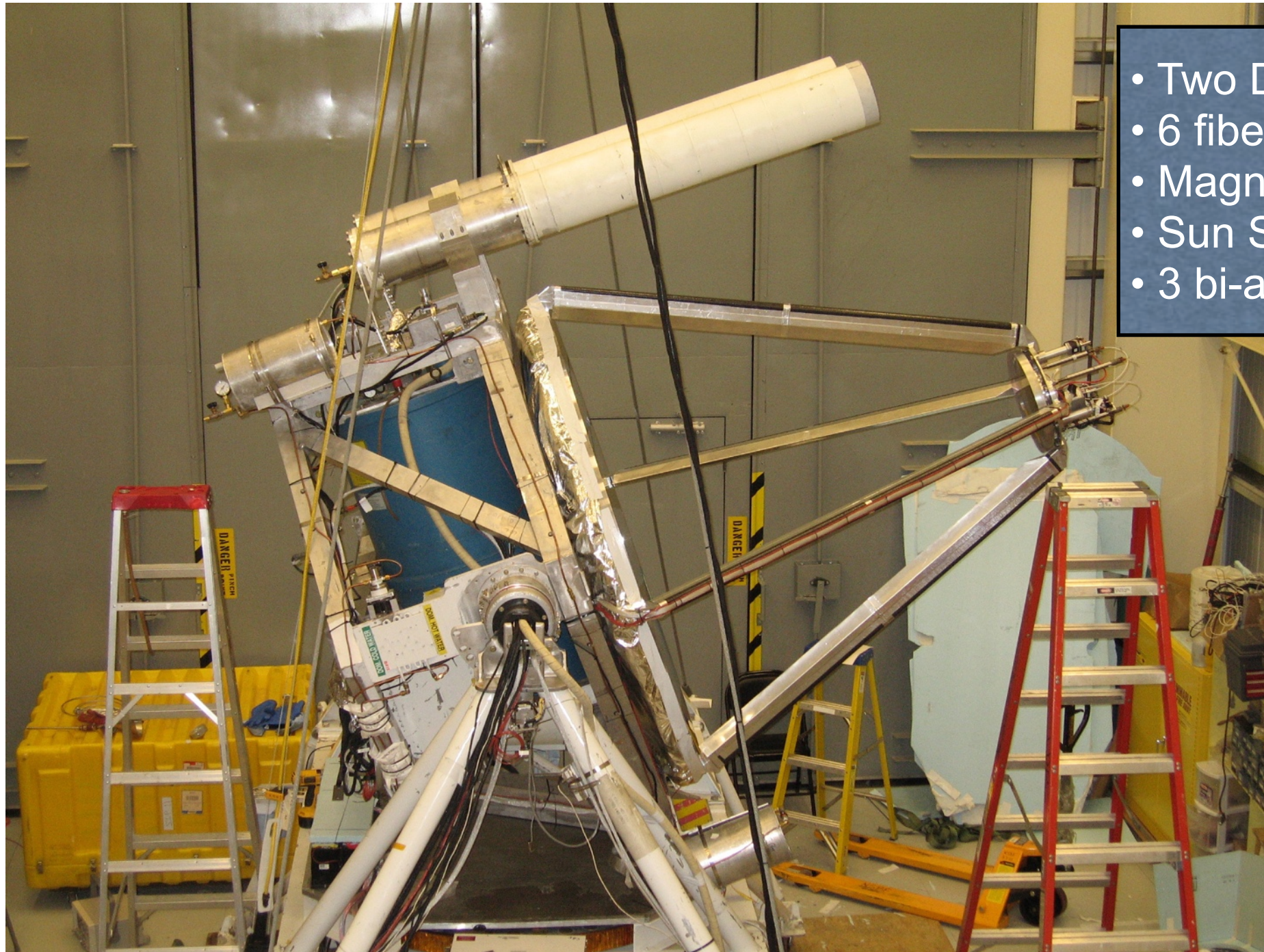
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- CSBF is *not* the bottleneck. They fly nearly every payload that NASA R&A programs recommend to them.
- Super-pressure balloons have the potential to be **RADICAL GAME-CHANGERS**. They enable (a) 100-day flights, (b) mid-latitude flights, and therefore (c) lots of **NIGHT** time at float.
- Balloon missions are cost effective even when compared to large ground-based observatories. Example: Keck time is valued \$50K per night (TSIP calculation), twice the rate of a \$5M balloon payload that flies for 100 days (day/night operation).
- Need for lighter payloads. The 25 MCF super-pressures can lift about 2200 lb, less than the 8000 lb limit raised by zero-pressure balloons. Even more critical for airships.



# **TALK OVERVIEWS: Mark Devlin (UPENN)**

## **BLAST (Balloon-borne Large Aperture Sub-mm Telescope)**



- Two DAYTIME Star trackers
- 6 fiber optic gyros
- Magnetometer
- Sun Sensor
- 3 bi-axial tilt meters



# TALK OVERVIEWS: Mark Devlin (UPENN)

BLAST: By the Numbers:



BLAST results: 16 papers and counting...



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## BLAST: By the Numbers:

Mass: 2000 kg



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Mass: 2000 kg

Mirror Diameter: 1.8 meters



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## BLAST: By the Numbers:

Mass: 2000 kg

Mirror Diameter: 1.8 meters

Motors: 3

Actuators: 4



BLAST results: 16 papers and counting...



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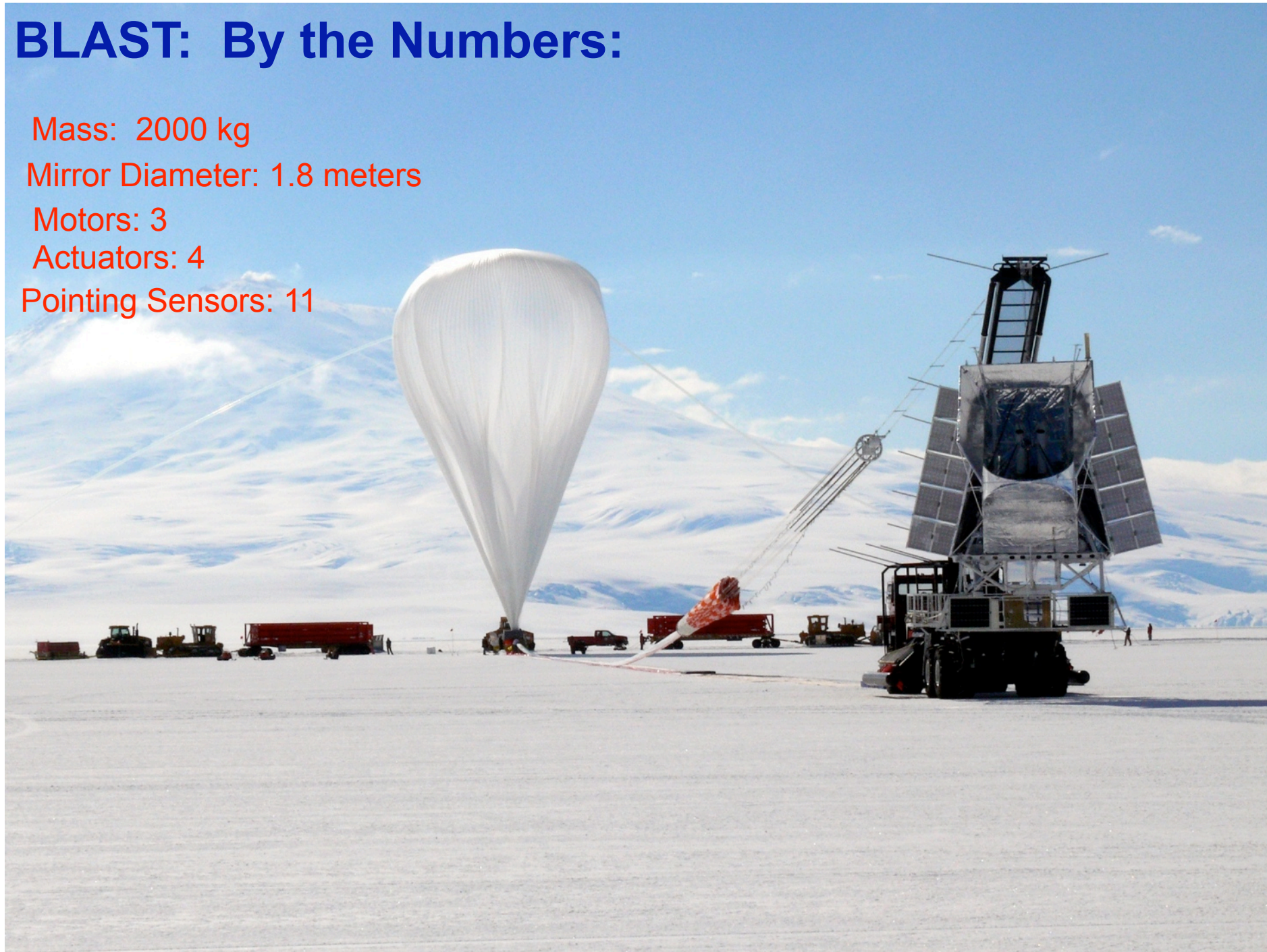
Mass: 2000 kg

Mirror Diameter: 1.8 meters

Motors: 3

Actuators: 4

Pointing Sensors: 11



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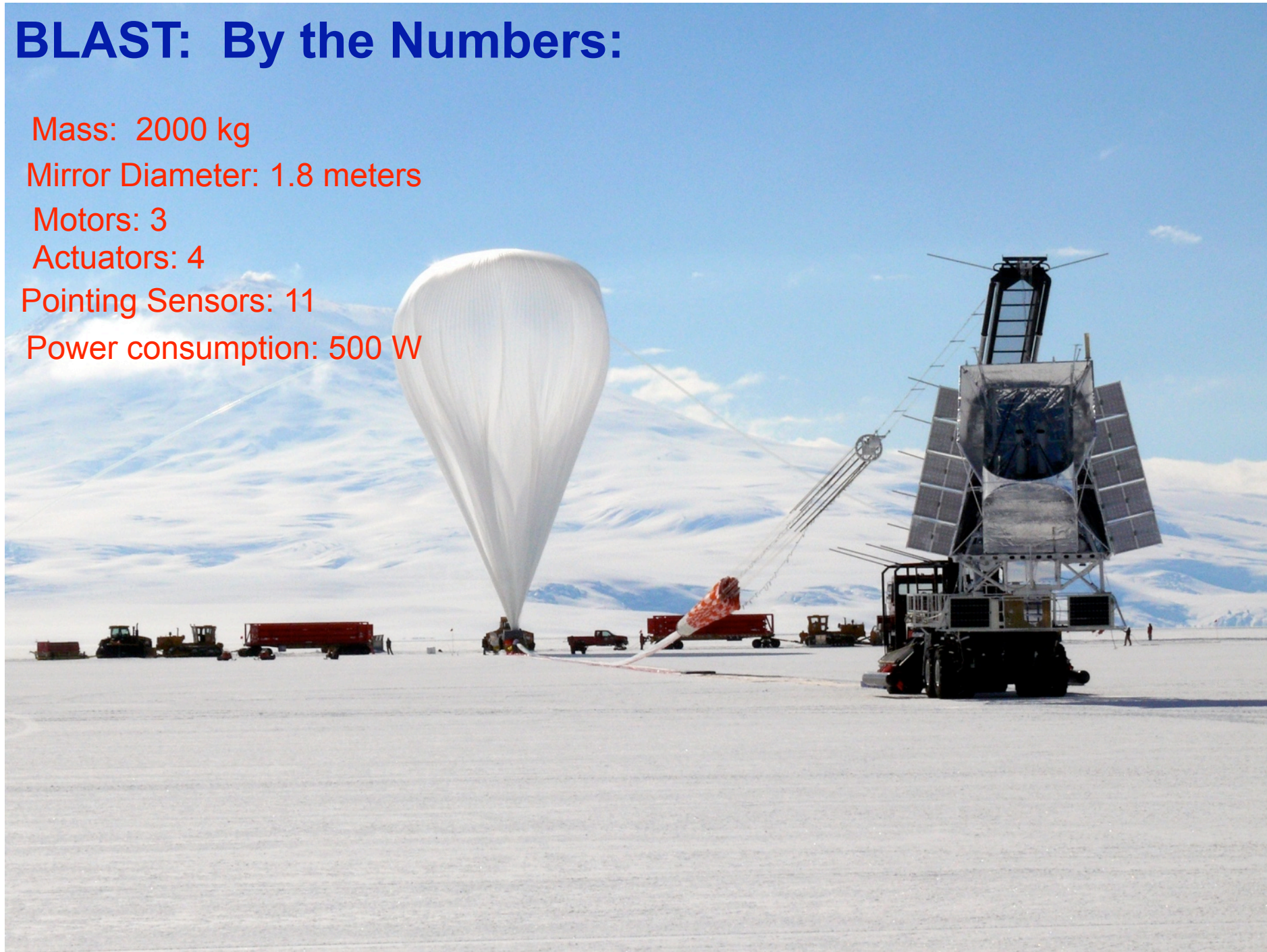
Mirror Diameter: 1.8 meters

Motors: 3

Actuators: 4

Pointing Sensors: 11

Power consumption: 500 W



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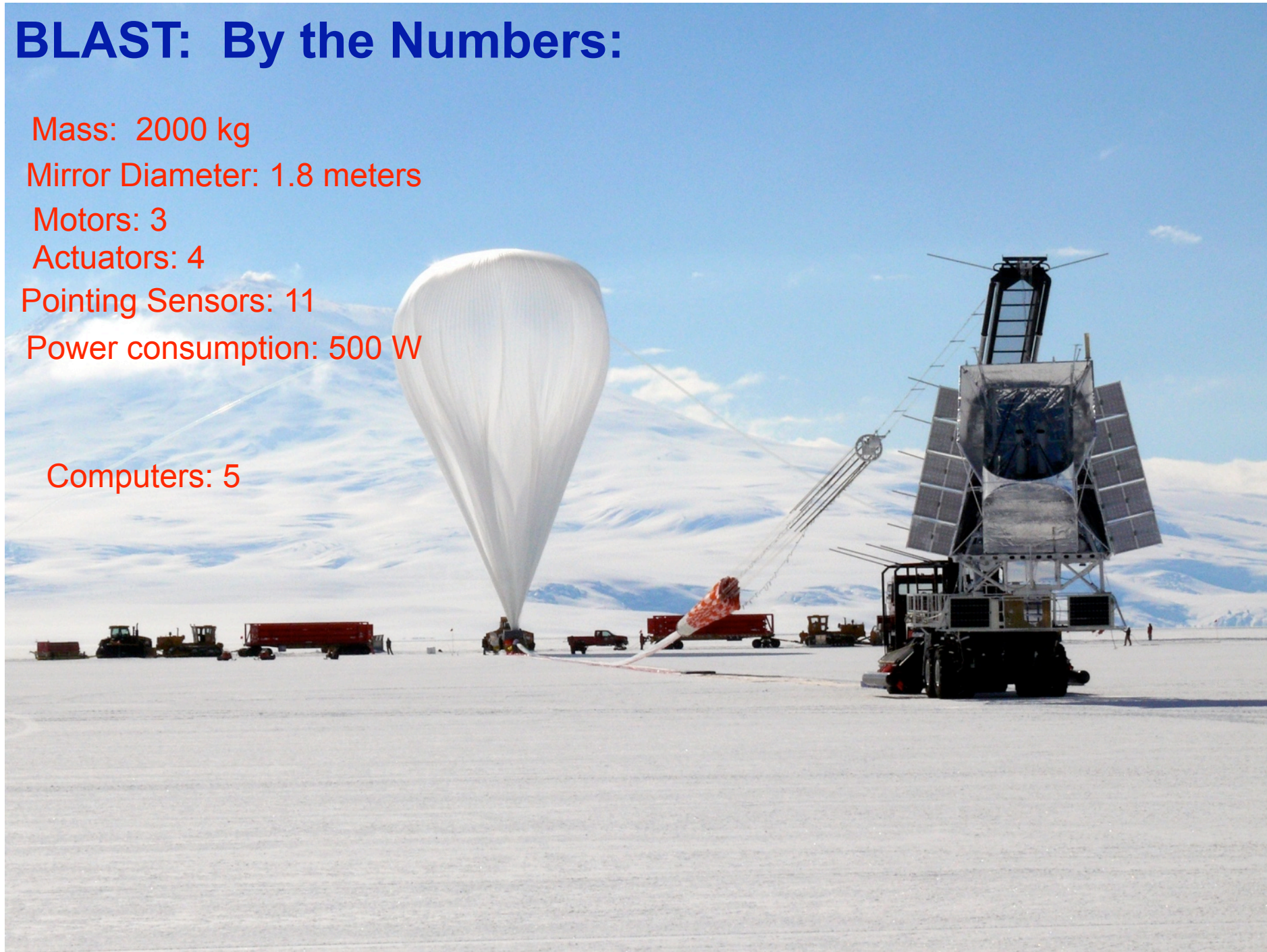
Motors: 3

Actuators: 4

Pointing Sensors: 11

Power consumption: 500 W

Computers: 5



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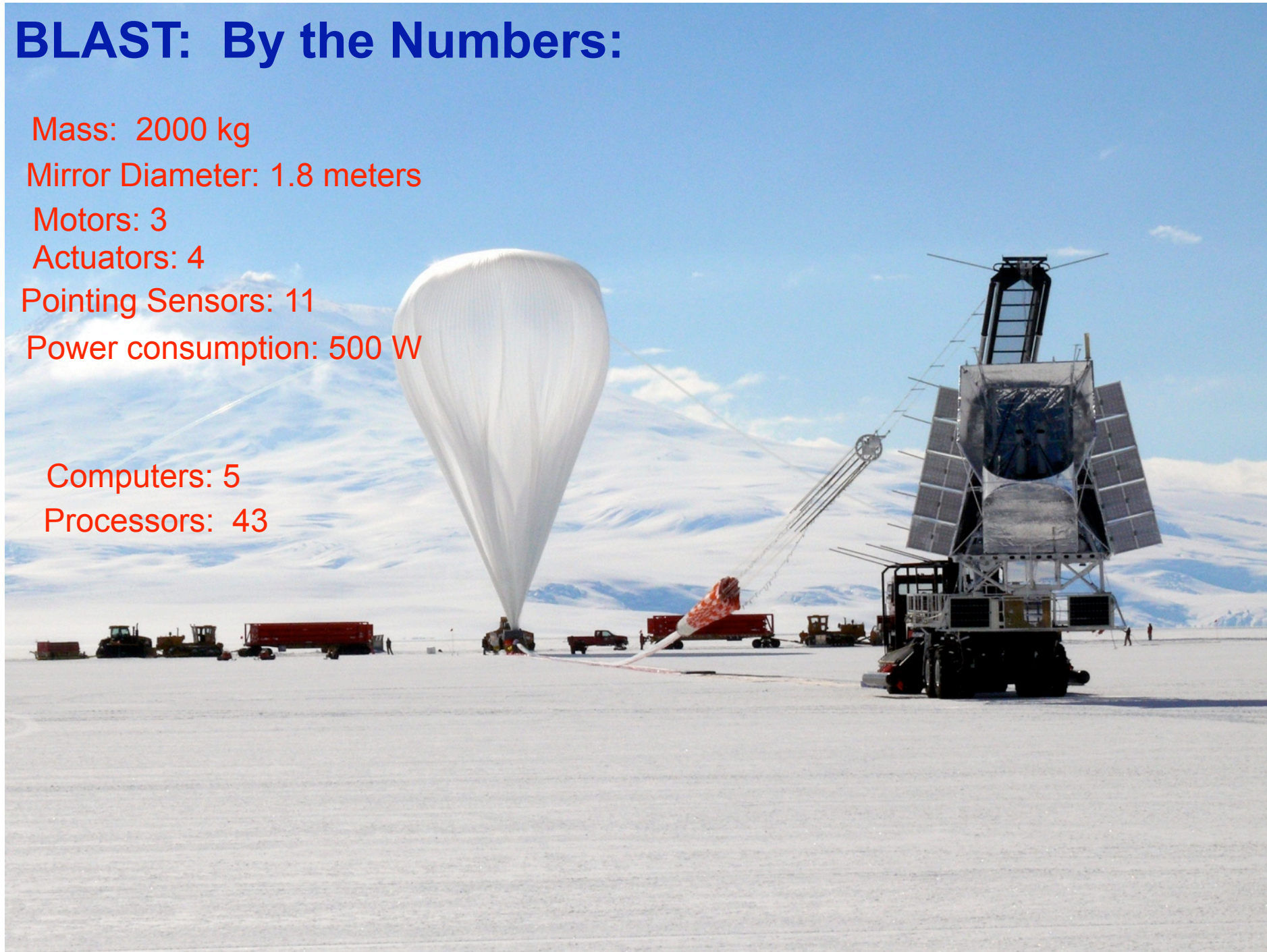
Actuators: 4

Pointing Sensors: 11

Power consumption: 500 W

Computers: 5

Processors: 43



## BLAST results: 16 papers and counting...

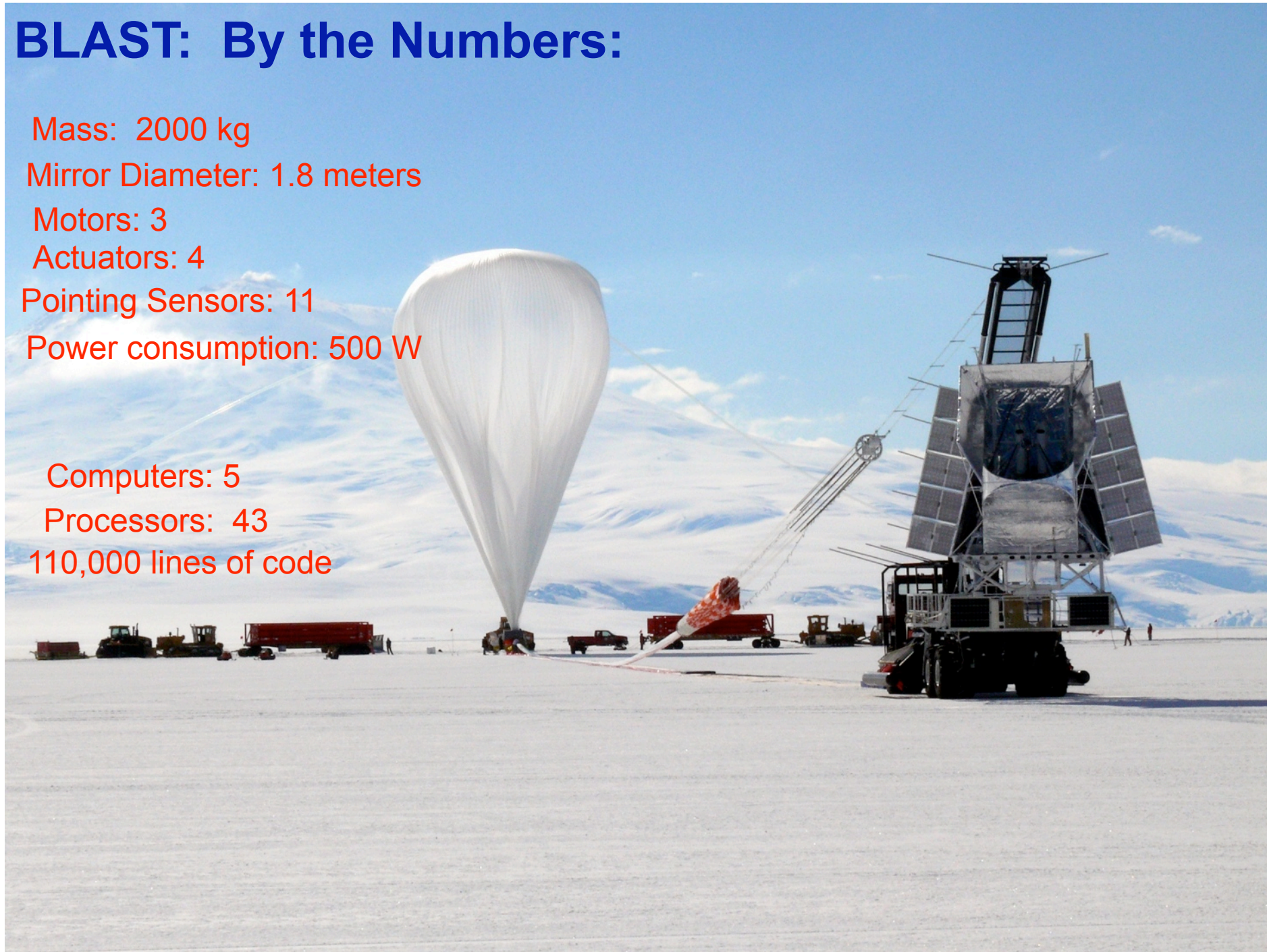


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Mass: 2000 kg  
Mirror Diameter: 1.8 meters  
Motors: 3  
Actuators: 4  
Pointing Sensors: 11  
Power consumption: 500 W

Computers: 5  
Processors: 43  
110,000 lines of code



BLAST results: 16 papers and counting...



# TALK OVERVIEWS: Mark Devlin (UPENN)

## BLAST: By the Numbers:

Altitude: 39 km

Mass: 2000 kg

Mirror Diameter: 1.8 meters

Motors: 3

Actuators: 4

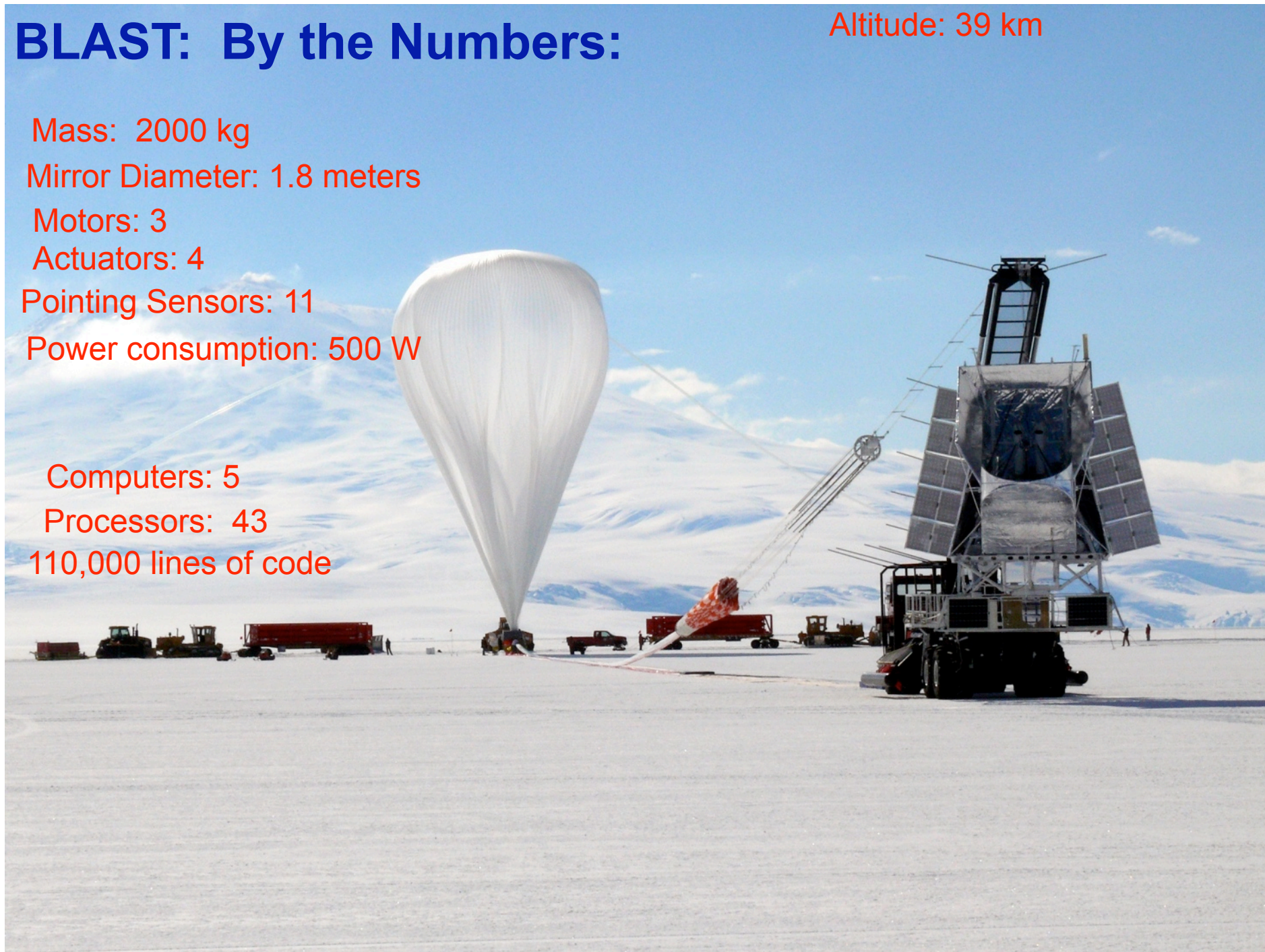
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Power consumption: 500 W

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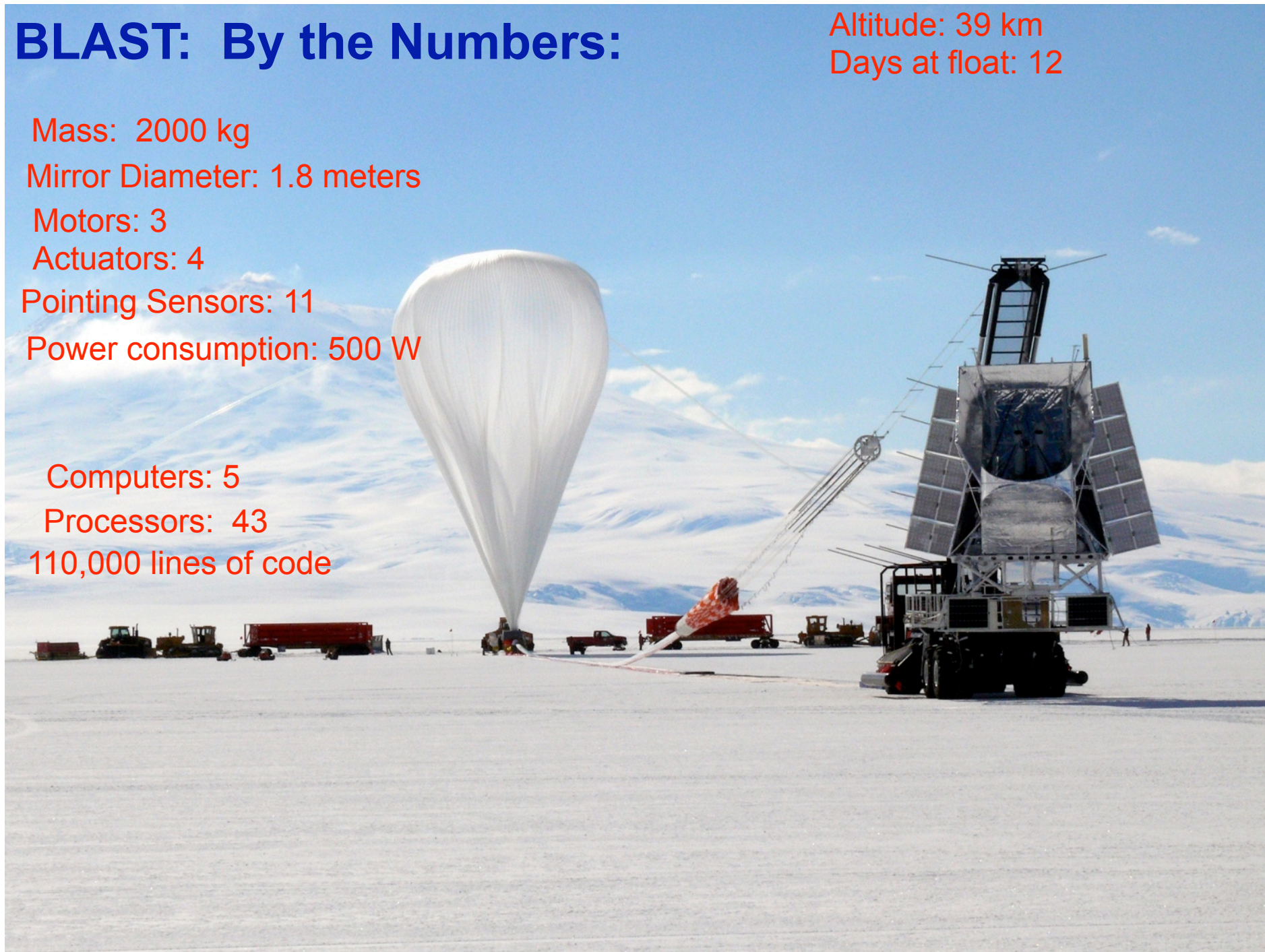
# TALK OVERVIEWS: Mark Devlin (UPENN)

## BLAST: By the Numbers:

Altitude: 39 km  
Days at float: 12

Mass: 2000 kg  
Mirror Diameter: 1.8 meters  
Motors: 3  
Actuators: 4  
Pointing Sensors: 11  
Power consumption: 500 W

Computers: 5  
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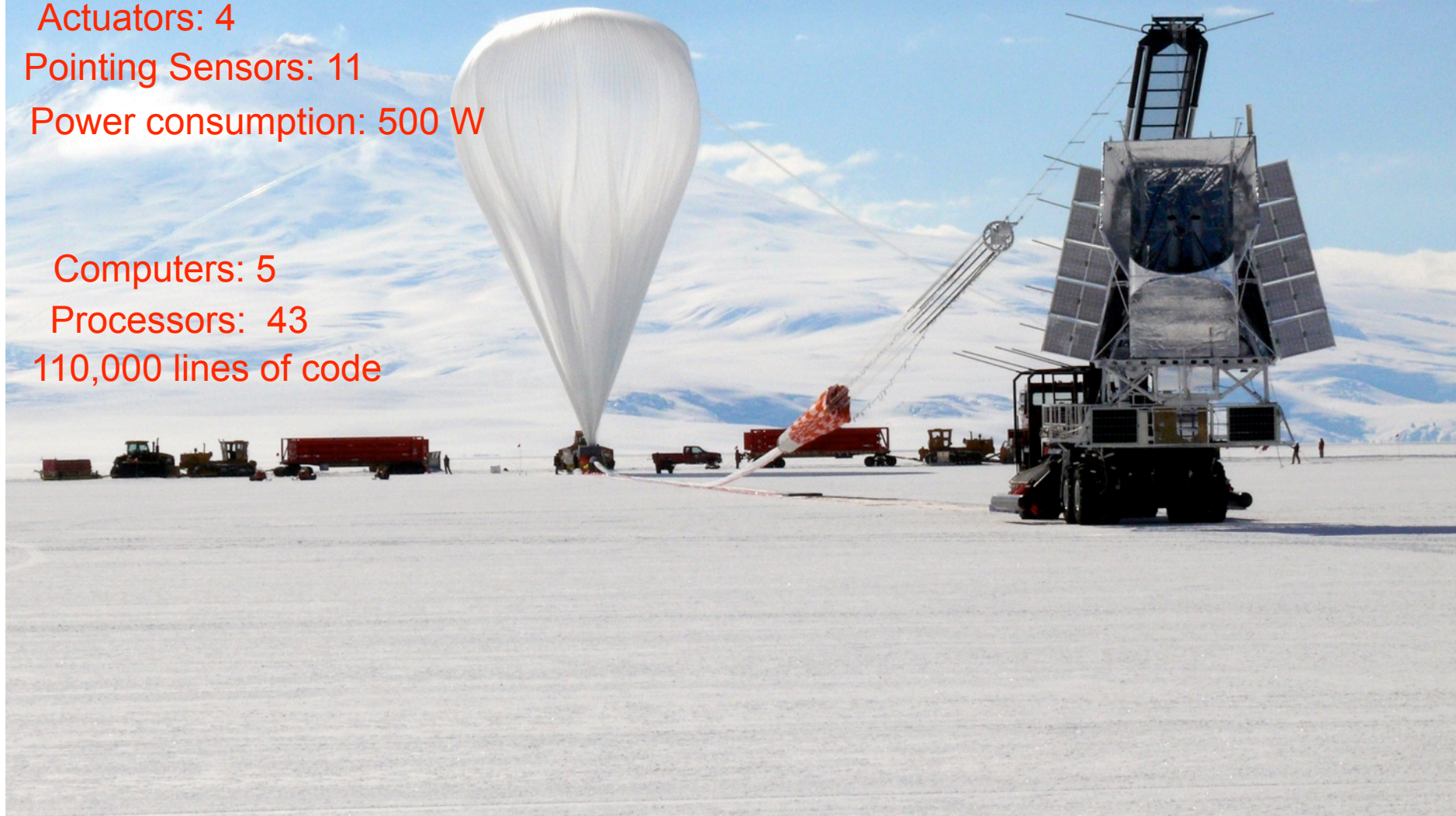
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Altitude: 39 km  
Days at float: 12

Colors: 3 (250, 350, 500 microns)  
Detectors: 260  
Beams: 32, 45, 62 arcseconds



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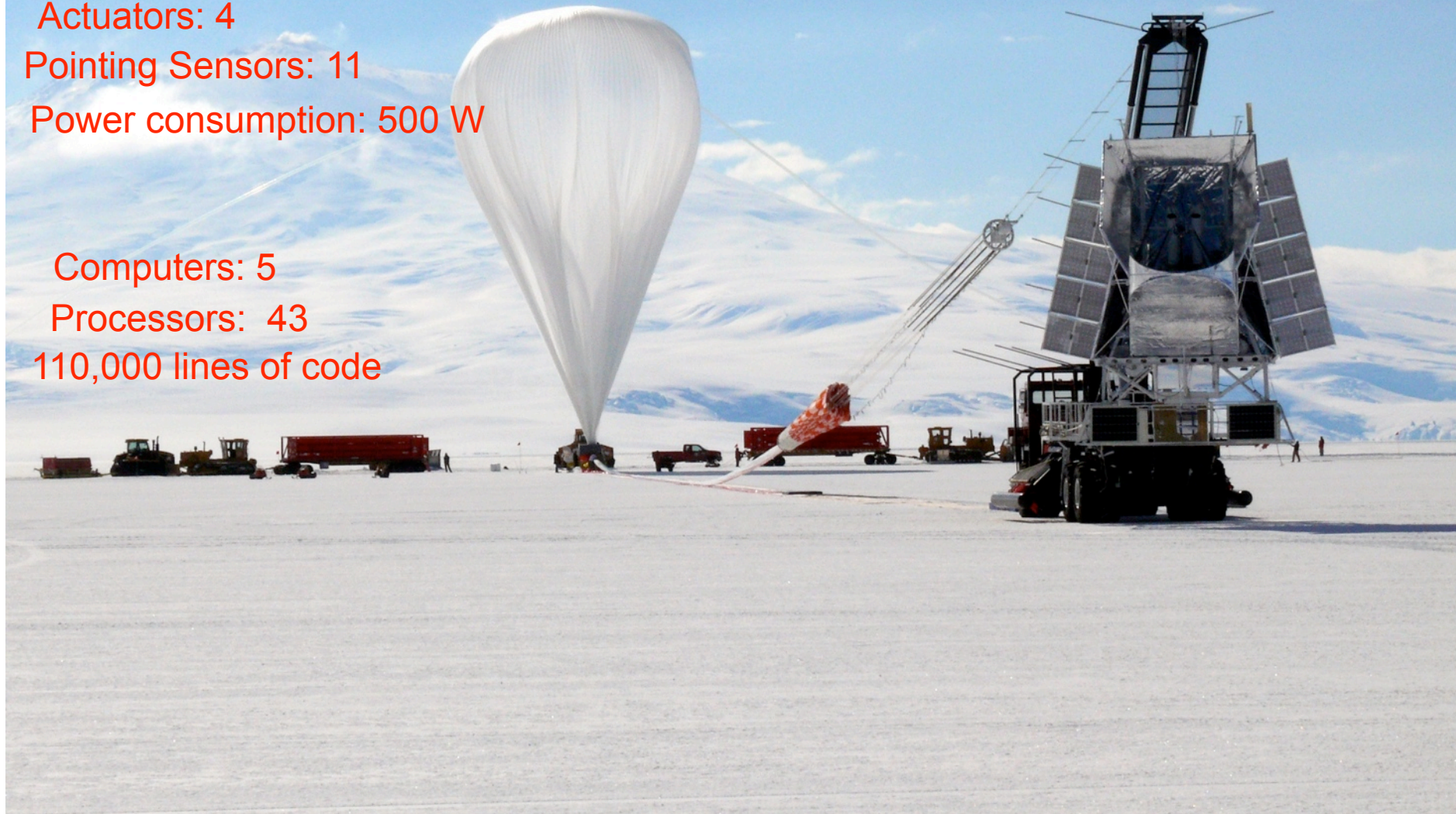
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Altitude: 39 km  
Days at float: 12

Colors: 3 (250, 350, 500 microns)  
Detectors: 260  
Beams: 32, 45, 62 arcseconds  
Amount of Data Collected: 120 GB



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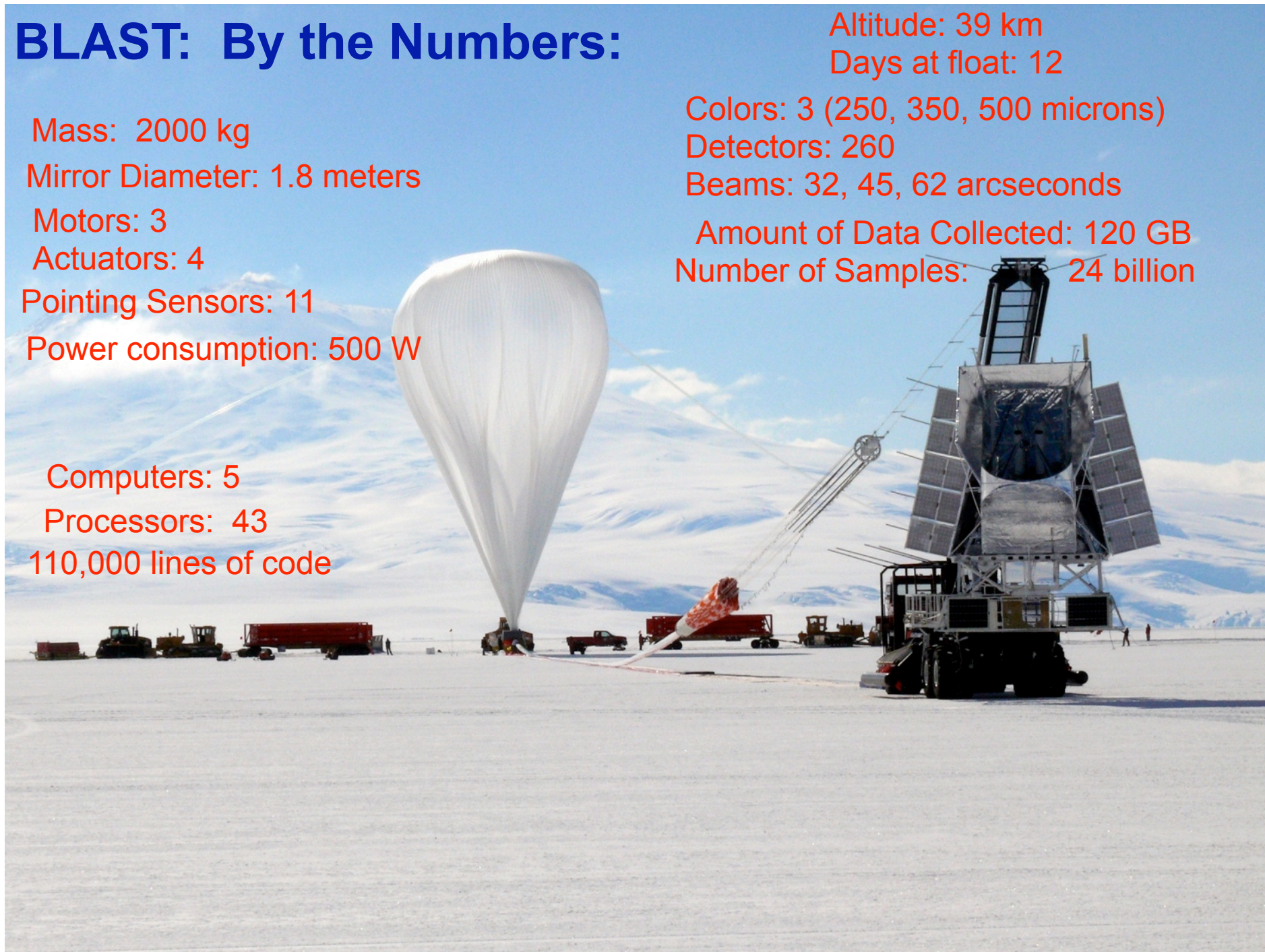
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Number of Samples: 24 billion



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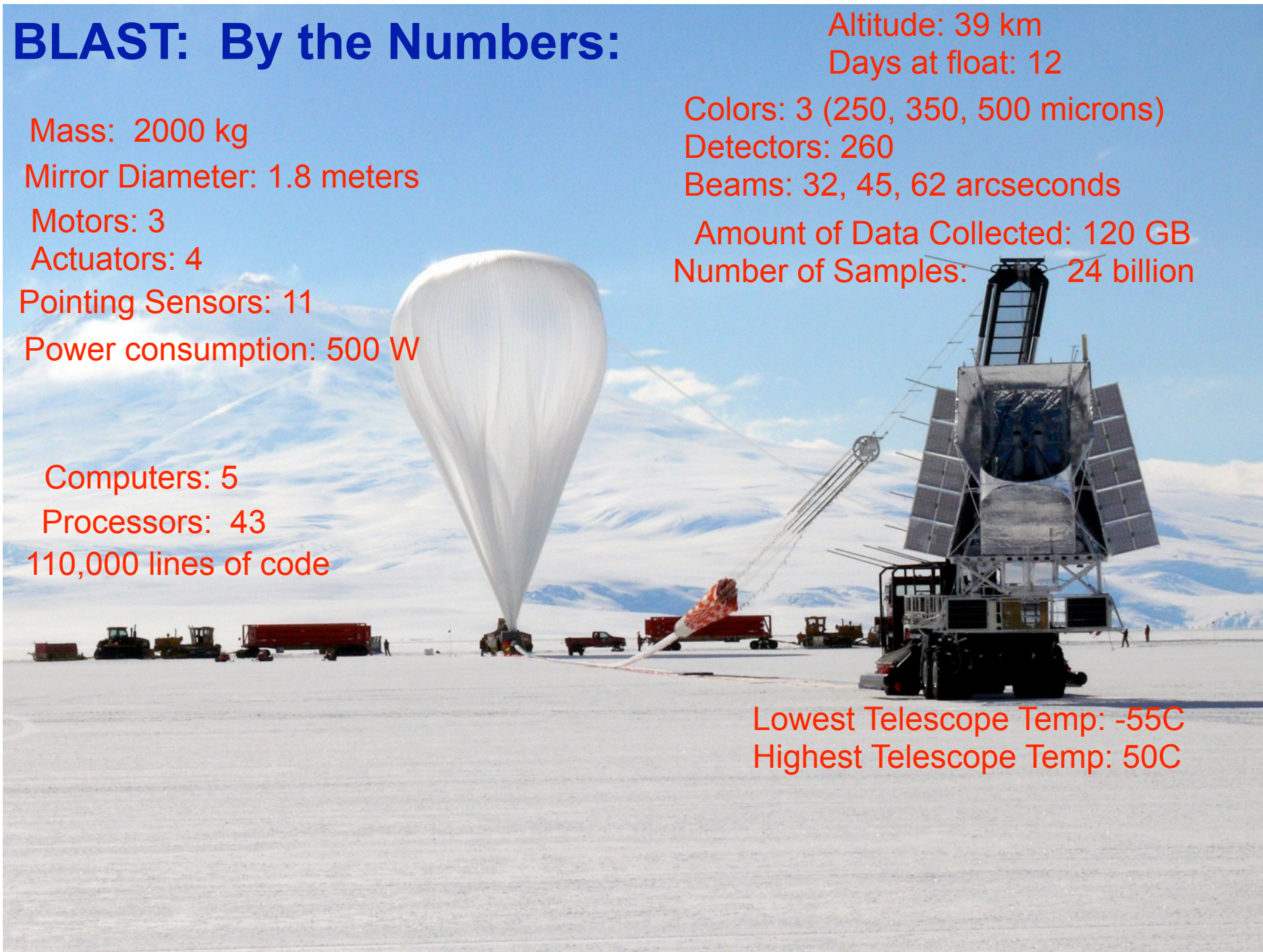
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Lowest Telescope Temp: -55C  
Highest Telescope Temp: 50C



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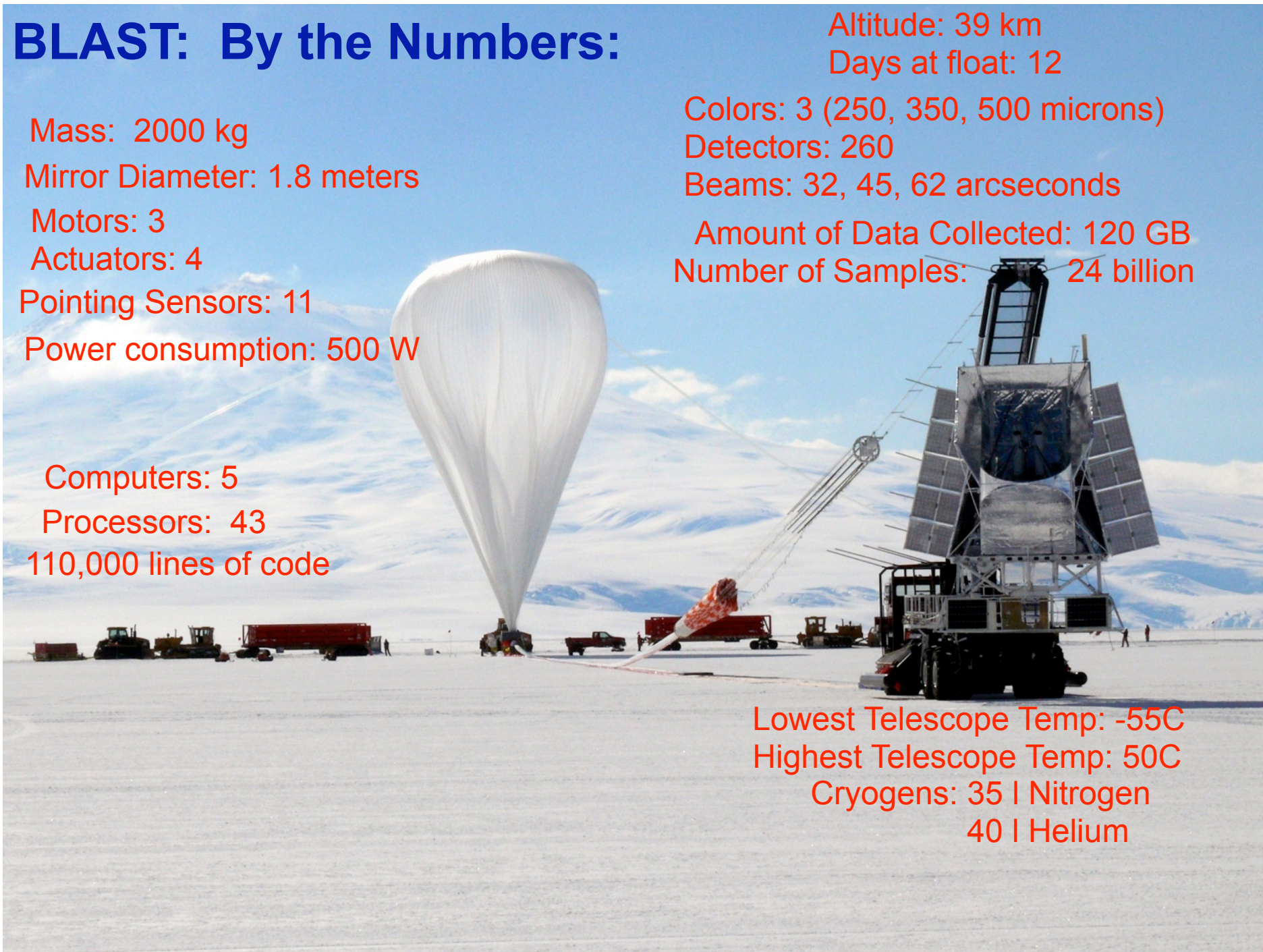
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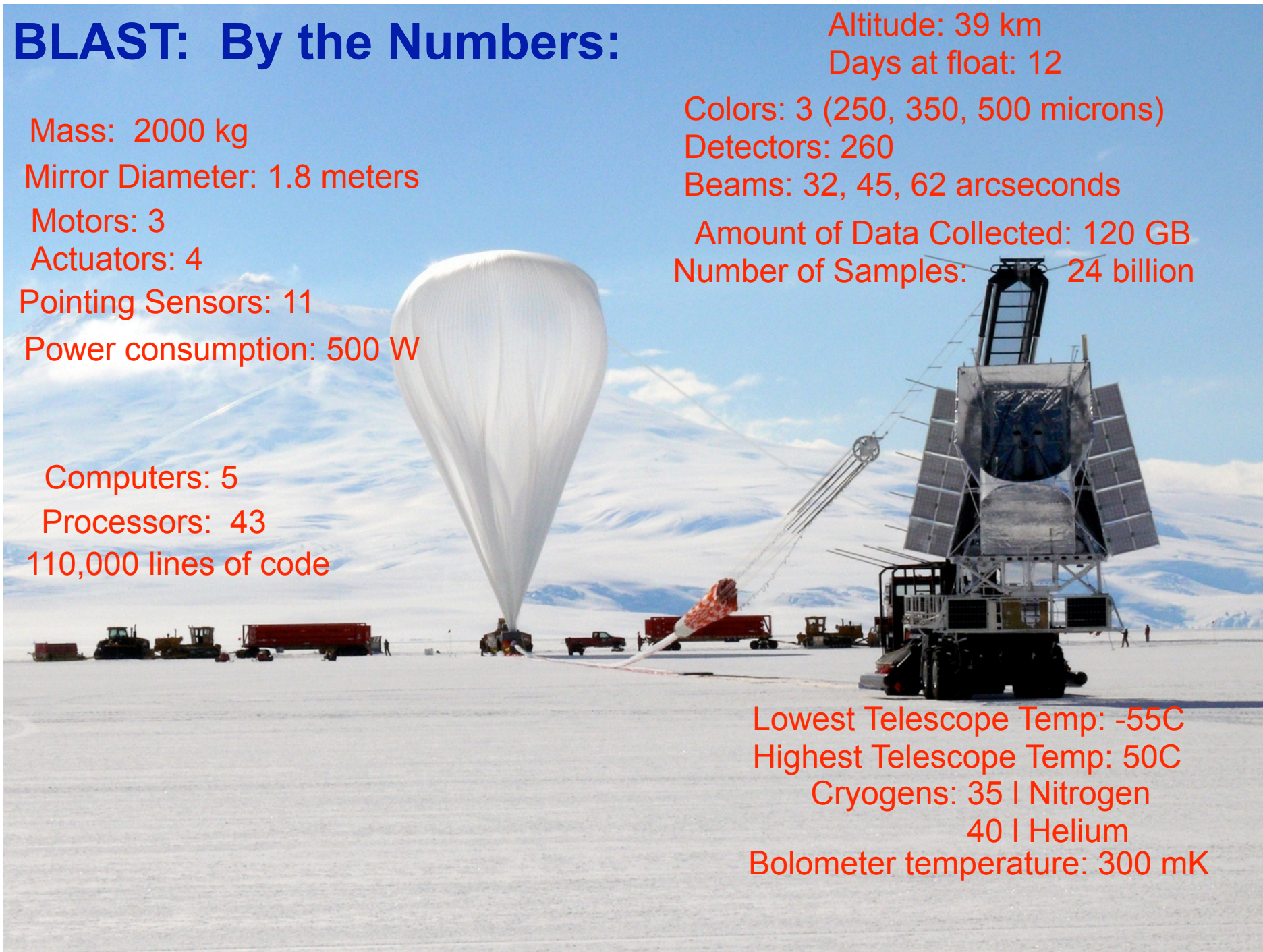
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Lowest Telescope Temp: -55C  
Highest Telescope Temp: 50C  
Cryogenics: 35 l Nitrogen  
40 l Helium  
Bolometer temperature: 300 mK



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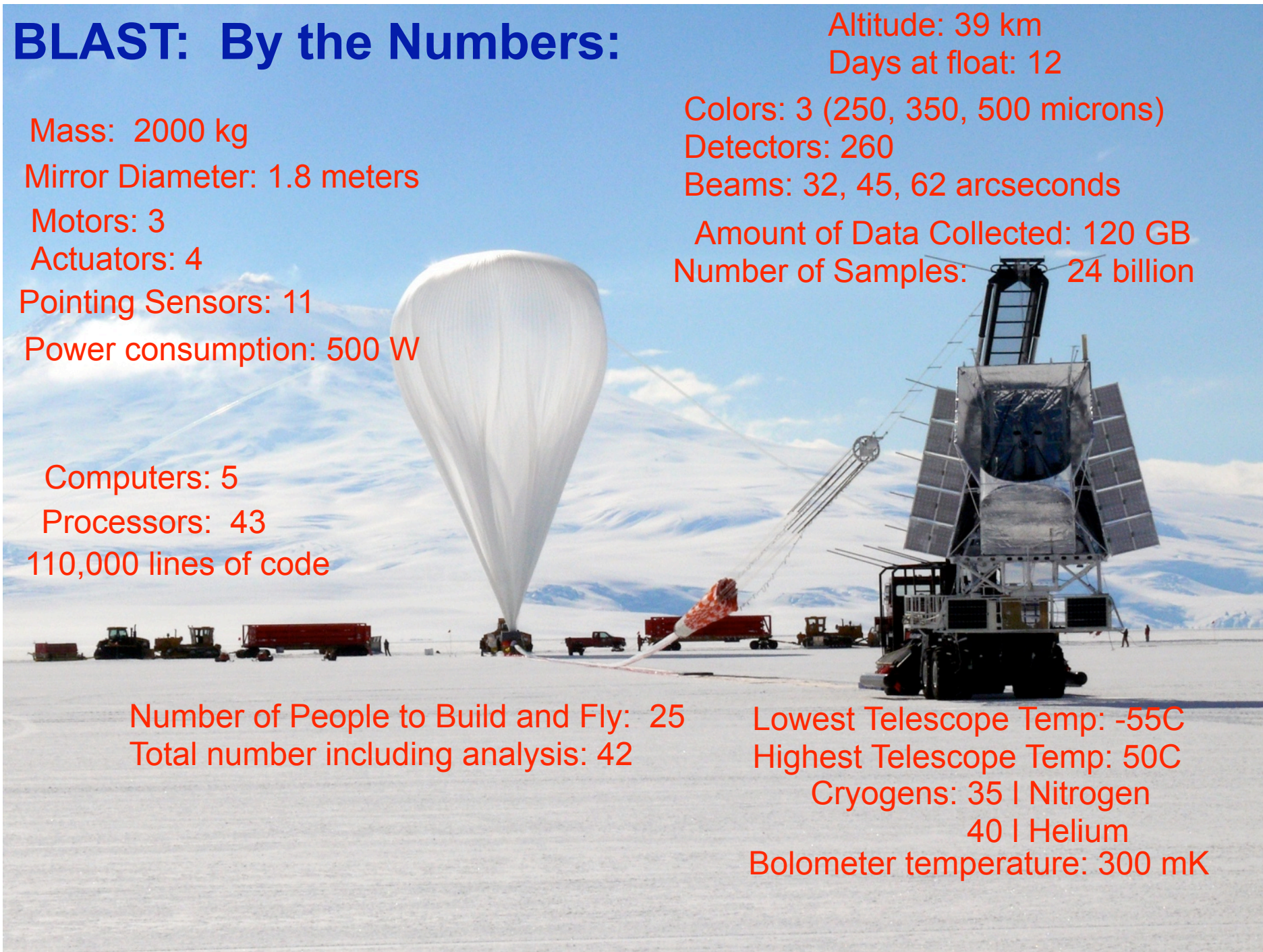
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Amount of Data Collected: 120 GB  
Number of Samples: 24 billion

Number of People to Build and Fly: 25  
Total number including analysis: 42

Lowest Telescope Temp: -55C  
Highest Telescope Temp: 50C  
Cryogenics: 35 l Nitrogen  
40 l Helium  
Bolometer temperature: 300 mK



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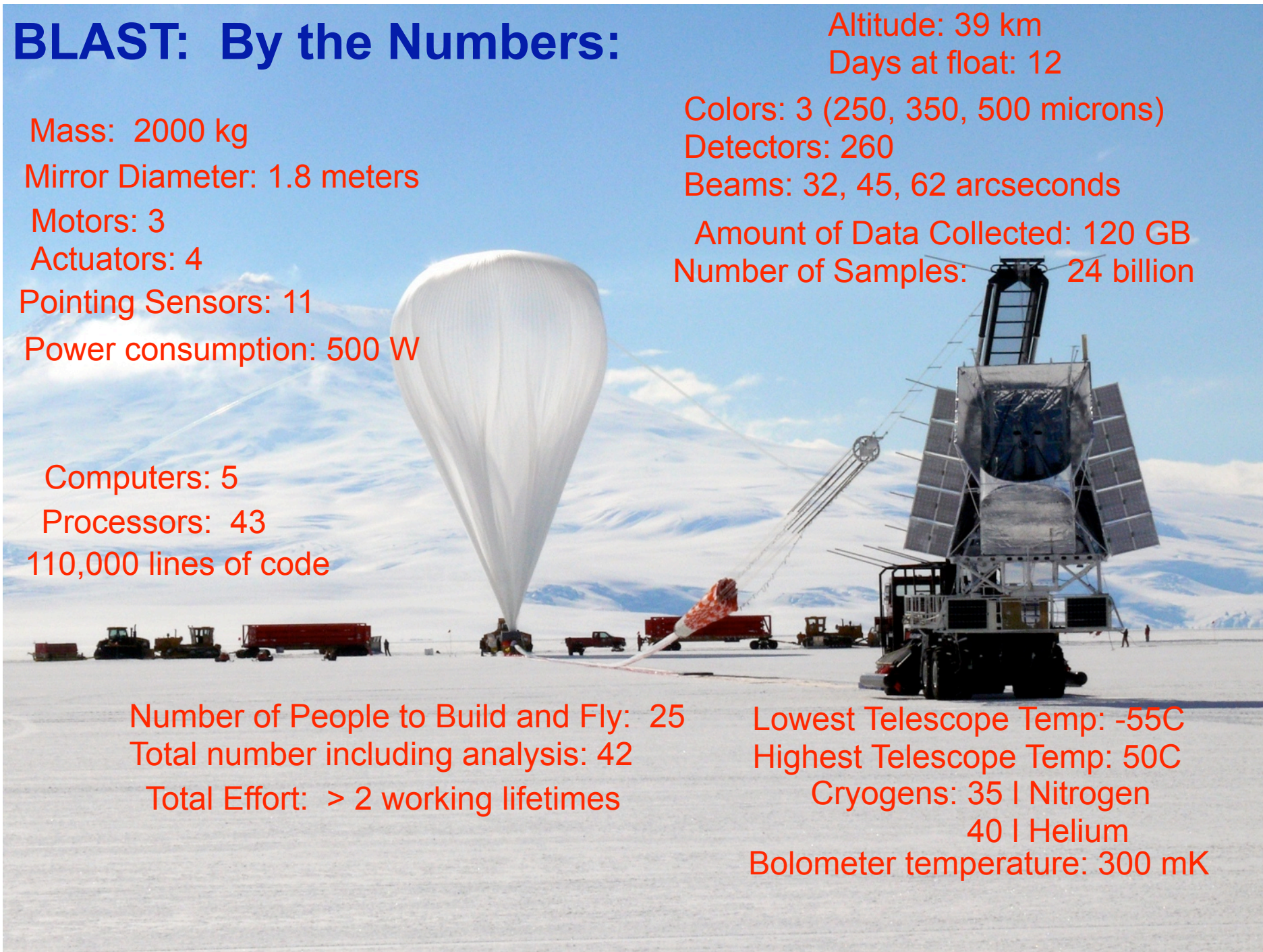
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Total Effort: > 2 working lifetimes

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SWAG orders: 5

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Mirror Diameter: 1.8 meters  
Motors: 3  
Actuators: 4  
Pointing Sensors: 11  
Power consumption: 500 W

Computers: 5  
Processors: 43  
110,000 lines of code

Number of People to Build and Fly: 25  
Total number including analysis: 42  
Total Effort: > 2 working lifetimes

SWAG orders: 5    Mugs, mouse pads, t-shirts, stickers, tattoos

Altitude: 39 km  
Days at float: 12

Colors: 3 (250, 350, 500 microns)  
Detectors: 260  
Beams: 32, 45, 62 arcseconds  
Amount of Data Collected: 120 GB  
Number of Samples: 24 billion

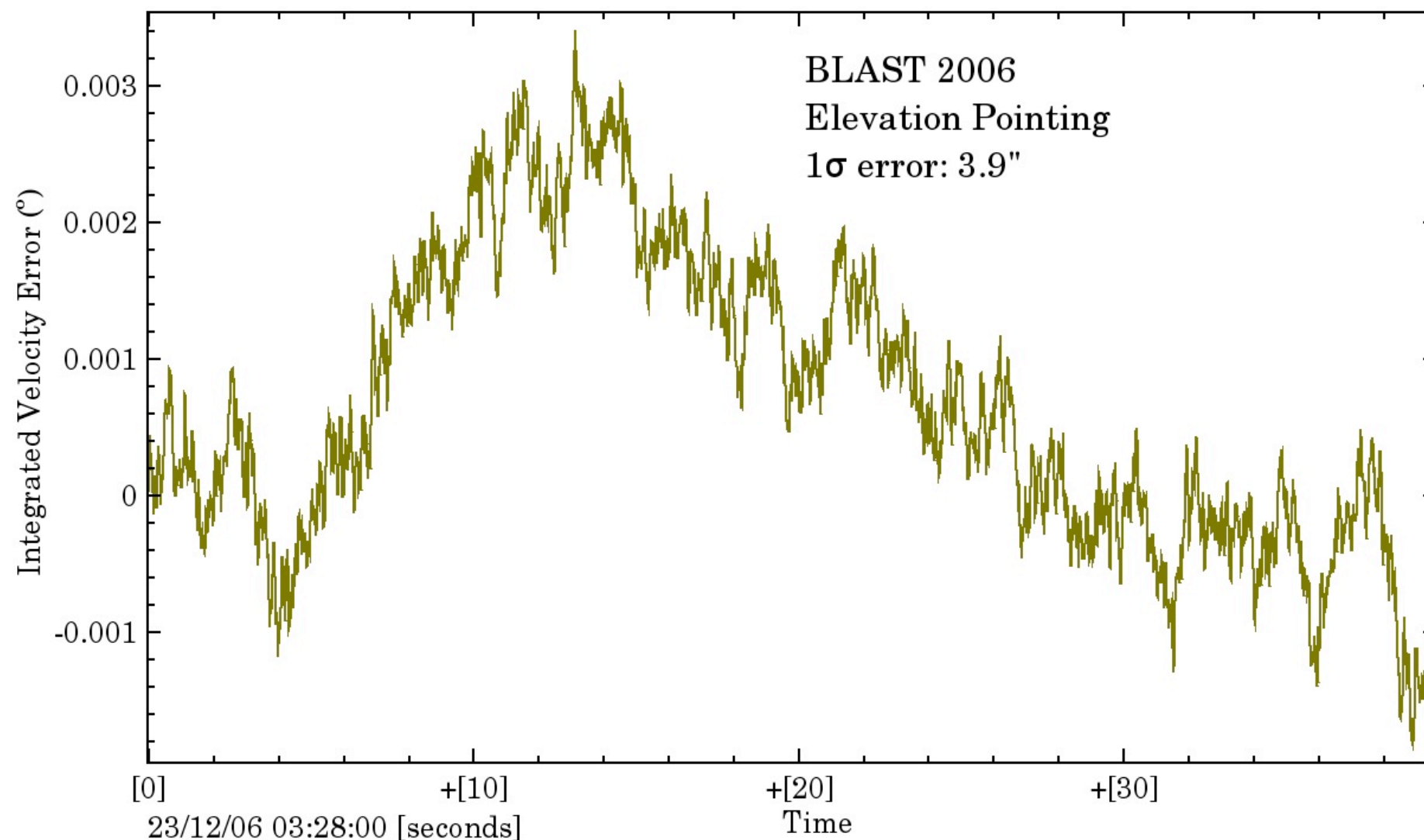
Lowest Telescope Temp: -55C  
Highest Telescope Temp: 50C  
Cryogenics: 35 l Nitrogen  
40 l Helium  
Bolometer temperature: 300 mK

## BLAST results: 16 papers and counting...



# TALK OVERVIEWS: Mark Devlin (UPENN)

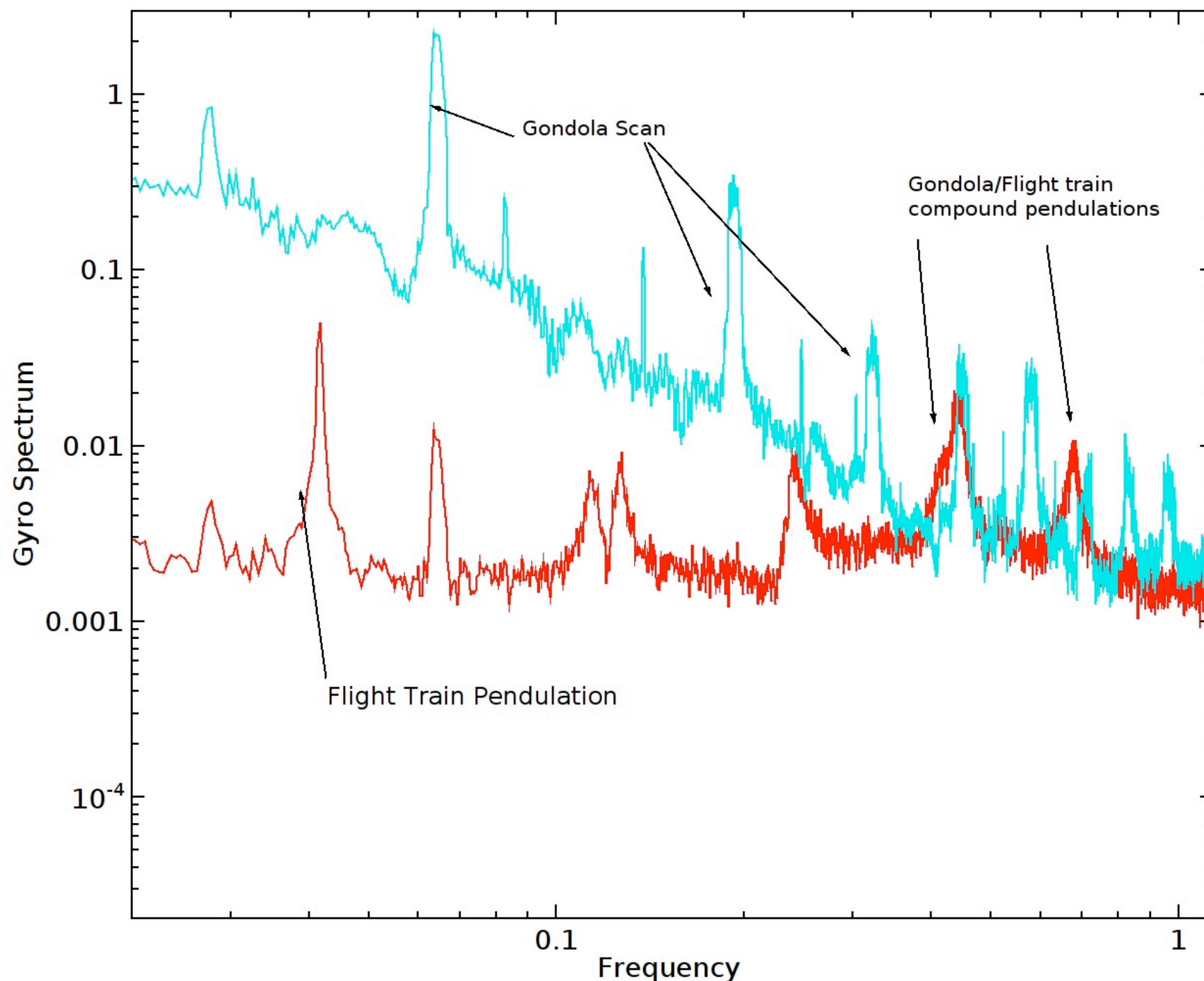
Pointing reconstruction: less than 5''





# TALK OVERVIEWS: Mark Devlin (UPENN)

## BLAST: power spectrum showing vibration modes



- For an UNPERTURBED payload, most of the power is in the pendulum fundamental (about a 20-sec period, about 14 Joules).
- The BLAST gondola scanned a patch of sky. You can see the modes driven by the scan motion.



## **ASIDE: The Environment at Float (CosmoCam)**

CosmoCam (Scott Murphy, GSFC) is a small, pointed video camera that has taken in-flight video on recent HASP payloads. HASP = High Altitude Student Payload.





# Eliot's Comments (what we should learn from BLAST)

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- BLAST is a good example of a well-designed, cost-effective payload. Many redundant systems. Recommended by Danny Ball (CSBF) as a gondola to study if you're building your own.
- BLAST shows that you can get a pointing solution to a few arcseconds with roll-your-own star trackers (\$25K?).
- BLAST carried cryogenics, detectors at 300 mK.
- Temperature control (workshop comments made by Mark): the temperature environment is the most challenging aspect of a stratospheric payload. With many layers of MLI and other solutions (like heat pipes), it should be possible to reduce temperature gradients across your OTA to  $\sim 1$  degree (?).
- Consider designs for torque-less telescopes (e.g., SUNRISE).



# TALK OVERVIEWS: Alice Lecinski (NCAR)

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# TALK OVERVIEWS: Alice Lecinski (NCAR)

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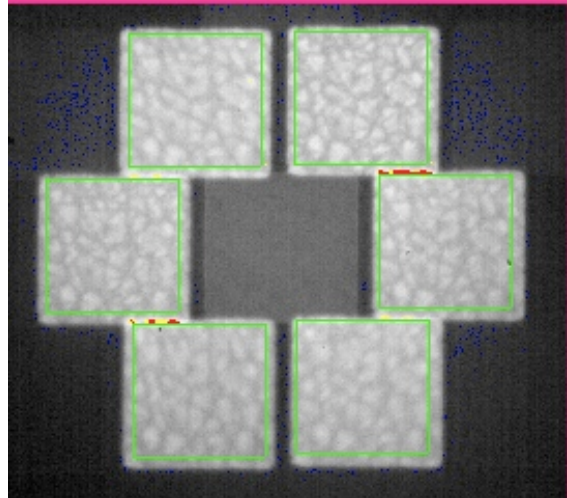
## The instruments

- 1m UV/VIS Telescope
- Filtergraph (SUFI)
  - Phase-Diversity Imager
  - 5 wavelength band between 214 and 397 nm (width 1 nm)
- Magnetograph (IMAX)
  - Tunable Fabry-Perot Etalon (LiNb), used in double path
  - LCD-Modulators
  - Phase-Diversity channel
- Wavefront correction (CWS)
  - 6-element Wave-front sensor, Tip-tilt-mirror
  - Closed-loop bandwidth (0dB) 90 Hz

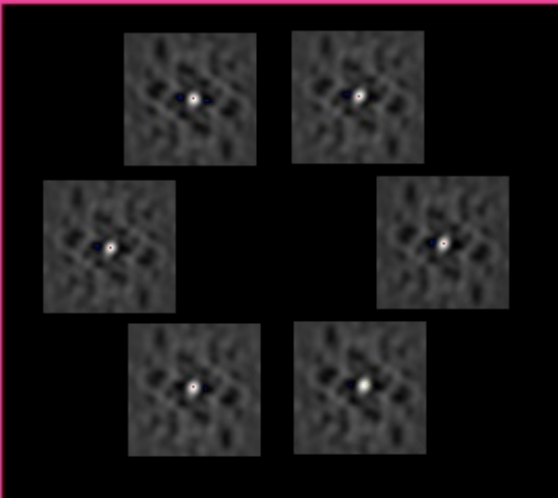


# TALK OVERVIEWS: Alice Lecinski (NCAR)

get raw camera image



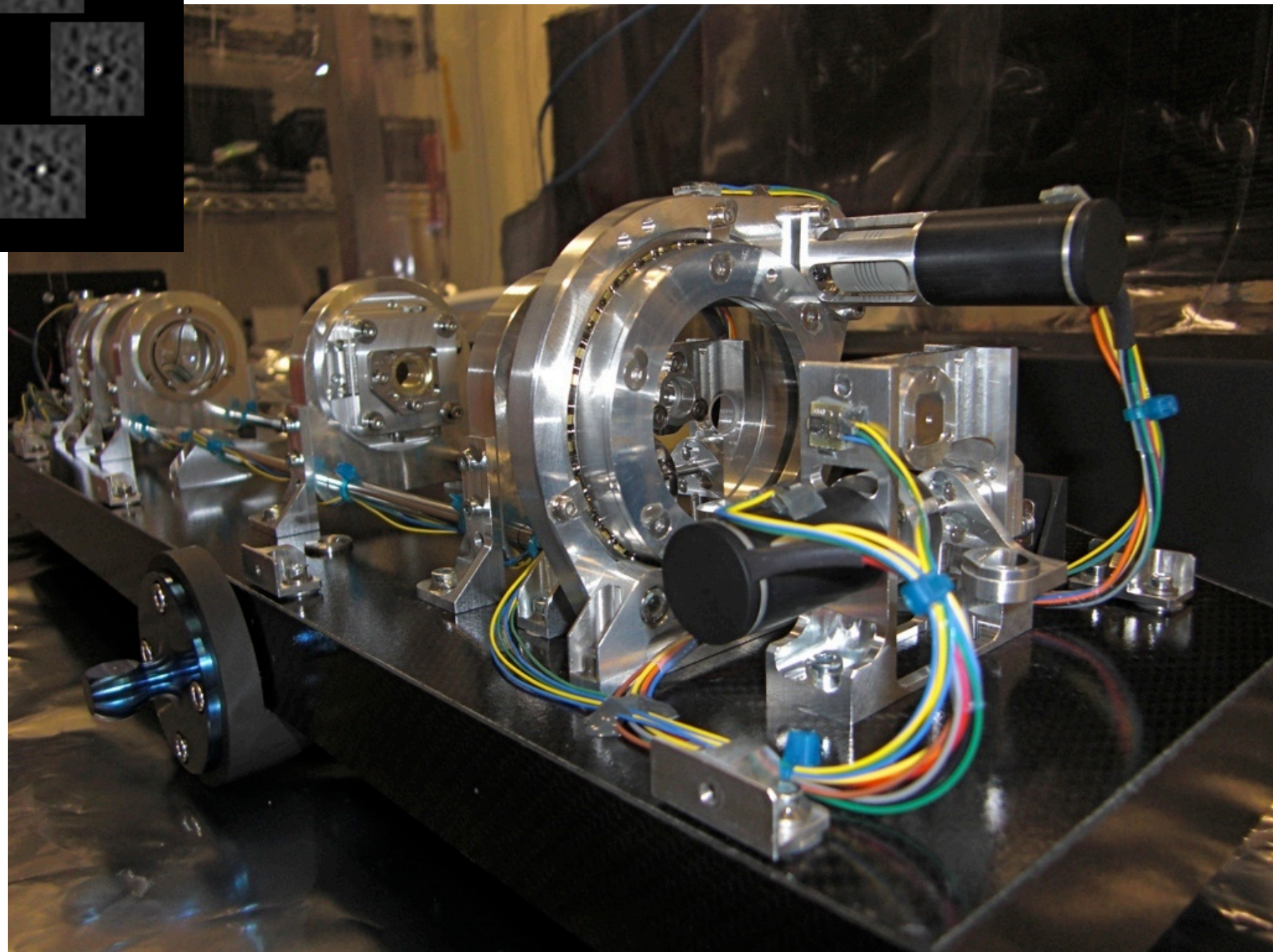
get correlation functions



- 0.002 arcsec RMS measurement accuracy
- 90 Hz bandwidth (0 dB)

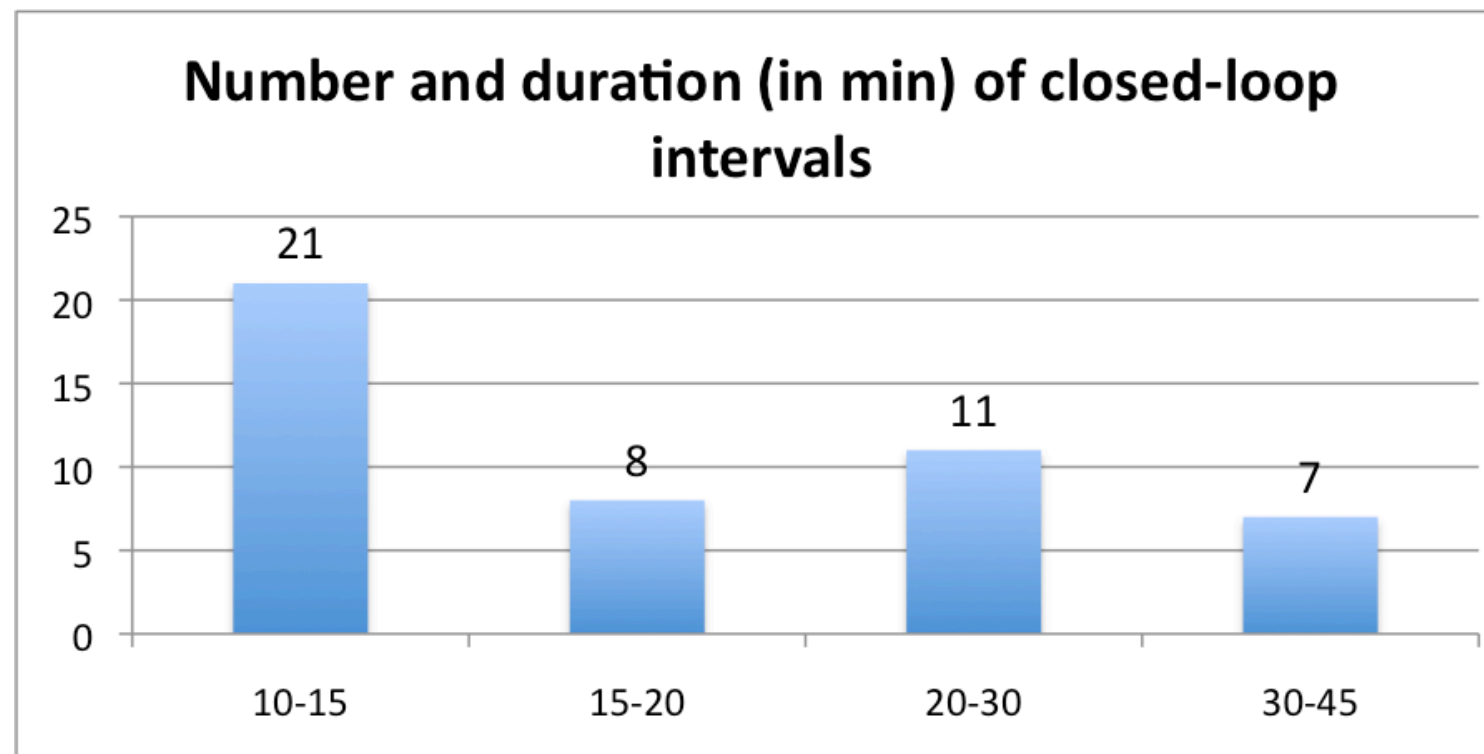
Slide courtesy W. Schmidt, KIS

## CWS: The Correlated Wavefront Sensor





# TALK OVERVIEWS: Alice Lecinski (NCAR)



- Not continuous performance through the entire flight, but sequences with extraordinarily good pointing performance for 10 - 45 minutes at a stretch.
- Thirty-three hours of excellent pointing in total, producing the sharpest images of the Sun ever obtained.
- Reasons for loss of feedback loop may include vibration from the flywheel.



# TALK OVERVIEWS: Alice Lecinski (NCAR)

**HAO's job: provide 'crude' 50 arcsec pointing**

Elevation control - straightforward

Azimuth control – tricky, nothing external to push against

Coarse Az motor

Flywheel

Essentially a torque-less telescope in azimuth.



# **Eliot's Comments (or why Alice's talk on SUNRISE is important)**

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- SUNRISE is the best demonstration to date of a pointed, stabilized balloon-borne telescope.
- The SUNRISE azimuthal flywheel/coarse pointing system should serve as (a) an example of a torque-less system and (b) a starting point. Can it be modified to make it even quieter?
- Correlated wavefront system: need to find out more. Did it only provide tip-tilt correction? Is that sufficient in the stratosphere?
- Questions that this group needs to investigate: “What is the atmospheric degradation that remains after tip-tilt correction?” and “Is a full-up AO system needed to correct for mirror distortions due to, say, transient thermal gradients?”



# **TALK OVERVIEWS: Steve Kendrick (Ball) and Charles Kirk (ITT) on Lightweight Mirrors**

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Note: we cannot archive or show slides from Charles Kirk's talk, but here are some points that he discussed.

- HST mirror: about 150 kg/m<sup>2</sup>. ITT's lightest technology: about 10 kg/m<sup>2</sup>.
- SiO<sub>2</sub> doped with TiO<sub>2</sub>: near zero CTE near room temperature. You can adjust the CTE point by -5/+15 K.
- Borosilicate: relatively high CTE, but the CTE is near zero around -40 K. Borosilicate takes advantage of flat screen TV technology. ITT has the first ion-figured test bed (check to see if that refers to borosilicate mirrors).
- FRIT process: a toothpaste-like substance that joins faceplates to cores with well-matched CTEs.
- AMSD technology: core of segmented hex segments, pretty cheap. 18 nm (rms) segmented surface.



# **TALK OVERVIEWS: Steve Kendrick (Ball) and Charles Kirk (ITT) on Lightweight Mirrors**

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## **Stephen Kendrick on Mirrors**

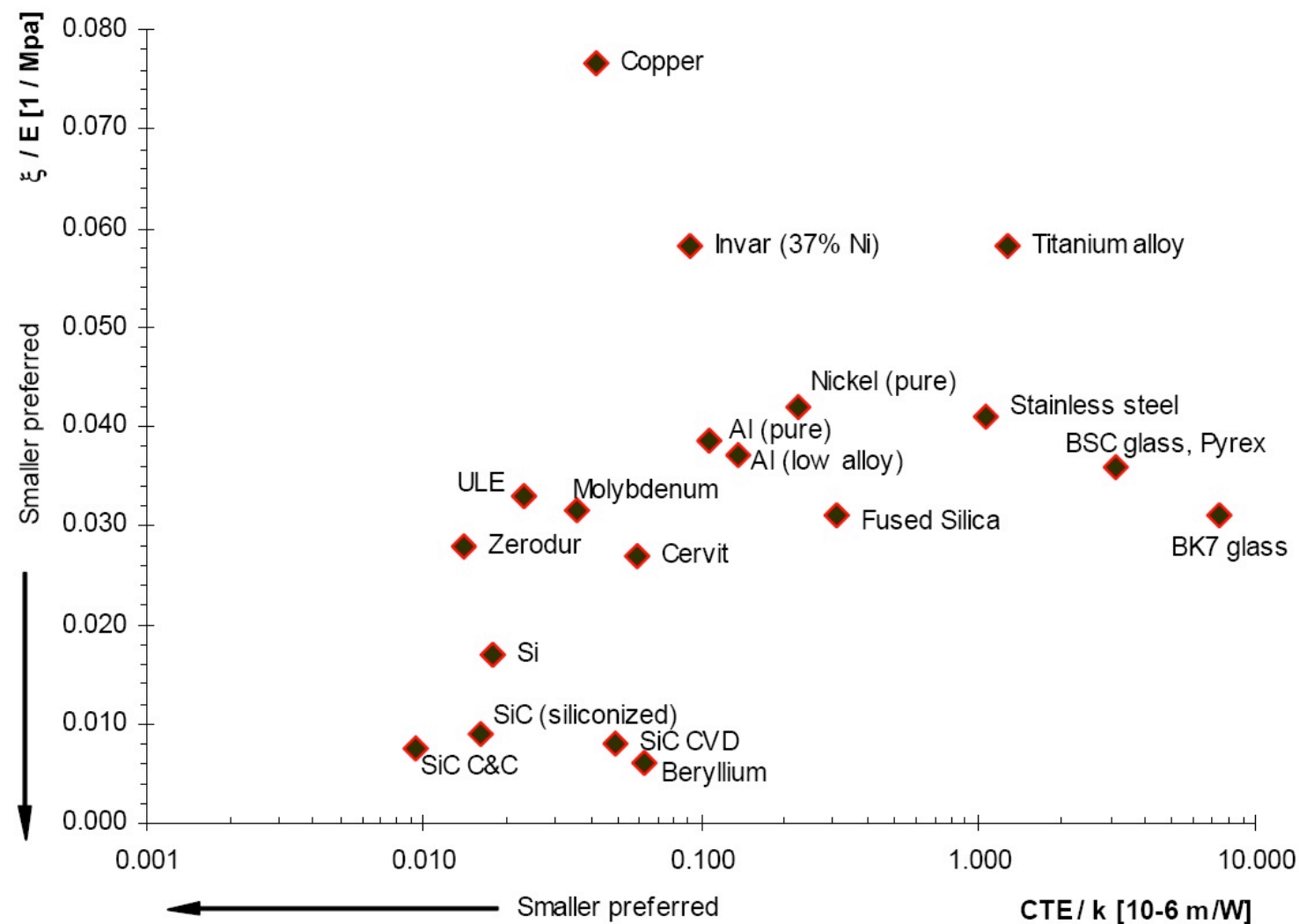
- **Material properties – merit factors (density/stiffness, CTE/thermal conductivity, polishability, manufacturing and shaping processes, ability to impose integral mounting features, scatter, etc.)**
- **Mirror material candidates**
  - **Mature with high TRL**
    - ❖ **“Glass” (borosilicate, fused silica, Zerodur<sup>®</sup>, CLEARCERAM<sup>®</sup>-Z, ULE<sup>®</sup>)**
    - ❖ **SiC**
    - ❖ **Aluminum**
  - **Emerging technologies**
    - ❖ **Membrane**
    - ❖ **Composite**
    - ❖ **Foam (various materials)**
    - ❖ **Glass corrugated mirrors**



# TALK OVERVIEWS: Steve Kendrick (Ball) and Charles Kirk (ITT) on Lightweight Mirrors

Material selection for the mirror mounts and metering structure is critical to provide mechanical and thermal stability

- Prefer materials or constructions that offer:
  - Low mass
  - Thermal stability
  - Alignment and pointing stability
- Athermalized designs possible when structural and optical materials match:
  - Silicon Carbide with Si or SiC mirrors
  - Aluminum
  - Composites
  - Beryllium



[www.eso.org/projects/owl/Blue\\_Book/6\\_Telescope\\_optics.pdf](http://www.eso.org/projects/owl/Blue_Book/6_Telescope_optics.pdf)

CTE – coefficient of thermal expansion;  $k$  – thermal conductivity  
 $\xi$  – density;  $E$  – Young's Modulus



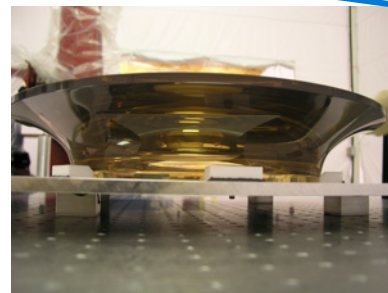
# TALK OVERVIEWS: Steve Kendrick (Ball) and Charles Kirk (ITT) on Lightweight Mirrors

## Stephen Kendrick on Mirrors

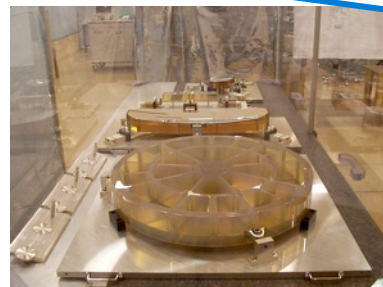
- **Mirror mass** factors include:
  - Material density and stiffness; mirror blank geometry also strongly affects stiffness
  - Manufacturing limitations on dimensions (i.e., facesheet & web thickness) as well as joining techniques
  - Testing implications (gravity deflection effects)
  - Lower mass means higher costs for the same aperture – so don't overspecify
- **Mirror construction approach (architecture solution) is usually a stronger driver of achievable lightweighting than choice of substrate material**
  - ❖ Rigid vs. semi-rigid vs flexible (meniscus or membrane) mirrors
  - ❖ Solid, open back, closed back, partially closed back, foam core, meniscus



Spitzer **Solid single arch** (Be)



HiRISE **Solid dual arch** (Zerodur®)



QuickBird **open back** (Zerodur®)



Ball IR&D **Partially closed back** (SiC)



Kepler **closed back** (ULE®)

Decreasing areal density  
generally means increasing costs

Ball has designed and implemented a range of lightweighting approaches matched to the particular system requirements



# TALK OVERVIEWS: Steve Kendrick (Ball) and Charles Kirk (ITT) on Lightweight Mirrors

“Glass” and SiC are mature telescope material technologies

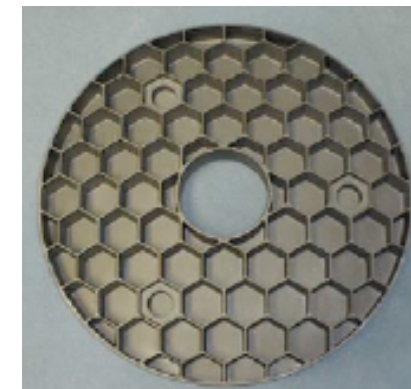


1.0 m f/2 PM with  
70% lightweighting



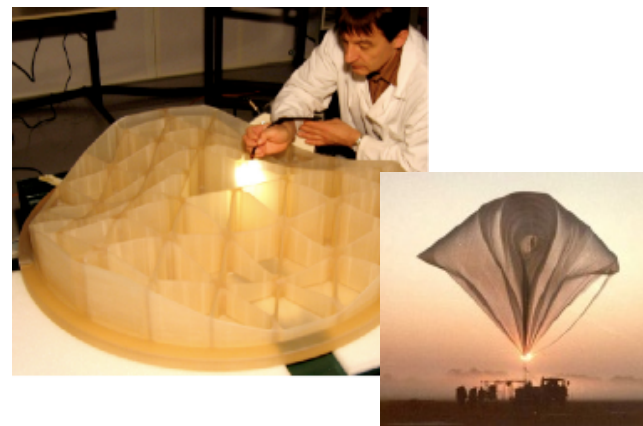
Gas-fusion **borosilicate**  
by Hextek up to 1.5m;  
15kg/m<sup>2</sup> demonstrated

**RB SiC** by SSG  
(open back  
example)  
[1.8-m capability]



Kepler 1.45-m **ULE**<sup>®</sup> closed back; ~  
50 kg/m<sup>2</sup> areal density

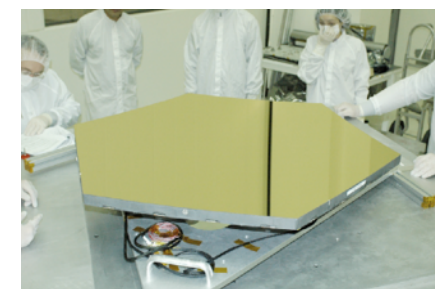
[Corning ULE<sup>®</sup> blanks can be  
fabricated up to 8m]



1-m lightweighted open-back  
**Zerodur**<sup>®</sup> PM (<40kg) fabricated by  
REOSC for SUNRISE balloon-borne  
optical solar telescope; Gregorian  
[Schott Zerodur<sup>®</sup> blanks presently  
available up to 4m; Ohara  
CLEARCERAM<sup>®</sup>-Z up to ~1.6m]



1.5-m **CVC SiC** plate  
by Trex Enterprises

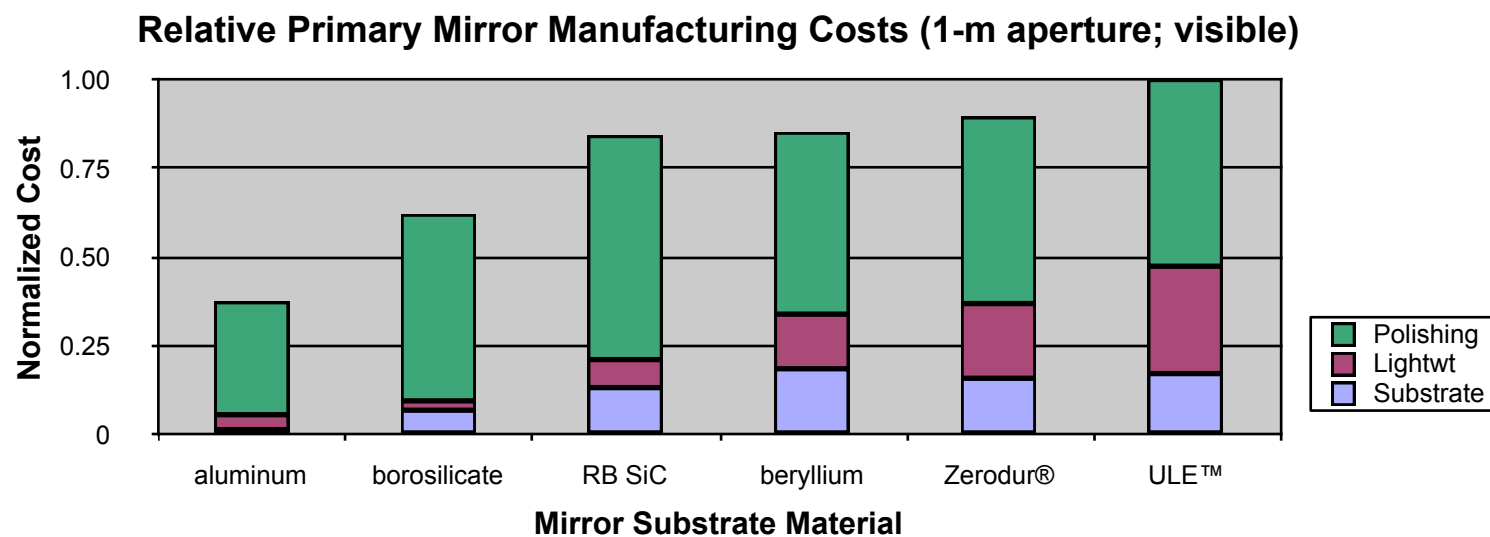


1-m **RB SiC** open back  
mirror by Xinetics  
[2-m blank capability]



# TALK OVERVIEWS: Steve Kendrick (Ball) and Charles Kirk (ITT) on Lightweight Mirrors

Polishing is often the most significant mirror fabrication cost



- For the particular application look at:
  - substrate costs
  - degree of **lightweighting** required and subsequent lightweighting cost
  - **polishing** (WFE, smoothness) requirements
    - ❖ WFE drives polishing time
    - ❖ Some materials will require cladding to achieve microroughness

## Fabrication Trade Factors

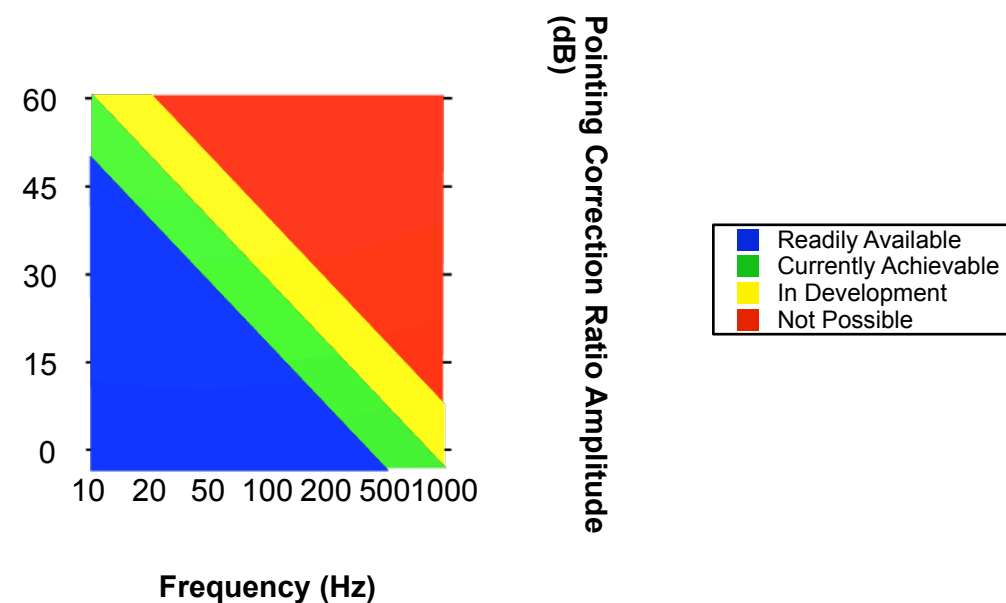
- ULE closed back construction costs more than open-back Zerodur, but offers higher degree of lightweighting
- ULE can be slumped to shape, whereas Zerodur must be machined
- Beryllium has higher stiffness, but substrate material more expensive and would require cladding for low scatter
- SiC can have lightweight features and mounting points cast, but takes slightly longer to polish; clad to reduce porosity
- Borosilicate offers optical performance with lower material and lightweighting costs if reduced thermal stability acceptable
- Aluminum material is lowest cost and can be diamond turned, but surface scatter and smearing can yield lower quality surface; Aluminum also highest mass



# TALK OVERVIEWS: Larry Germann (Left Hand Design) on Fine Pointing

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Pointing System Cost is Related to the Correction Ratio Spectrum



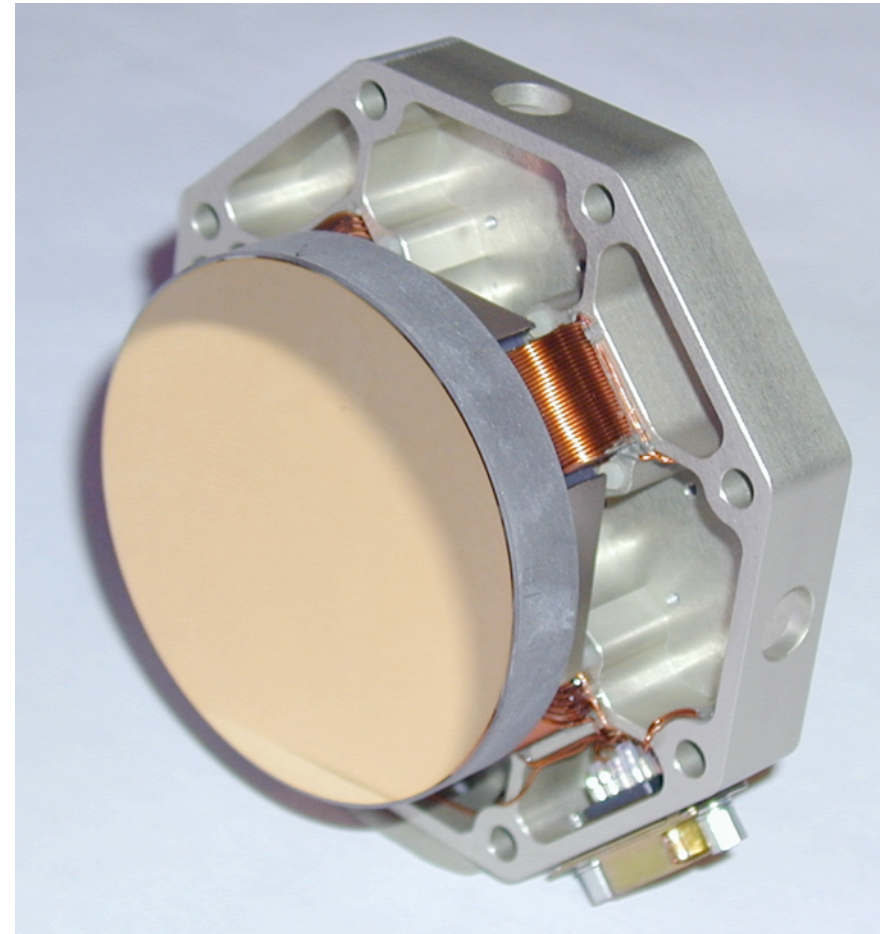
$$\text{Correction Ratio Amplitude (f)} = \text{Base Motion (f)} / \text{Residual LOS Jitter Requirement (f)}$$



# TALK OVERVIEWS: Larry Germann (Left Hand Design) on Fine Pointing

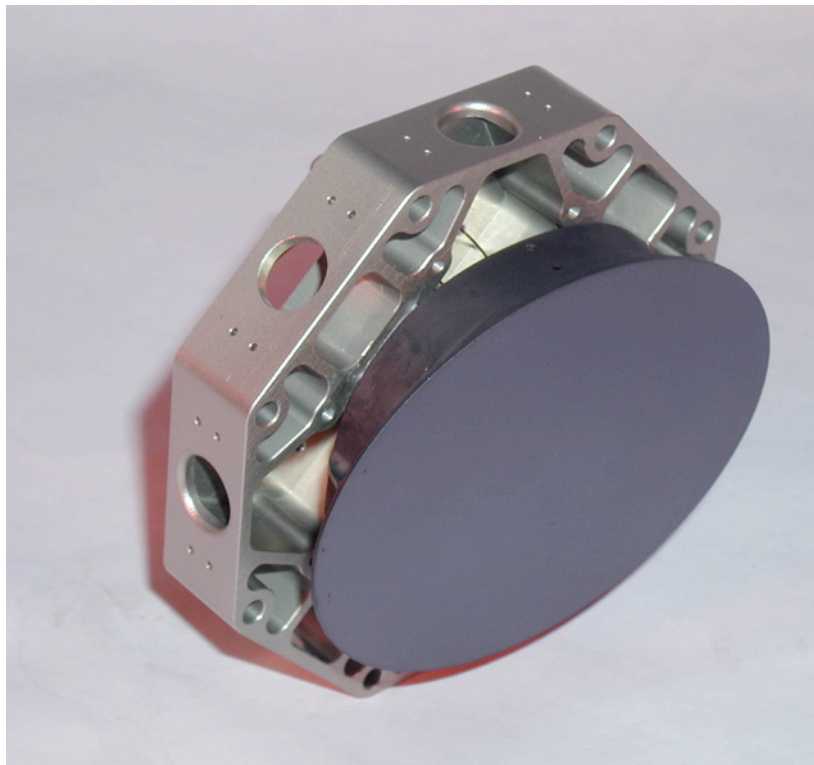
## CE50-35-CV-RC2 FSM Is Simple, Robust and Mature

- The CE75-35-BK SN140
- BK-7 mirror
- 76.2mm diameter aperture
- $\pm 35\text{mRad}$  travel
- 120 Rad/Sec<sup>2</sup>/rootW efficiency
- 2,300 Rad/Sec<sup>2</sup> acceleration
- wave PV @633nm surface figure error
- 450 Hz -3dB closed-loop servo control bandwidth



## FO50-35-SC-RT7 Achieves Record Servo Control Bandwidth

- FO50-35-SC-RT7 SN133
- Silicon carbide mirror
- 80.7 x 60mm polished aperture
- $\pm 5\text{mrad}$  travel with the reduced-travel option
- 5,000 Hz -3dB closed-loop servo control bandwidth when base-referenced
- 6,000 Hz -3dB closed-loop servo control bandwidth when optically referenced
- 3,300 Rad/Sec<sup>2</sup> acceleration





# **Eliot's Comments**

## **(or why Larry's talk on FSMs is important)**

- The natural perturbations on a balloon-borne telescope are **EASY** to correct with a Fine Steering Mirror. Even a low-cost model should do the job - frequencies are low. Self-induced perturbations may be much higher in frequency.
- An optical reference is better than a base reference. Best strategy is to have a fine motion sensor as close to the science focal plane as possible.
- Correction is only half the story. If you want to drive your FSM at 10 Hz, you probably need an optical reference signal that is sampled at 100 Hz. **CONSIDER ANALOG SENSORS**, like a quad cell of photodiodes.



# TALK OVERVIEWS: Jeff Percival (UWisc) on the ST5000 Star Tracker

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## Star Tracker 5000

A low-cost star tracker and attitude determination system



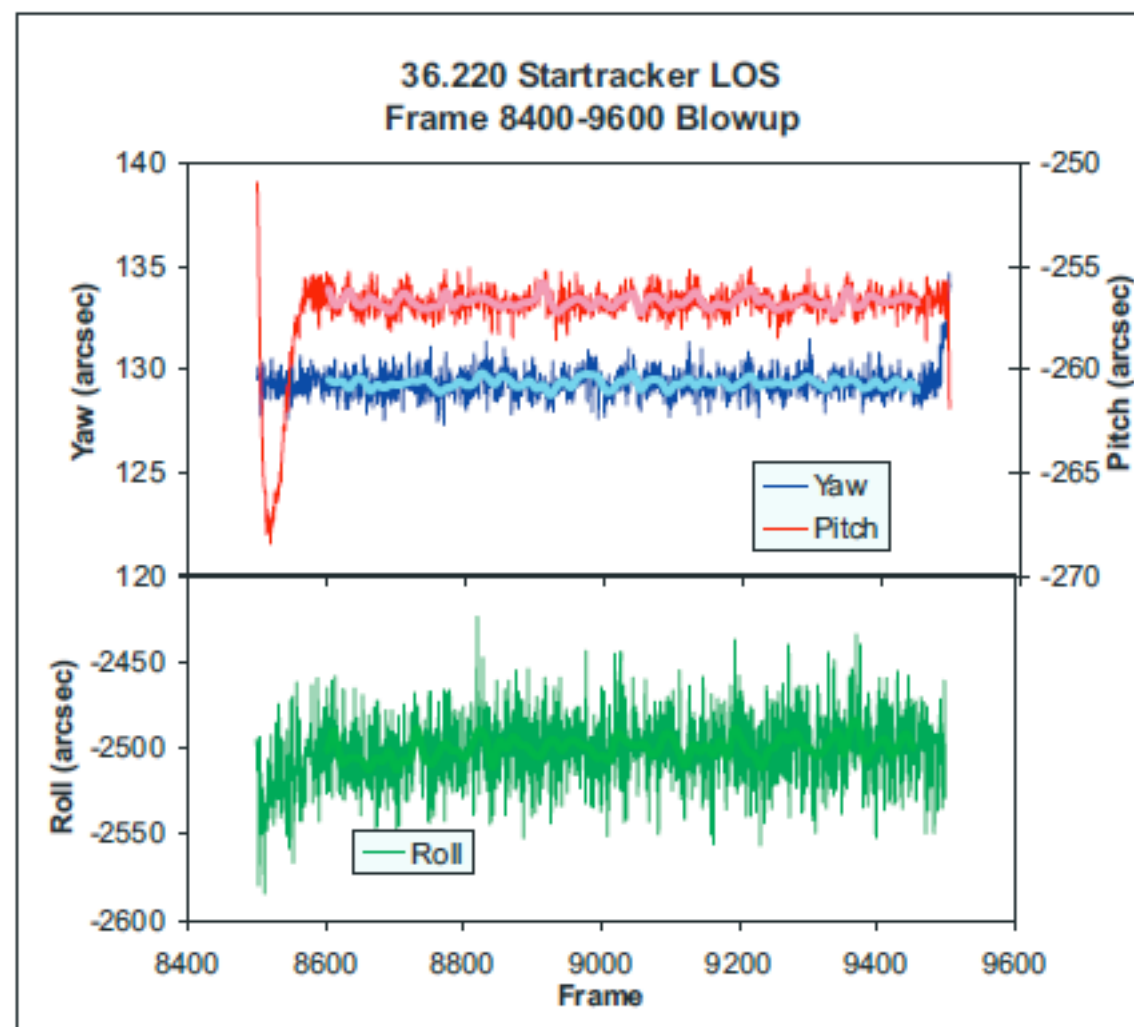


# TALK OVERVIEWS: Jeff Percival (UWisc) on the ST5000 Star Tracker

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## Tracking Performance

- ST5000 tracks at 10 Hz
- 3-axis tracking, Yaw, Pitch & Roll
- In-flight performance on sounding rocket flight 36.220:
- RMS tracking error in yaw and pitch: 0.54 arcseconds.
- RMS tracking error in roll: 17 arcseconds
- RMS errors depend on stars in the FOV: one flight had tracking errors  $> 3''$  for sparse, faint fields

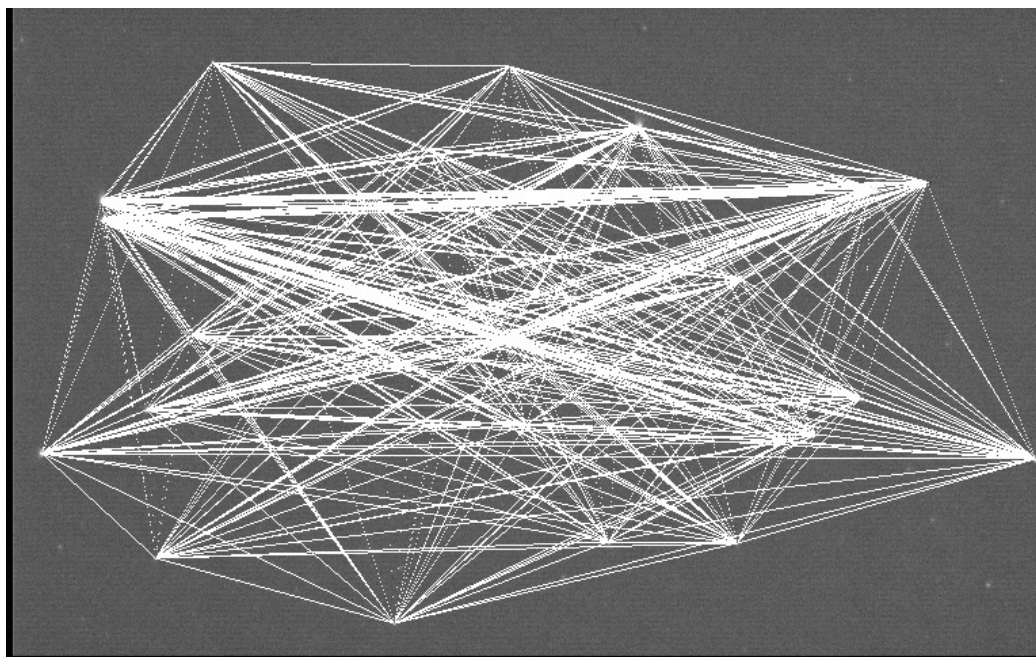




# TALK OVERVIEWS: Jeff Percival (UWisc) on the ST5000 Star Tracker

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## Attitude Determination

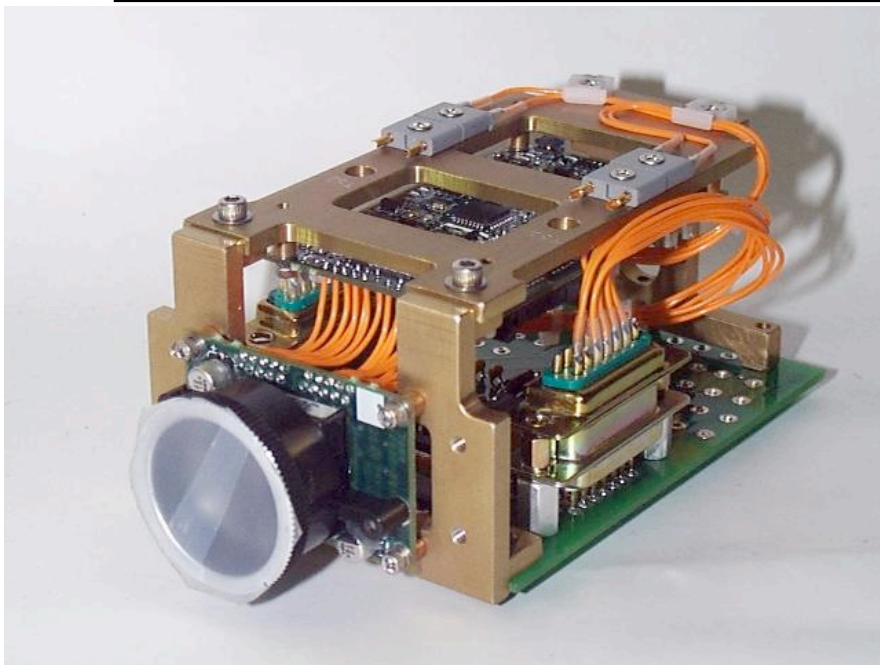


Our “lost in space” mode uses an on-board star catalog of 38400 stars with V magnitudes between 4 and 8.

- ST5000 can recognize where it's pointing by analyzing star patterns
- Some other trackers can do this, but may take long (minutes) or provide low precision (many arcminutes)
- ST5000 can solve its attitude in a few seconds, and is accurate to a few seconds of arc



# TALK OVERVIEWS: Jeff Percival (UWisc) on the ST5000 Star Tracker



Sensor electronics shown above; control electronics are in a separate box that can be up to 4 meters away.

- We use commercial “off the shelf” parts where possible
- Our Electronics Technician has decades of experience building electronics for space flight
- Assemblies must withstand very-high vibration environments (20 g)
- High accelerations: the rocket can be supersonic in 1-2 seconds

## ST5000 Status Summary

- Licensed to Northrop Grumman (non-exclusive)
- Working on a “Mark III” upgrade
  - Lower mass
  - Lower power
  - 35% reduction in obscuration
  - Faster, newer CPU (10x CPU speed, 32x more storage)
  - Redesigned sensor board and electronics
- Our cost is about \$100,000 per unit for a “sub-orbital” level of design; commercial trackers suitable for orbital or interplanetary missions start at over \$1,000,000. Our “Mark III” design will address some of these design differences.



# **Eliot's Comments (or why Jeff's talk on the ST5000 is important)**

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- Disclaimer: Jeff is a co-I with me on a NASA/APRA project to flight-qualify the ST5000 on a balloon.
- Current design should provide better than 3" pointing information AT NIGHT. Needs to be modified for daytime use.
- Current design is being superseded by the Mark III. Faster CPU, bigger CCD, smaller and lower power are the most likely changes.
- By itself, not sufficient to generate a 0.01" optical reference.
- By itself, not sufficient to generate a 1000 Hz optical reference.
- I suggest that an exoplanet telescope carries a quad cell bolted next to the science detector.

## **OTHER INTERESTING TALKS (ONLINE)**

- Orthogonal Transfer CCDs (Barry Burke, MIT/LL). For visible imaging systems, these might bridge the gap between pointing systems that can achieve 1"-2" and the target of 0.05", with no moving parts.
- Balloon-borne interferometers (Stephen Rinehart, GSFC). Question: is there enough signal to use with exoplanets?
- Small balloon systems (Tim Lachenmeier (NSC); Mike Smith (Aerostar); Dwayne Orr (CSBF)). The road to an exoplanet observing telescope will invariably follow demonstrations that will likely consist of small, focused payloads.

**[www.boulder.swri.edu/LCANS09/Talks](http://www.boulder.swri.edu/LCANS09/Talks)**



# CONCLUSIONS

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- Exoplanet observations may well be the driver that leads to an “HST in the stratosphere.” That’s good, because the requirements for observing exoplanets are stringent.
- I suggest we proceed in small, easily demonstrated steps. Example: measure seeing as a function of altitude to quantify whether tip-tilt corrections alone are good enough in the stratosphere. Another example: demonstrate temperature control of the OTA that is sufficient to maintain good enough image quality to provide HST-like performance. 3rd example: test quiet flywheel designs to provide torque-less pointing. 4th example: demonstrate a 2-stage optical reference system (e.g., a COTS star tracker/fast quad cell).
- NASA needs to hear the demand (paraphrasing an email from Jim Green, PSD). I suggest that we form a consortium to design and build generic stratospheric telescope “facilities” to which PIs could attach detectors. Possible members might include SwRI, JPL, NCAR, UWisc, UPenn, APL, NASA/Ames. One way to pool resources (IR&D funds), but even more significantly, it demonstrates the perceived value of developing this capability.