



## Science yield modeling with the Exoplanet Open-Source Imaging Mission Simulator (EXOSIMS)

Christian Delacroix, KISS Workshop, August 2016

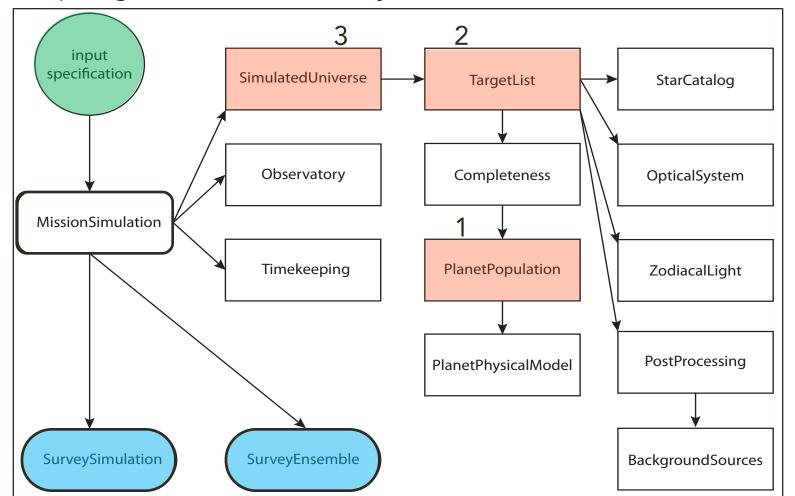
#### Collaborators:

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#### **EXoplanet Open-Source Imaging Mission Simulator**

- EXOSIMS developed as part of WFIRST Preparatory Science
- Performs ensembles of simulations to determine science yield distributions
- Modular architecture, allows multiple mission designs
- https://github.com/dsavransky/EXOSIMS



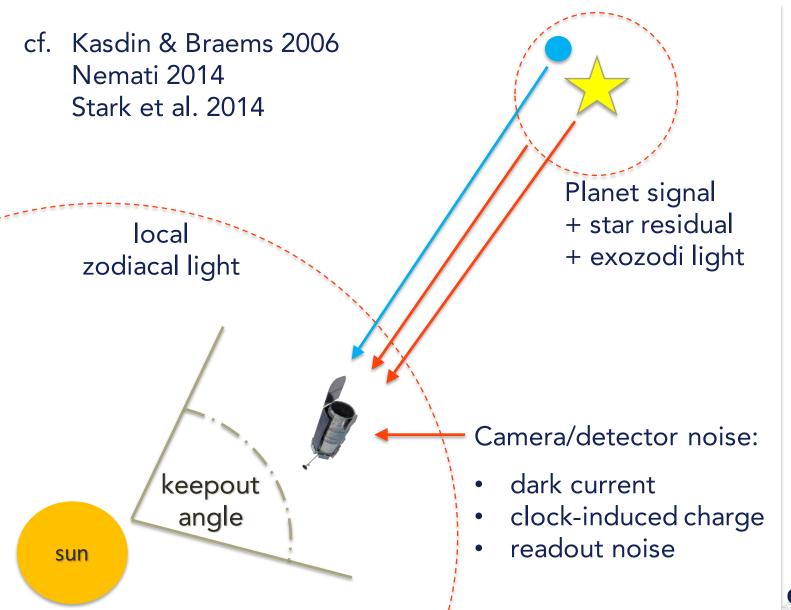


#### The Scheduler – which target to observe?

- Find spacecraft orbital START positions and filter out unavailable targets (including settling time, occulter slew time)
- Calculate integration times for the preselected targets and filter out t > threshold (arbitrary)
- Find spacecraft orbital END positions and filter out unavailable targets
- Filter out all previously visited targets, unless in revisit list (e.g. detected planets, but not yet characterized)
- From remaining, choose the target with highest completeness



### Planet integration time – noise budget





#### How do we determine integration time?

spectral flux density electron count rate

$$C_{\mathcal{F}0}(\lambda) = \epsilon A \Delta \lambda T(\lambda) \mathcal{F}_0(\lambda) \quad \text{with } \mathcal{F}_0(\lambda) = 10^{\left(4.01 - \frac{\lambda - 550}{770}\right)}$$

planet signal

Total throughput

$$C_p(\lambda) = C_{\mathcal{F}0}(\lambda) \, 10^{-0.4} \, (v \text{mag} + \Delta \text{mag})$$

star residual

$$C_{sr}(\lambda) = C_{\mathcal{F}0}(\lambda) \ 10^{-0.4 \, V\text{mag}} \, \mathbf{Q}(\lambda)$$

background noise

Instrument contrast

$$C_b(\lambda) = C_{sr}(\lambda) + C_{zl}(\lambda) + C_{dc} + C_{cc} + C_{rn}$$
zodiacal dark clock-induced read light current charge noise

SNR

$$SNR = \frac{C_p t}{\sqrt{C_p t + C_b t + (f_{pp} C_{sr} t)^2}}$$

with  $f_{pp}$  = post-processing factor

speckle residuals (systematic error)



#### Implemented detection methods

From Nemati SPIE 2014

$$t(\lambda) = \frac{(c_p + c_b) SNR^2}{c_p^2 - (SNR f_{PP} c_{sr})^2}$$

From Kasdin & Braems 2006

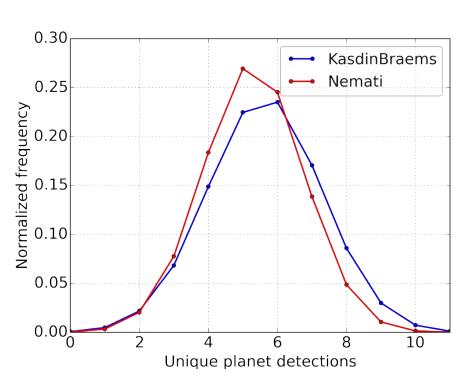
$$t(\lambda) = \frac{C_b}{C_p^2 \overline{\Delta \alpha}} \left( \mathbf{z}_{\mathsf{FA}} - \mathbf{z}_{\mathsf{MD}} \sqrt{1 + \frac{C_p \sum \overline{\mathsf{PSF}}_{\mathsf{ij}}^3}{C_b \sum \overline{\mathsf{PSF}}_{\mathsf{ij}}^2}} \right)^2$$

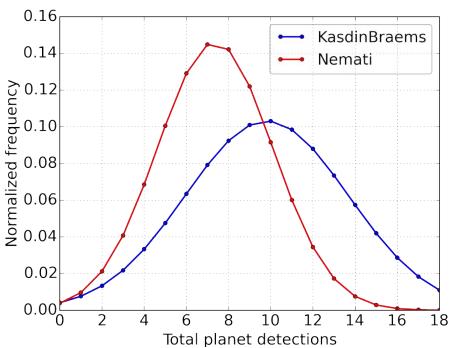
where  $\overline{\Delta \alpha}$  is the dimensionless pixel size, and  $\overline{\mathsf{PSF}}$  is the normalized PSF



#### Comparison using EXOSIMS

- method 1, Nemati 2014: setting a SNR = 5
- method 2, Kasdin 2006:  $P_{FA} = 3E-5$  and  $P_{MD} = 1E-3$







Null hypothesis  $H_0$ : there is no planet. Alternative hypothesis  $H_1$ : there is a planet.

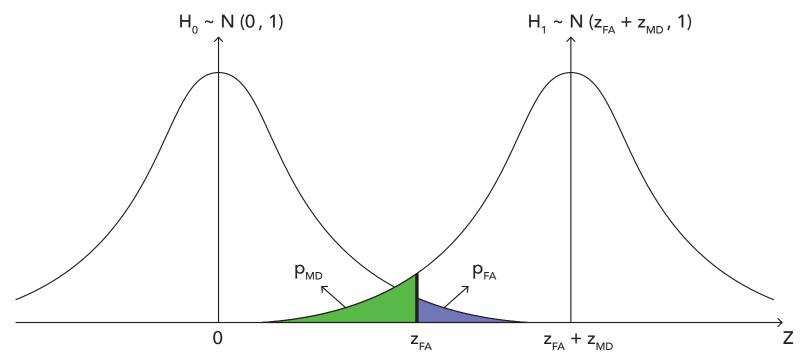
- Fail to reject  $H_0$  while true (True Negative):  $P(\text{no detection}) = P(Z < z_{FA}) = F_Z(z_{FA}) = 1 p_{FA}$
- Reject  $H_0$  while true (type I error, False Positive):  $P(false\ alarm) = p_{FA}$

- Reject H<sub>0</sub> while false (True Positive):

$$P(detection) = P (Z < z_{MD}) = F_{_{Z}}(z_{MD}) = 1 - p_{_{MD}}$$

- Fail to reject H<sub>0</sub> while false (type II error, False Negative):

 $P(missed detection) = p_{MD}$ 



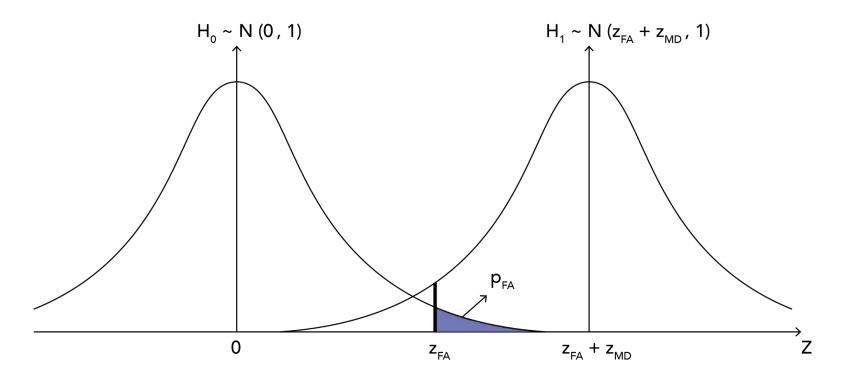
#### Probabilistic case

Case 1, no calculated SNR.

For the whole system:

- True Negative: P(no detection) =  $F_z(z_{FA}) = 1 - p_{FA}$ 

- False Positive:  $P(false alarm) = p_{FA}$ 



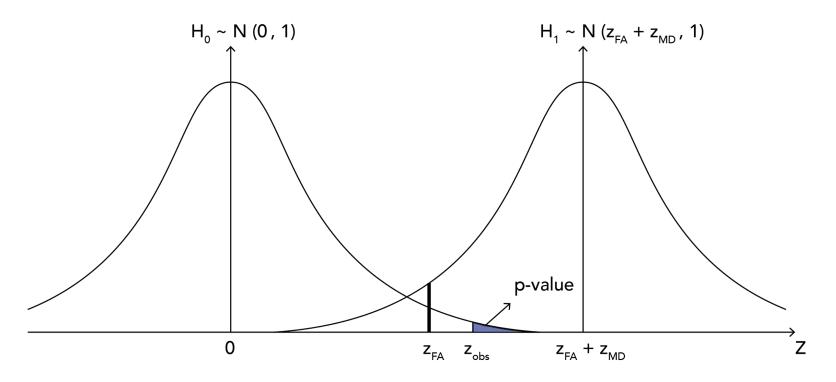


#### Probabilistic case (cont'd)

Case 2.1, calculated SNR =  $z_{obs} > z_{FA} --> reject H_0$ .

- True Positive:  $P(detection) = P(Z < z_{obs}) = F_{Z}(z_{obs})$ 

- False Positive: P(false alarm) = 1 -  $F_Z(z_{obs})$  = p-value

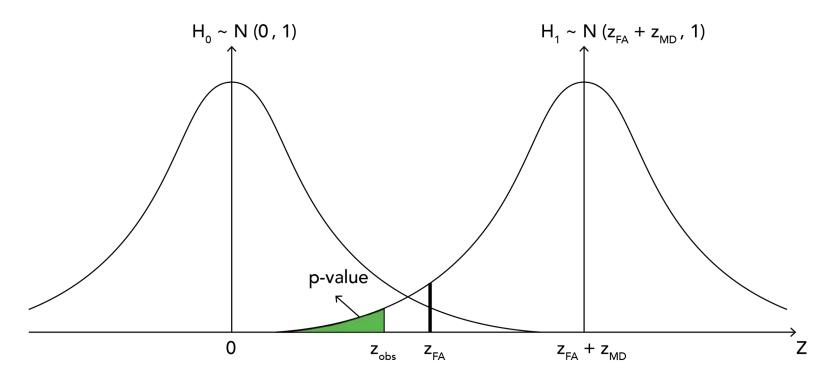




#### Probabilistic case (cont'd)

Case 2.2, calculated SNR =  $z_{obs} < z_{FA} -->$  fail to reject  $H_0$ .

- True Negative: P(no detection) = P(Z <  $z_{FA}$  +  $z_{MD}$   $z_{obs}$ ) =  $F_{Z}(z_{FA}$  +  $z_{MD}$   $z_{obs}$ )
- False Negative: P(missed detection) = 1  $F_z(z_{FA} + z_{MD} z_{obs}) = p$ -value





### Backup slides



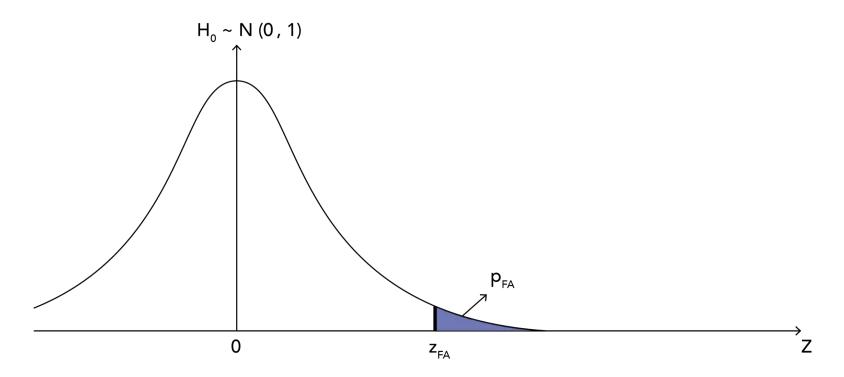
# Deterministic case We 'know' if there is a planet or not

Case 1, there is no planet,  $H_0$  is true.

For the whole system:

- True Negative: P(no detection) =  $F_z(z_{FA}) = 1 - p_{FA}$ 

- False Positive:  $P(false alarm) = p_{FA}$ 

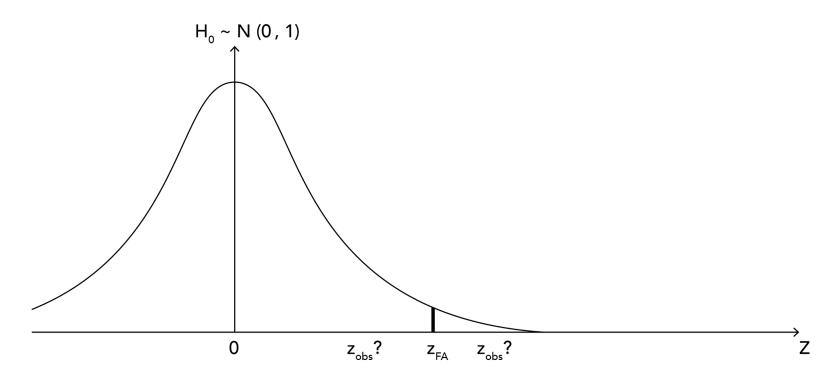




#### Deterministic case (cont'd)

Case 2, there is a planet,  $H_0$  is false.

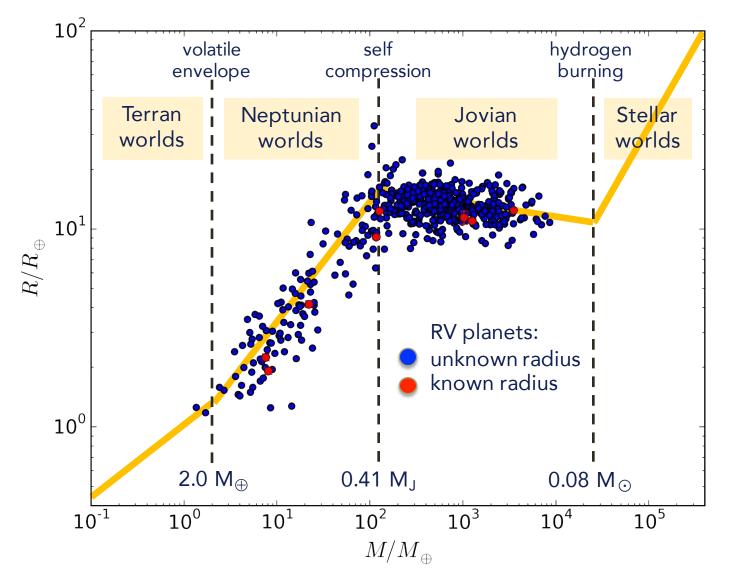
- if  $SNR = z_{obs} > z_{FA}$  --> reject  $H_0$ : True Positive (detection)
- if  $SNR = z_{obs} < z_{FA}$  --> fail to reject  $H_0$ : False Negative (missed detection)





### Populate Universe: e.g. known RV planets

M-R relation from FORECASTER (Chen and Kippling 2016) available at github.com/chenjj2/forecaster

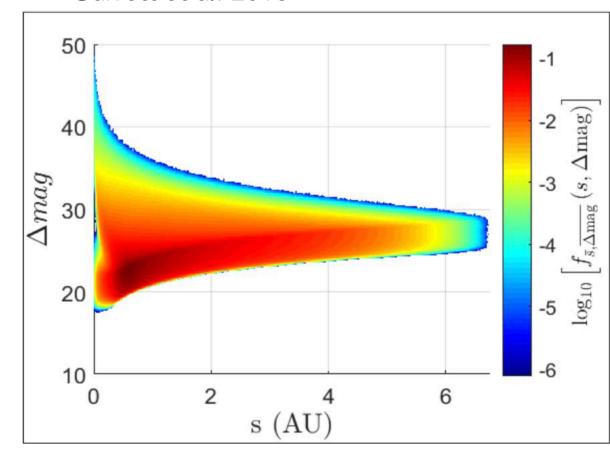




### Example of joint probability density function

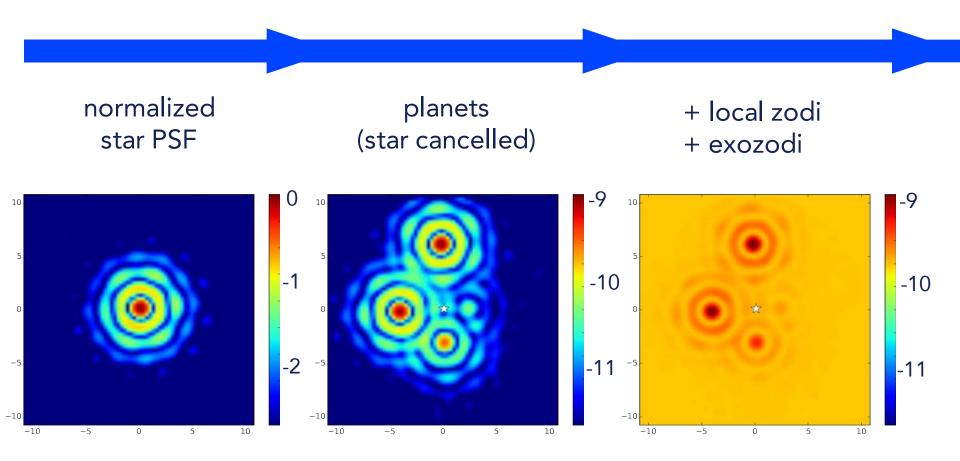
- PDF of planet orbital and physical properties
- Completeness = CDF (cf. Brown 2005)
- Probability to detect a planet
- Updates completeness values for systems previously observed

#### Garrett et al. 2016



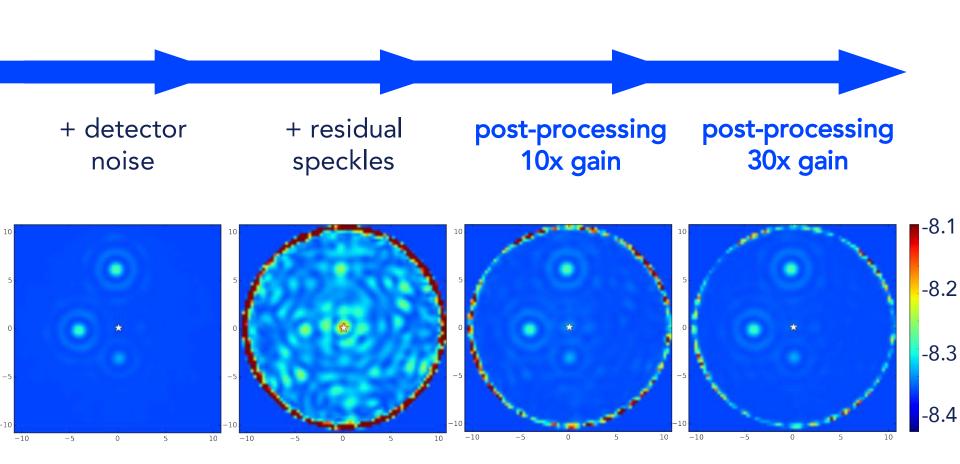


# Planet integration time – noise budget (cont'd)





## Planet integration time – noise budget (cont'd)





#### e.g. WFIRST contrast/throughput curve

