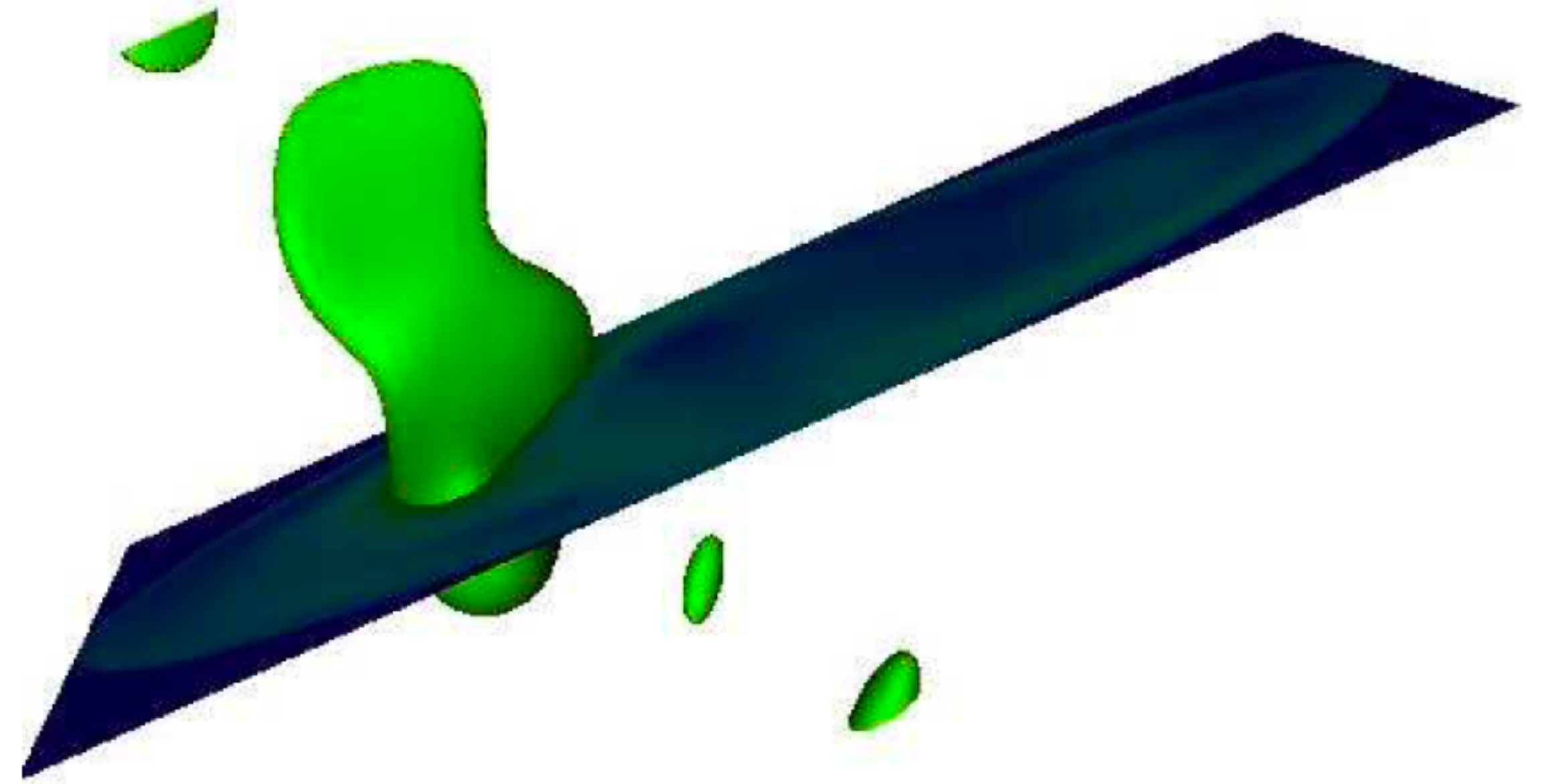
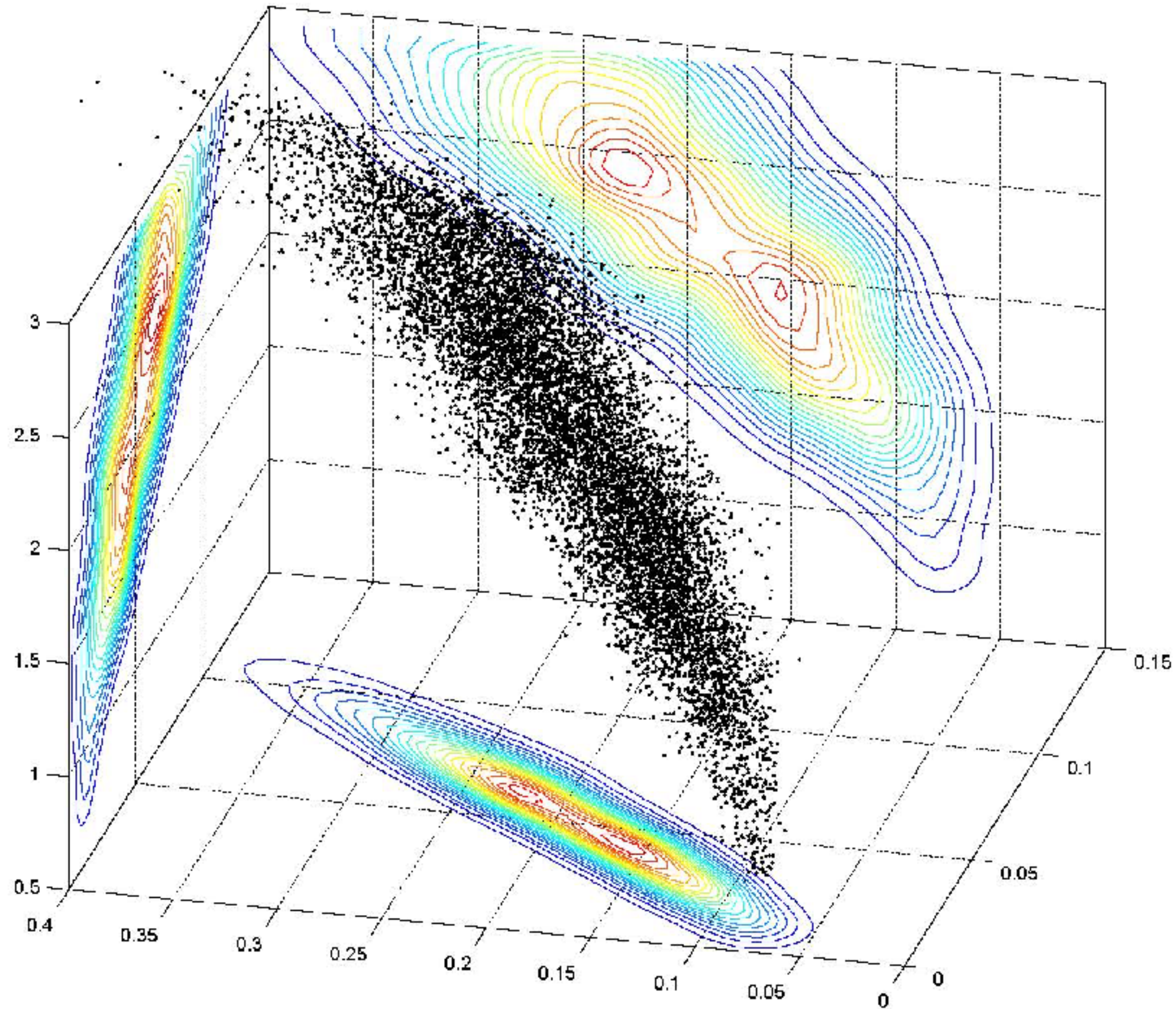


# Stochastic Methods in LISA Searches





Saturday, 25 March 1995

# 11th Pacific Coast Gravity Meeting 24-25 Mar 1995. Pasadena, California

8:30 Coffee and donuts

\*\*\*\* Experimental Gravity and Gravitational Radiation \*\*\*\*

8:45 Koya Suehiro "Operation of 20m Fabry-Perot prototype  
sue@gravity.mtk.nao.ac.jp with modecleaner"  
National Astronomical Observatory,  
Japan

9:00 Joe Weber "Gravitational Antenna Observations"  
???  
UC Irvine

9:15 Albert Lazzarini "Overview and Status of Ligo Project"  
lazz@ligo.caltech.edu  
Caltech

9:30 Aaron Gillespie "Installation of New Test Masses in the  
aaron@ligo.caltech.edu 40-meter Interferometer"  
Caltech

9:45 Torrey Lyons "Recombination of the 40-m Interferometer"  
torrey@ligo.caltech.edu  
Caltech

10:00 Alan Wiseman "Gravitational Wave Signals from  
agw@tapir.caltech.edu Coalescing Binaries"  
Caltech

10:15 Bill Folkner "LISA - Laser Interferometer Space Antenna  
wmf@logos.jpl.nasa.gov for Gravitational Wave Measurements"  
JPL



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# 11th Pacific Coast Gravity Meeting 24-25 Mar 1995. Pasadena, California





Déjà vu: Analysis Methods for Interferometric Gravitational-wave  
Observations from Space (AMIGOS)  
Caltech, Oct 13-15, 2005



AMIGOS  
Combined Analyses

Neil Cornish

## AMIGOS Section 7.3.3 Risks

- ⚠ Not thinking about combined analyses early enough
- ⚠ Data Gaps/Disturbances - may significantly worsen confusion problem
- ⚠ Magnitude of problem not understood (what effort needs to be devoted, not enough, early enough)



Déjà vu: Analysis Methods for Interferometric Gravitational-wave  
Observations from Space (AMIGOS)  
Caltech, Oct 13-15, 2005



n 7.3.3

analyses early

significantly

erstood (what  
enough, early

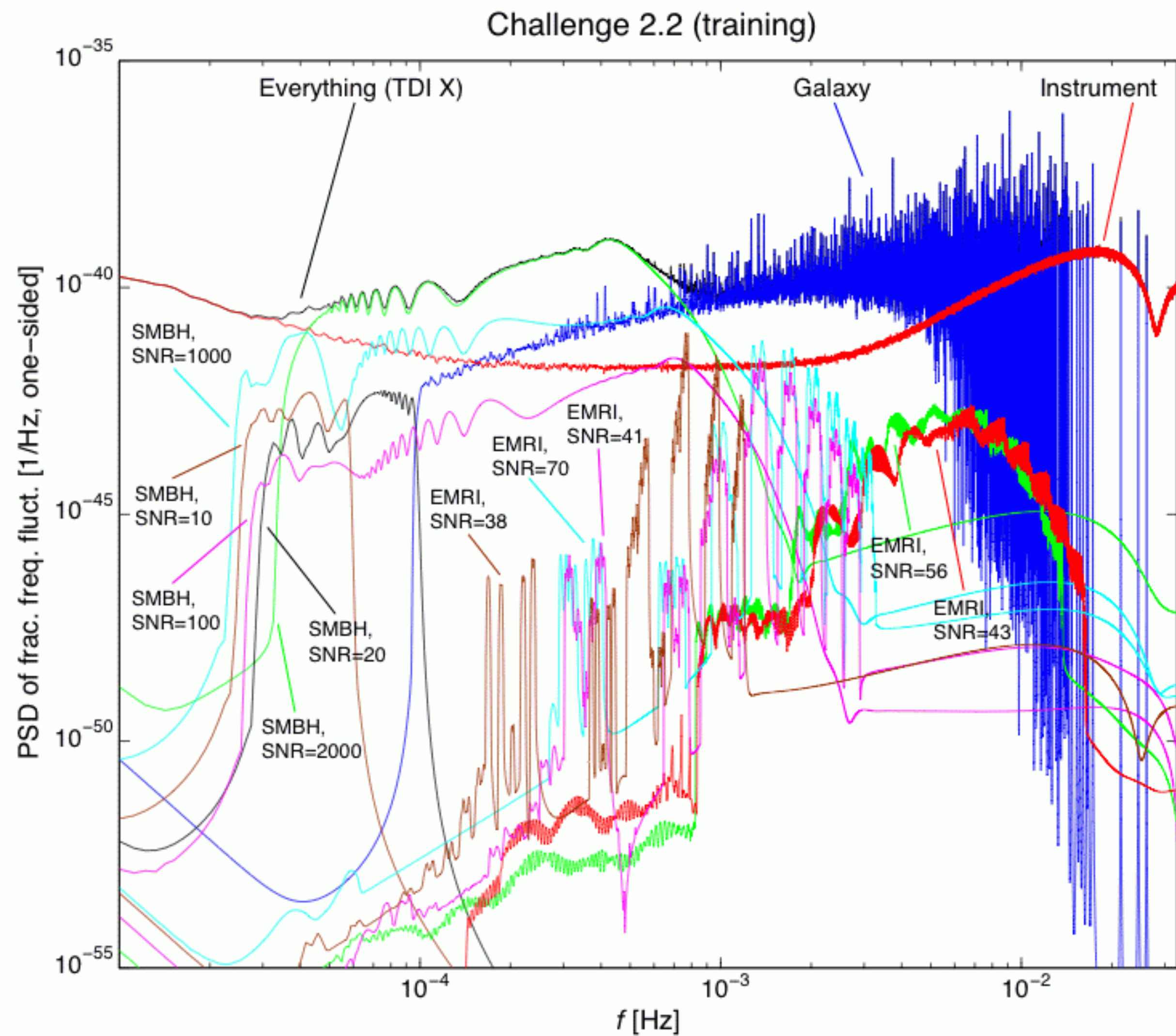


# Outline

- Signal and Noise model
- Likelihood function for non-stationary noise
- Trans-dimensional Bayesian modeling
- Galactic binaries
- EMRIs



# Signal & Noise models



$$p(\mathbf{d}|\mathbf{h}) = \frac{1}{\sqrt{\det(2\pi\mathbf{C})}} e^{-\frac{1}{2}(\mathbf{d}-\mathbf{h})^\dagger \mathbf{C}^{-1}(\mathbf{d}-\mathbf{h})}$$

Noise will be non-stationary and possibly non-Gaussian

$$\mathbf{h} = \sum_{j=1}^N \mathbf{h}_j(\vec{\lambda}_j)$$

Signal model is the sum over all  $N$  resolvable signals (convolved with the instrument response)

The number  $N$  of resolvable signals is *a priori* unknown. Parameters of the signals also unknown

Some of the signals are extremely complex (e.g. EMRIs)



## Likelihood for Non-stationary Gaussian Noise

$$p(\mathbf{d}|\mathbf{h}) = \frac{1}{\sqrt{\det(2\pi\mathbf{C})}} e^{-\frac{1}{2}(\mathbf{d}-\mathbf{h})^\dagger \mathbf{C}^{-1}(\mathbf{d}-\mathbf{h})}$$

Cost of computing the likelihood is far less in a representation where the noise correlation matrix  $\mathbf{C}$  is diagonal

e.g. Colored stationary noise has a diagonal noise correlation matrix in the Fourier domain

Pulsar Timing has to deal with colored, non-stationary data and un-even sampling - analysis performed directly in the time domain. Clever tricks have been developed to speed up the costly matrix inversions and sums



# Likelihood for Non-stationary Gaussian Noise

$$p(\mathbf{d}|\mathbf{h}) = \frac{1}{\sqrt{\det(2\pi\mathbf{C})}} e^{-\frac{1}{2}(\mathbf{d}-\mathbf{h})^\dagger \mathbf{C}^{-1}(\mathbf{d}-\mathbf{h})}$$

Cost of computing the likelihood is far less in a representation where the noise correlation matrix  $\mathbf{C}$  is diagonal

For a large class of discrete wavelet transformations and locally stationary noise <sup>[1]</sup>

$$C_{(i,j)(k,l)} = \delta_{ij}\delta_{kl} C_{ik} \quad [2]$$

Time      Frequency

This is the likelihood used by the LIGO coherent WaveBurst algorithm

[1. "Fitting time series models to nonstationary processes". Dahlhaus, Ann. Statist., 25, 1 (1997)]

[2. "Wavelet processes and adaptive estimation of the evolutionary wavelet spectrum", Nason, von Sachs, & Kroisandt, J. R. Statist. Soc. Series B62, 271 (2000)]

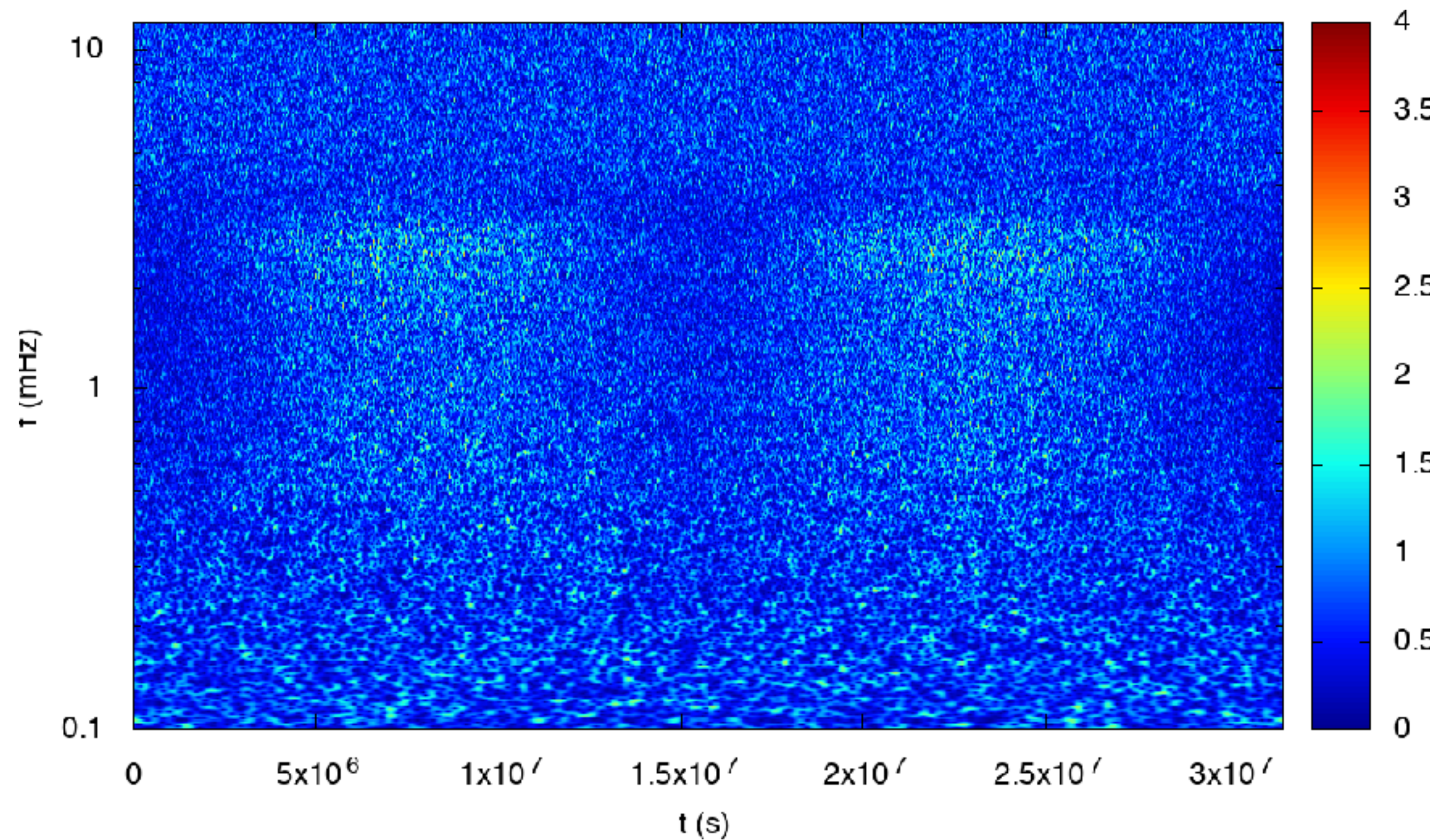


# Likelihood for Non-stationary Gaussian Noise

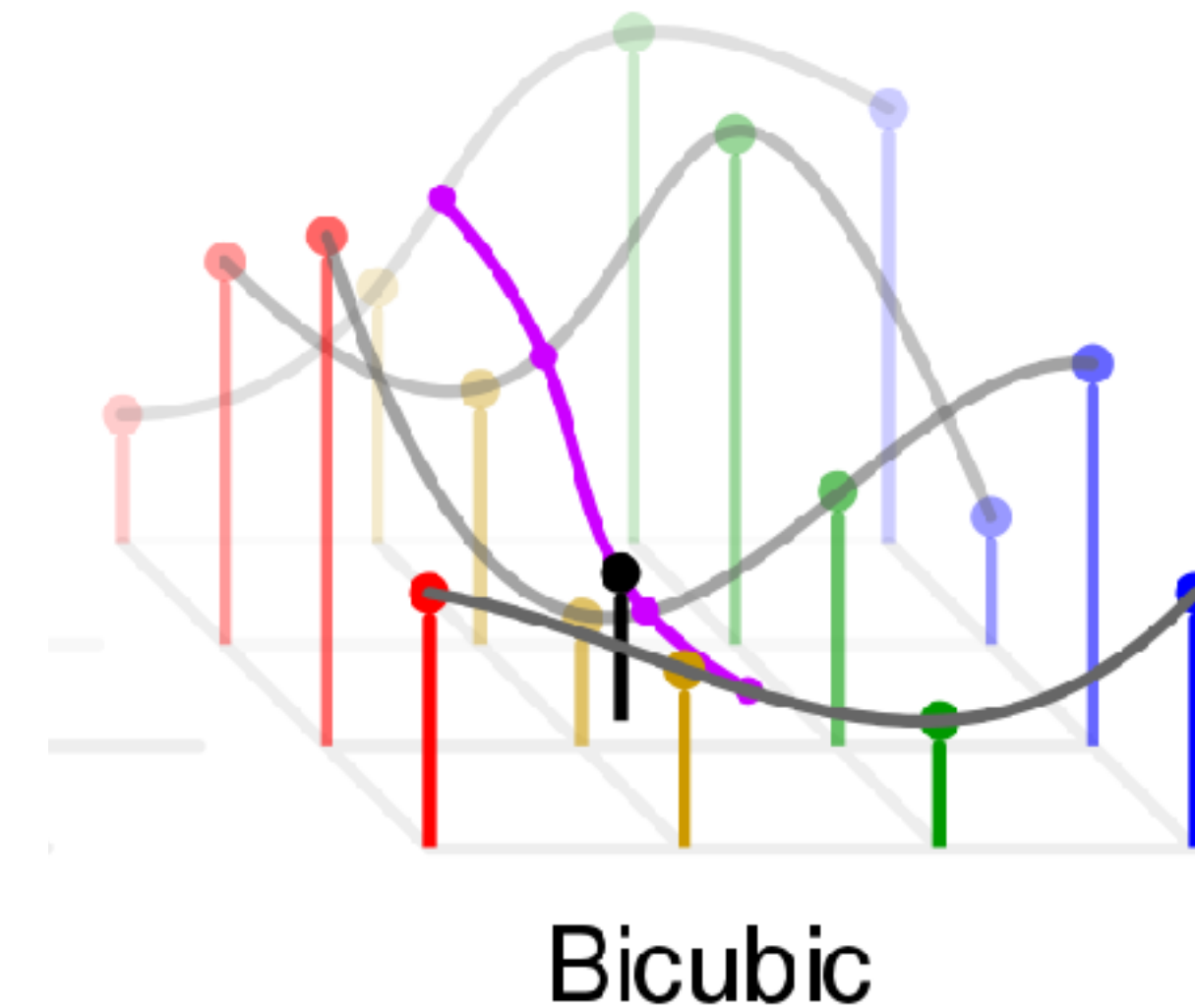
$$p(\mathbf{d}|\mathbf{h}) = \frac{1}{\sqrt{\det(2\pi\mathbf{C})}} e^{-\frac{1}{2}(\mathbf{d}-\mathbf{h})^\dagger \mathbf{C}^{-1}(\mathbf{d}-\mathbf{h})}$$

Propose that we use a discrete wavelet based likelihood for LISA data analysis

$$C_{(i,j)(k,l)} = \delta_{ij}\delta_{kl} C_{ik}$$



Model the wavelet spectrum  $C_{ik}$  as a smooth function in frequency and time. E.g. Trans-dimensional Bicubic spline

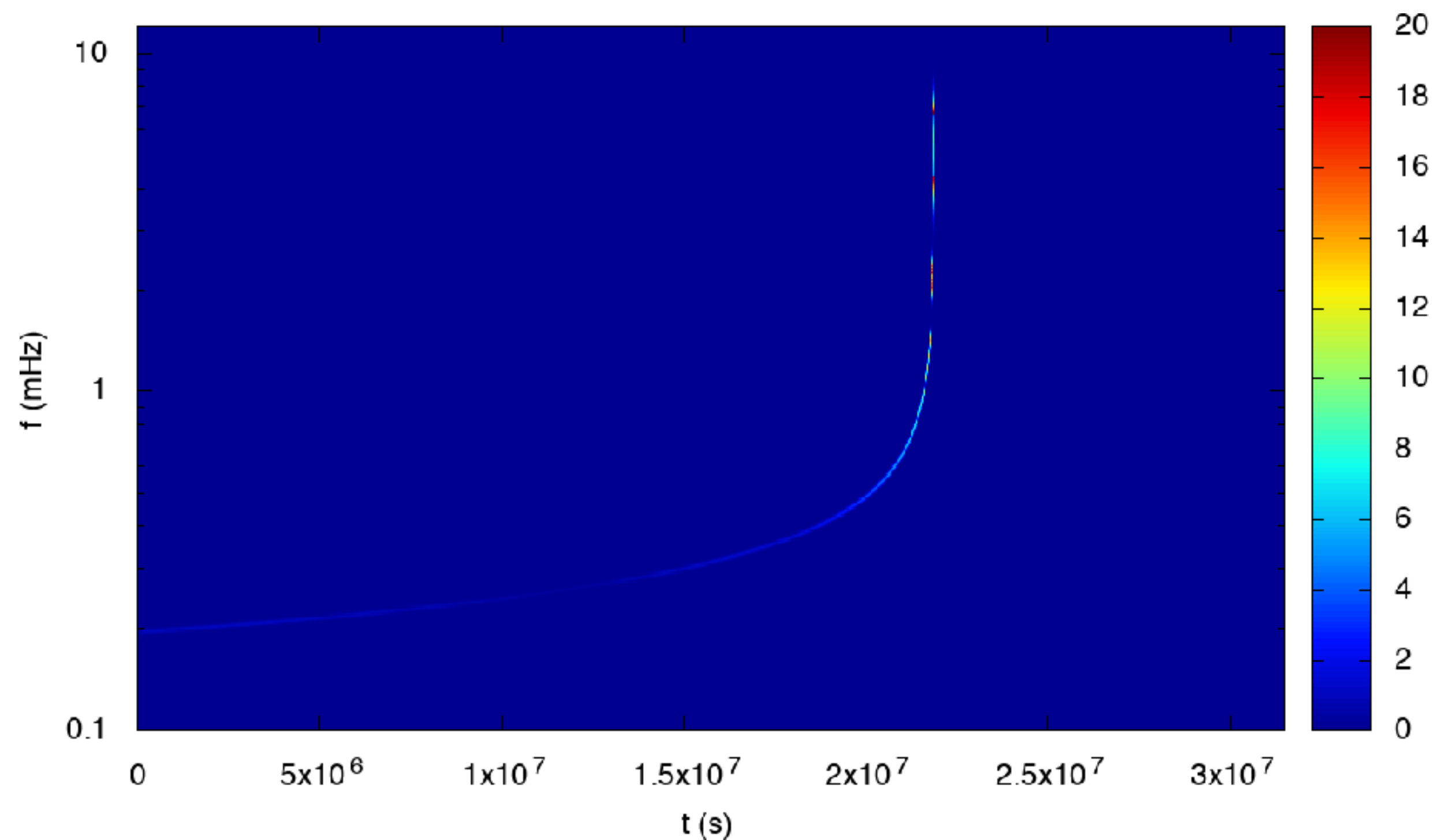




# Likelihood for Non-stationary Gaussian Noise

$$p(\mathbf{d}|\mathbf{h}) = \frac{1}{\sqrt{\det(2\pi\mathbf{C})}} e^{-\frac{1}{2}(\mathbf{d}-\mathbf{h})^\dagger \mathbf{C}^{-1}(\mathbf{d}-\mathbf{h})}$$

Propose that we use a discrete wavelet based likelihood for LISA data analysis  $C_{(i,j)(k,l)} = \delta_{ij}\delta_{kl} C_{ik}$



Need fast wavelet transforms of the signals for computational efficiency

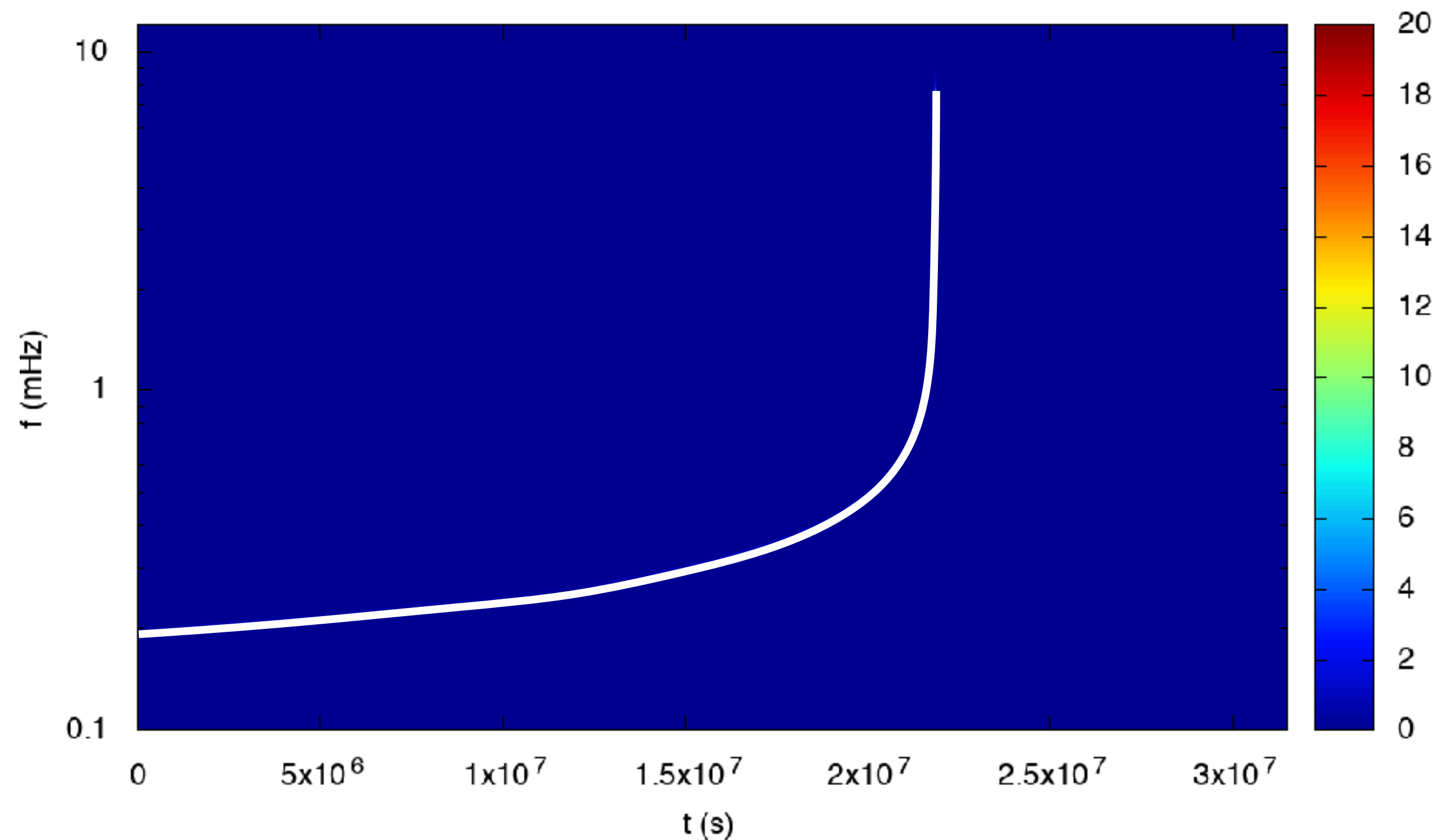
Use SPA to derive analytic wavelet domain waveforms?



# Likelihood for Non-stationary Gaussian Noise

$$p(\mathbf{d}|\mathbf{h}) = \frac{1}{\sqrt{\det(2\pi\mathbf{C})}} e^{-\frac{1}{2}(\mathbf{d}-\mathbf{h})^\dagger \mathbf{C}^{-1}(\mathbf{d}-\mathbf{h})}$$

Propose that we use a discrete wavelet based likelihood for LISA data analysis  $C_{(i,j)(k,l)} = \delta_{ij}\delta_{kl} C_{ik}$



Need fast wavelet transforms of the signals for computational efficiency

Use SPA to derive analytic wavelet domain waveforms?

Only compute wavelets along predicted t-f track?



# The Global Solution

$$\chi^2 = (\mathbf{d} - \mathbf{h} | \mathbf{d} - \mathbf{h}) = (\mathbf{d} | \mathbf{d}) - 2 \log \Lambda$$

Relative likelihood  $\log \Lambda = (\mathbf{d} | \mathbf{h}) - \frac{1}{2} (\mathbf{h} | \mathbf{h})$       Single source RL  $\log \Lambda_i = (\mathbf{d} | \mathbf{h}_i) - \frac{1}{2} (\mathbf{h}_i | \mathbf{h}_i)$

$$\log \Lambda = \sum_i \log \Lambda_i - \sum_{i>j} (\mathbf{h}_i | \mathbf{h}_j)$$

← Source confusion

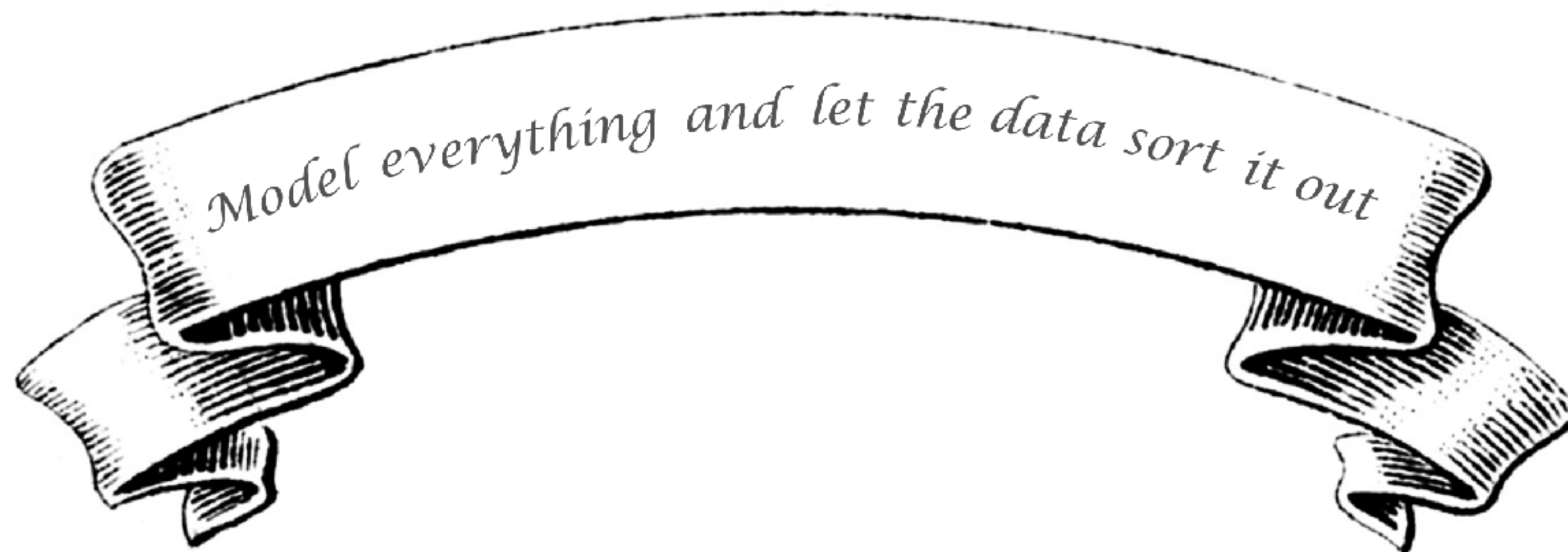
The typical overlaps between any two signals are very small (exceptions are WD binaries with ~same frequency and similar sky location). But, there are many signals, so the confusion adds up.

Any unresolved signals act as an effective noise term (though non-Gaussian and non-stationary)

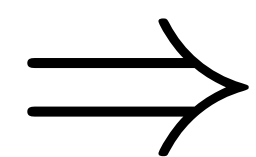
[Cutler & Harms, Phys.Rev. **D73** 042001 (2006)]

[Robson & Cornish, Class.Quant.Grav. **34** 244002 (2017) ]

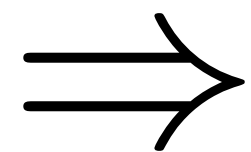




Unknown number of signals and source parameters. Noise model of unknown complexity



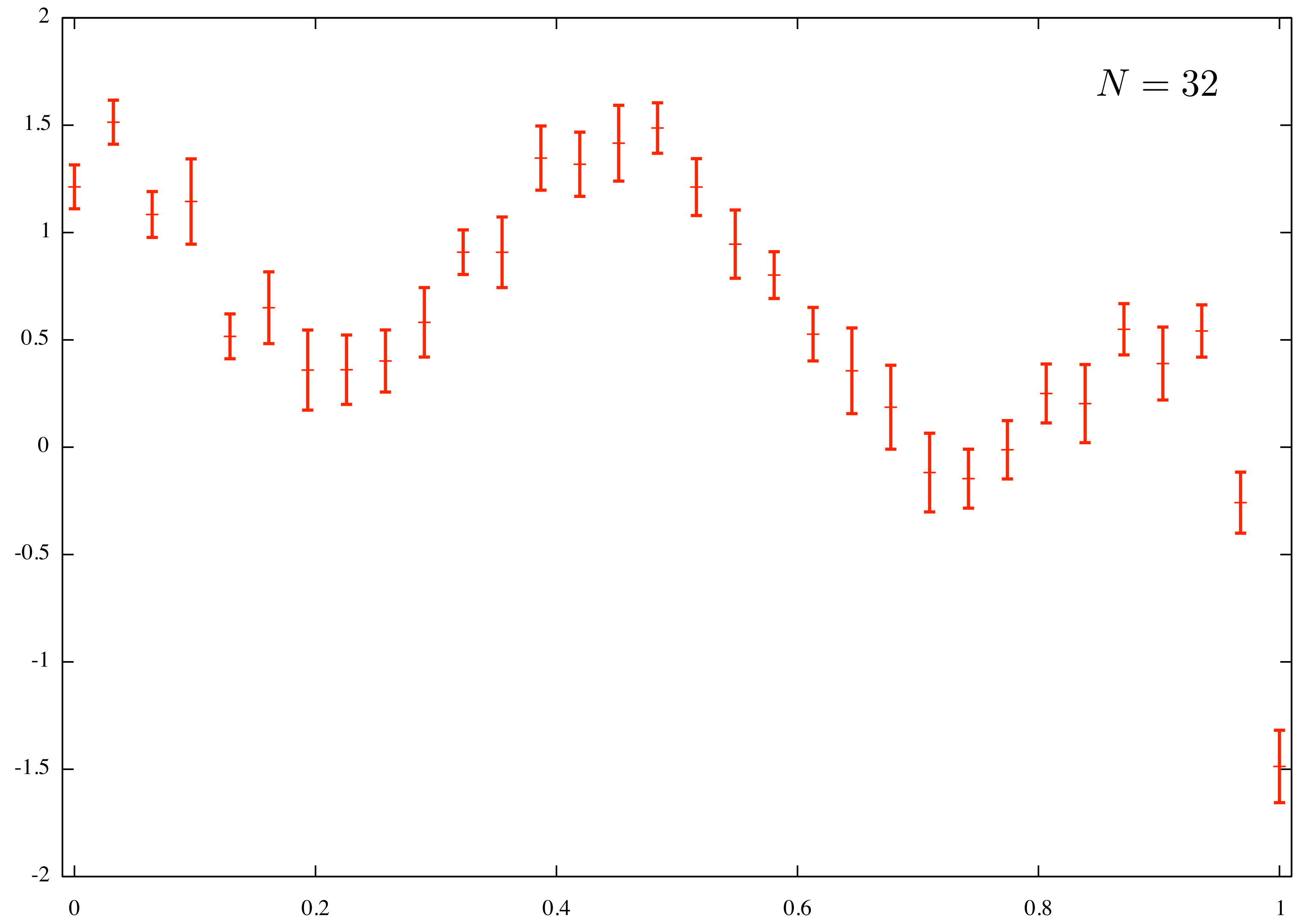
**Let the data decide the model dimension**



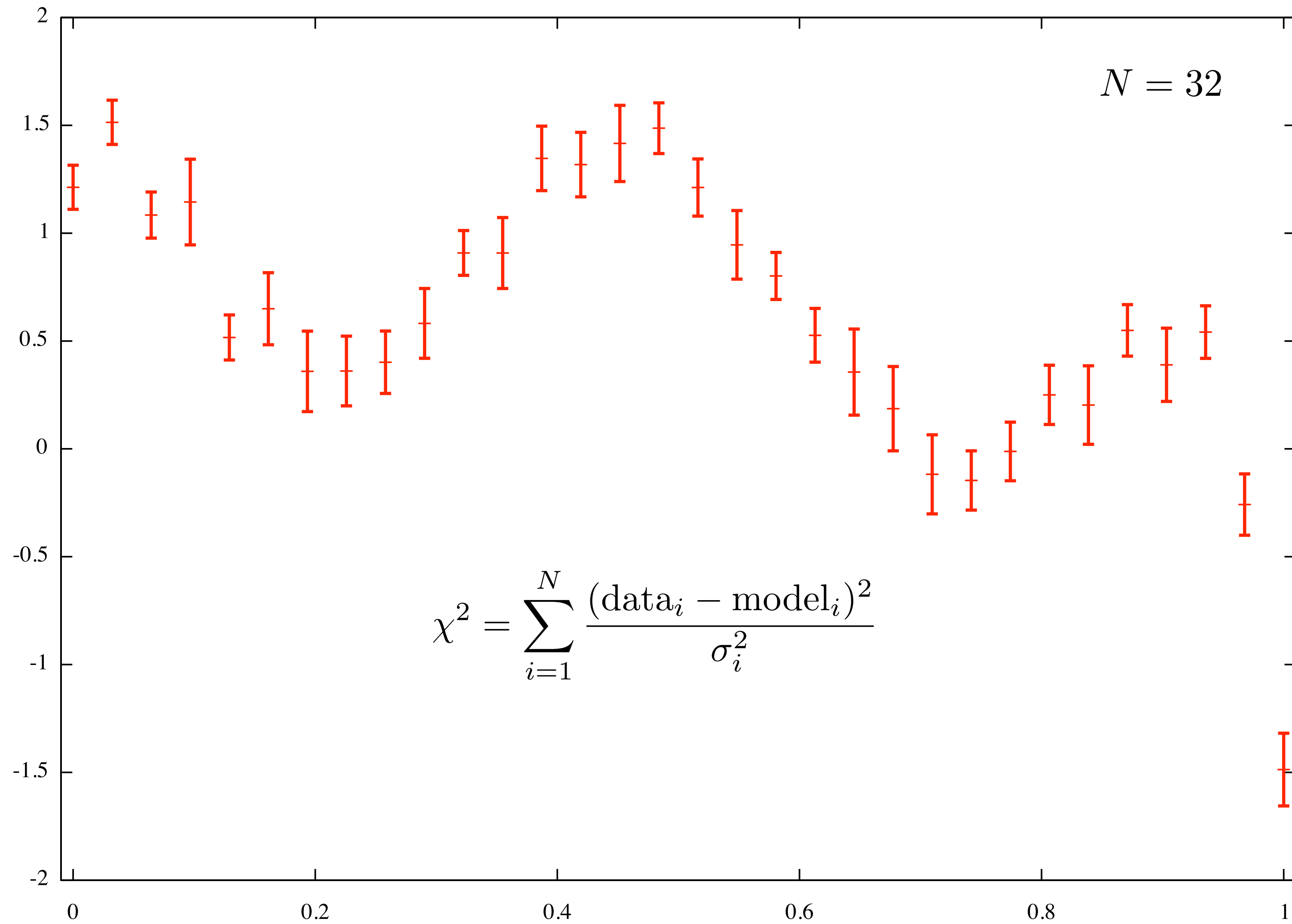
**Make the model dimension a parameter**

Trans-dimensional Markov Chain Monte Carlo

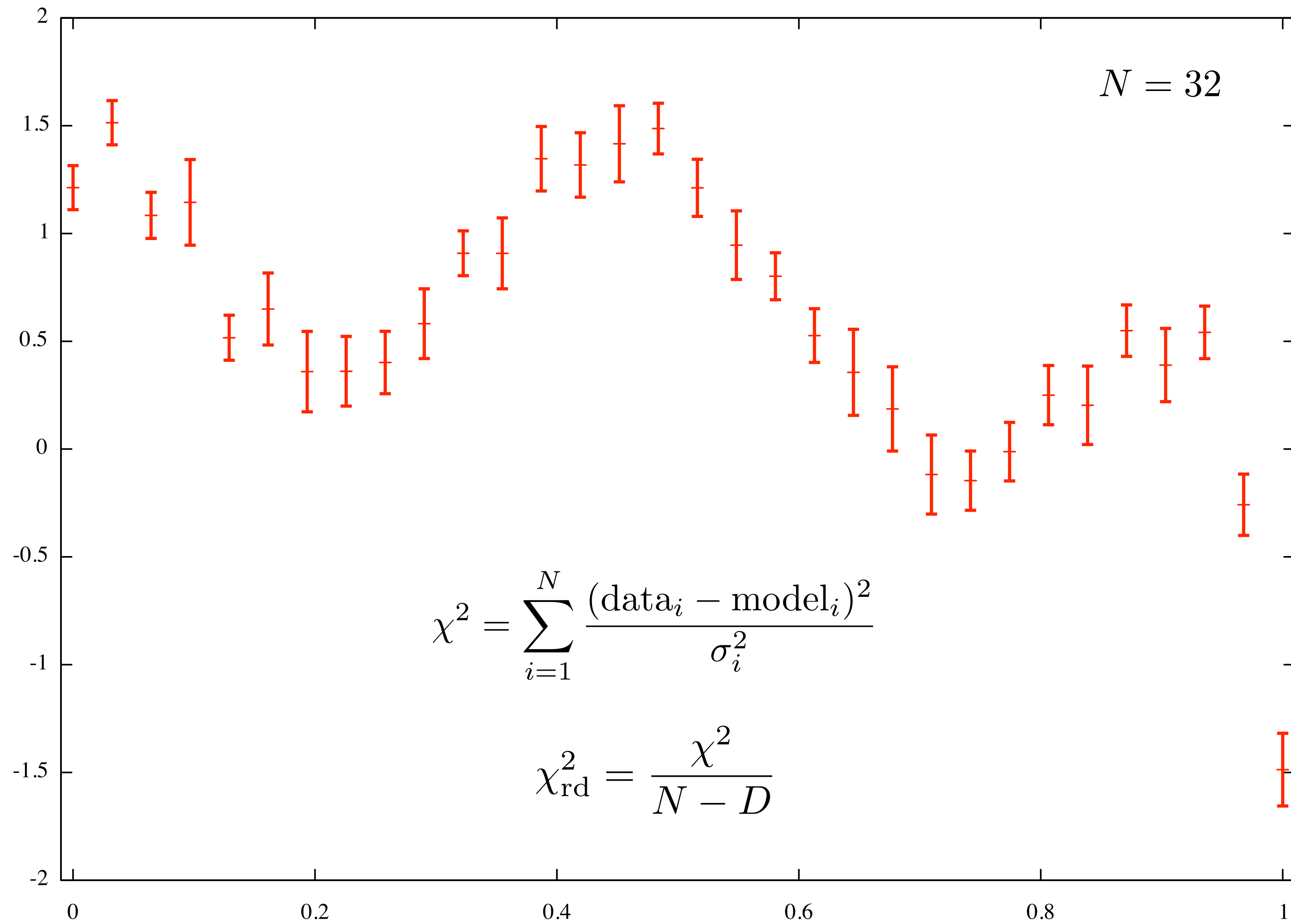




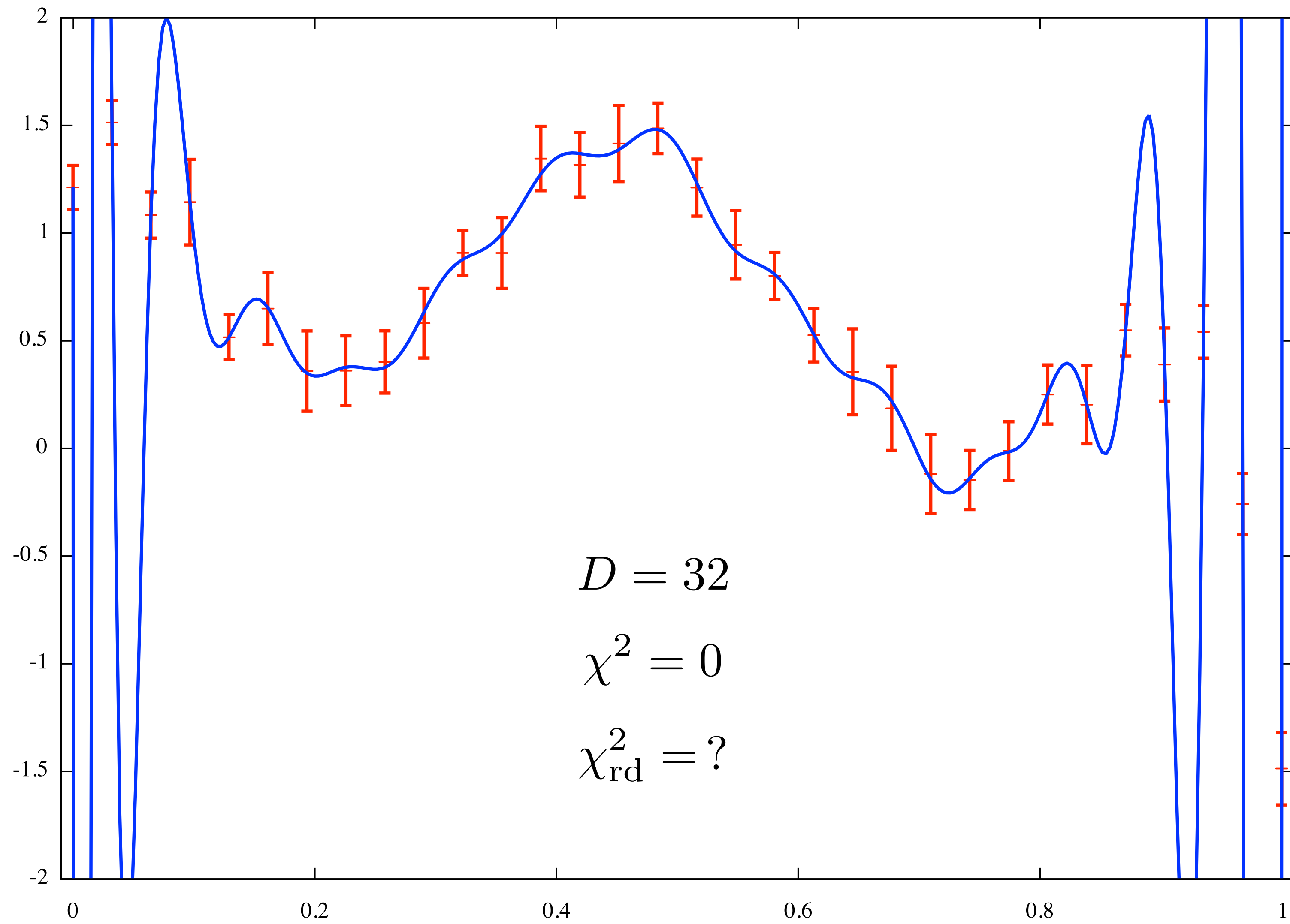


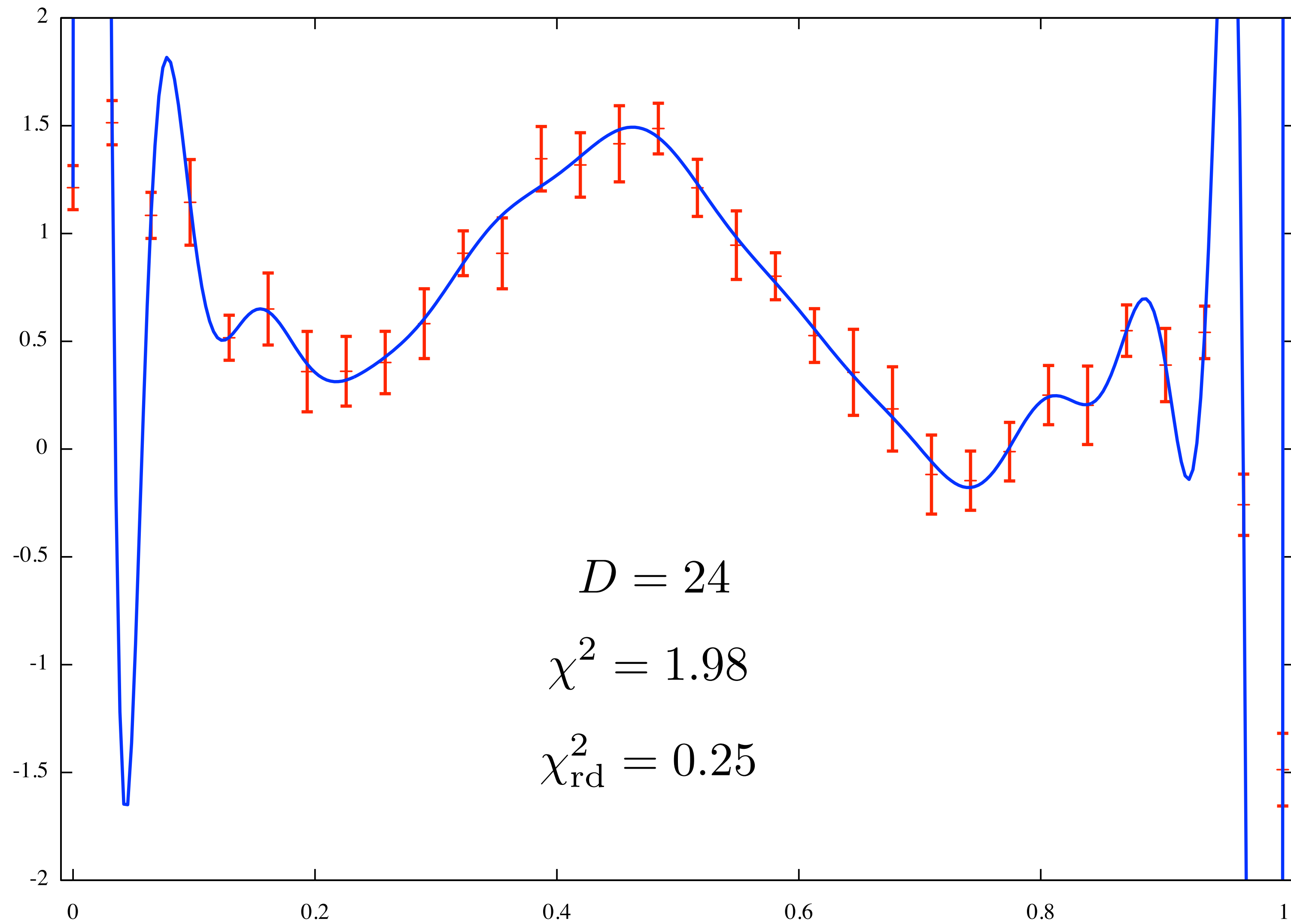




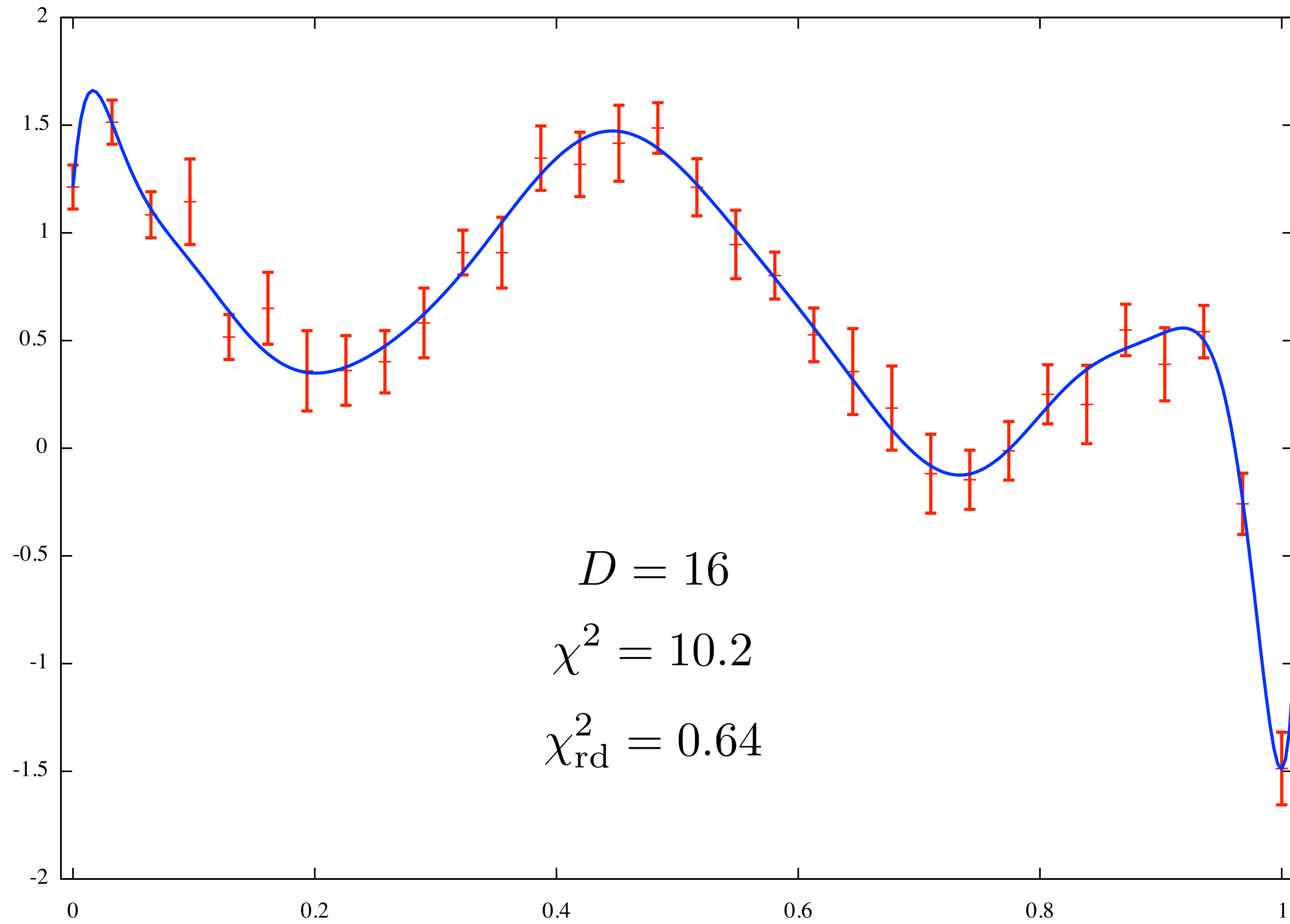


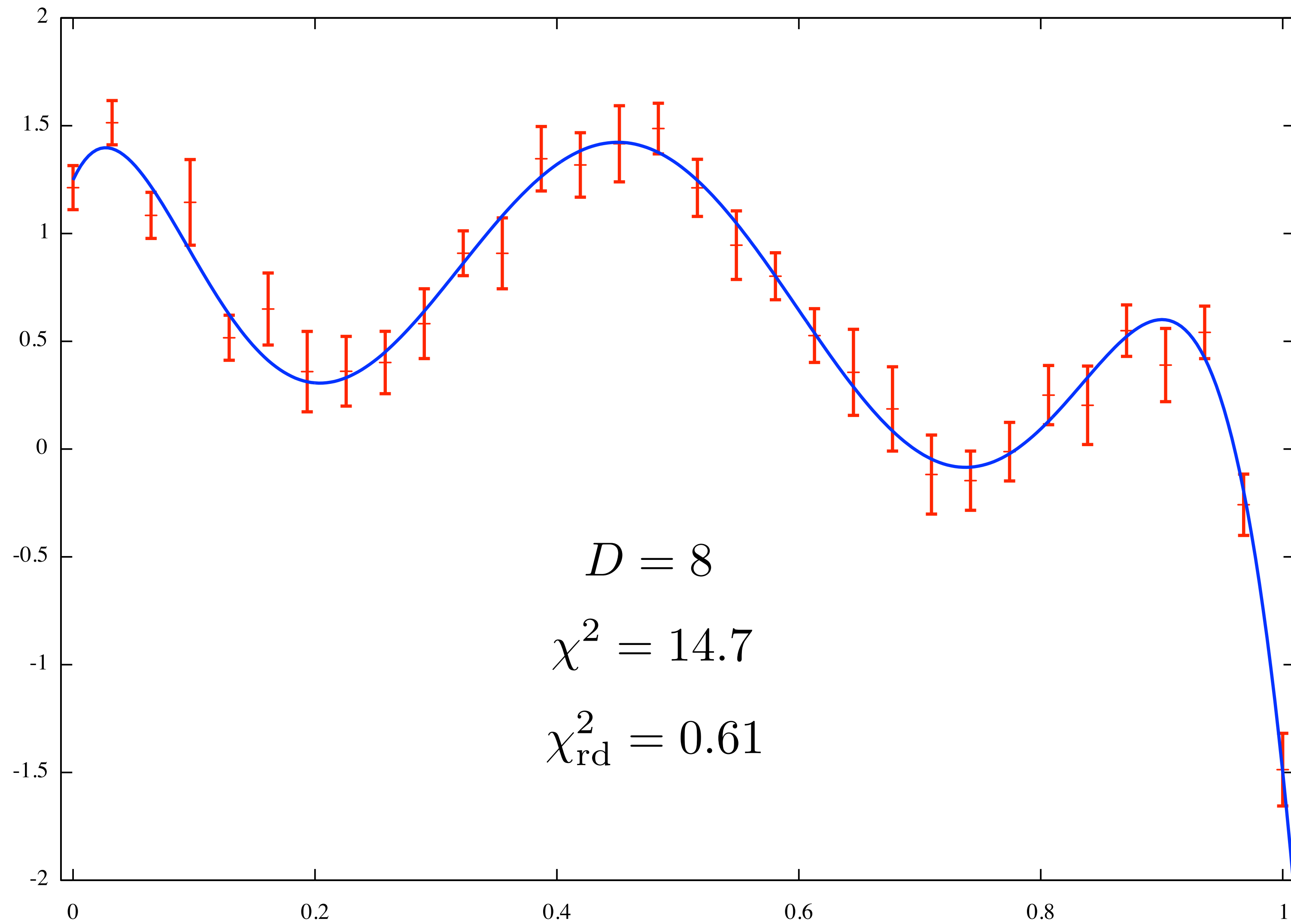




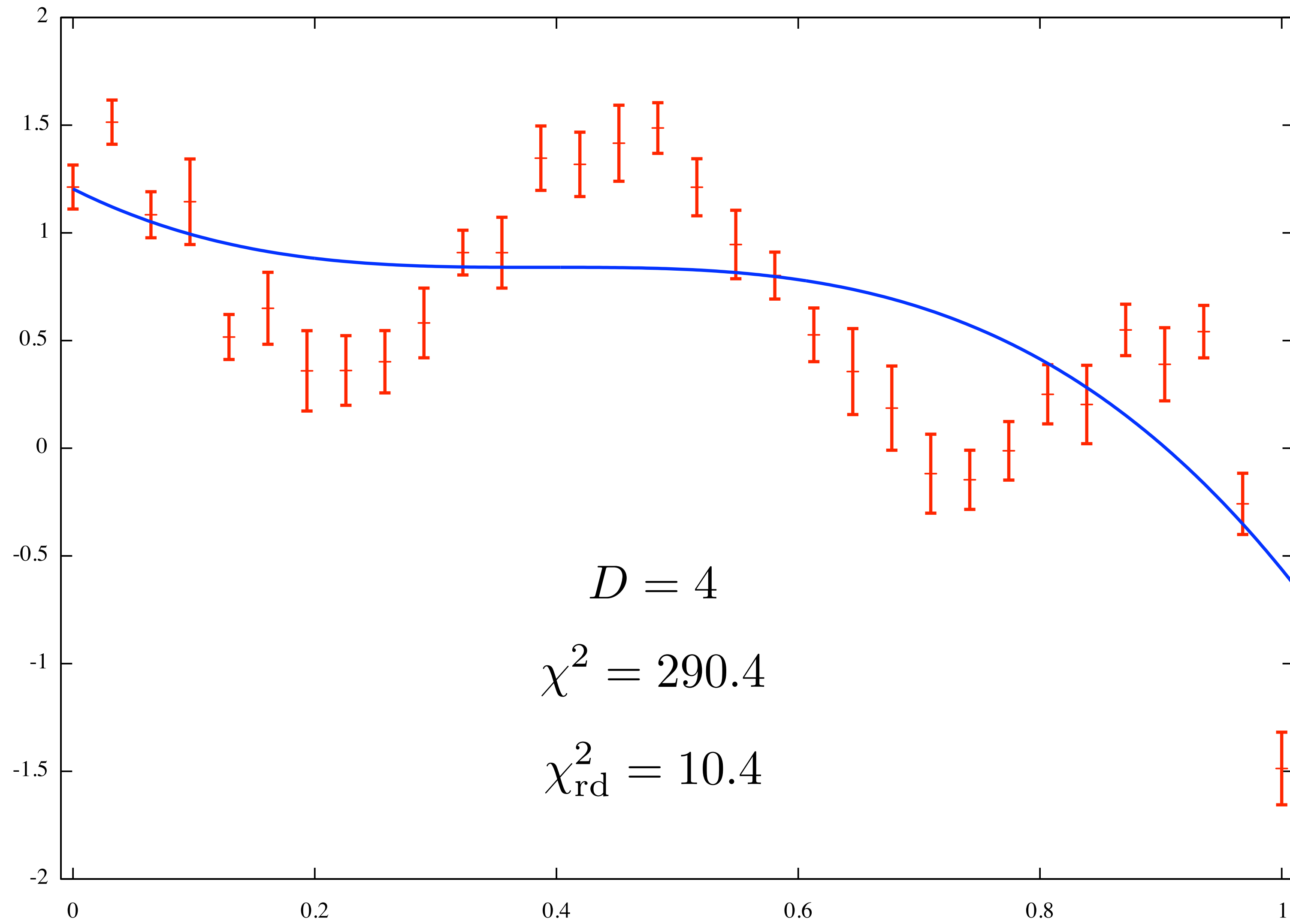




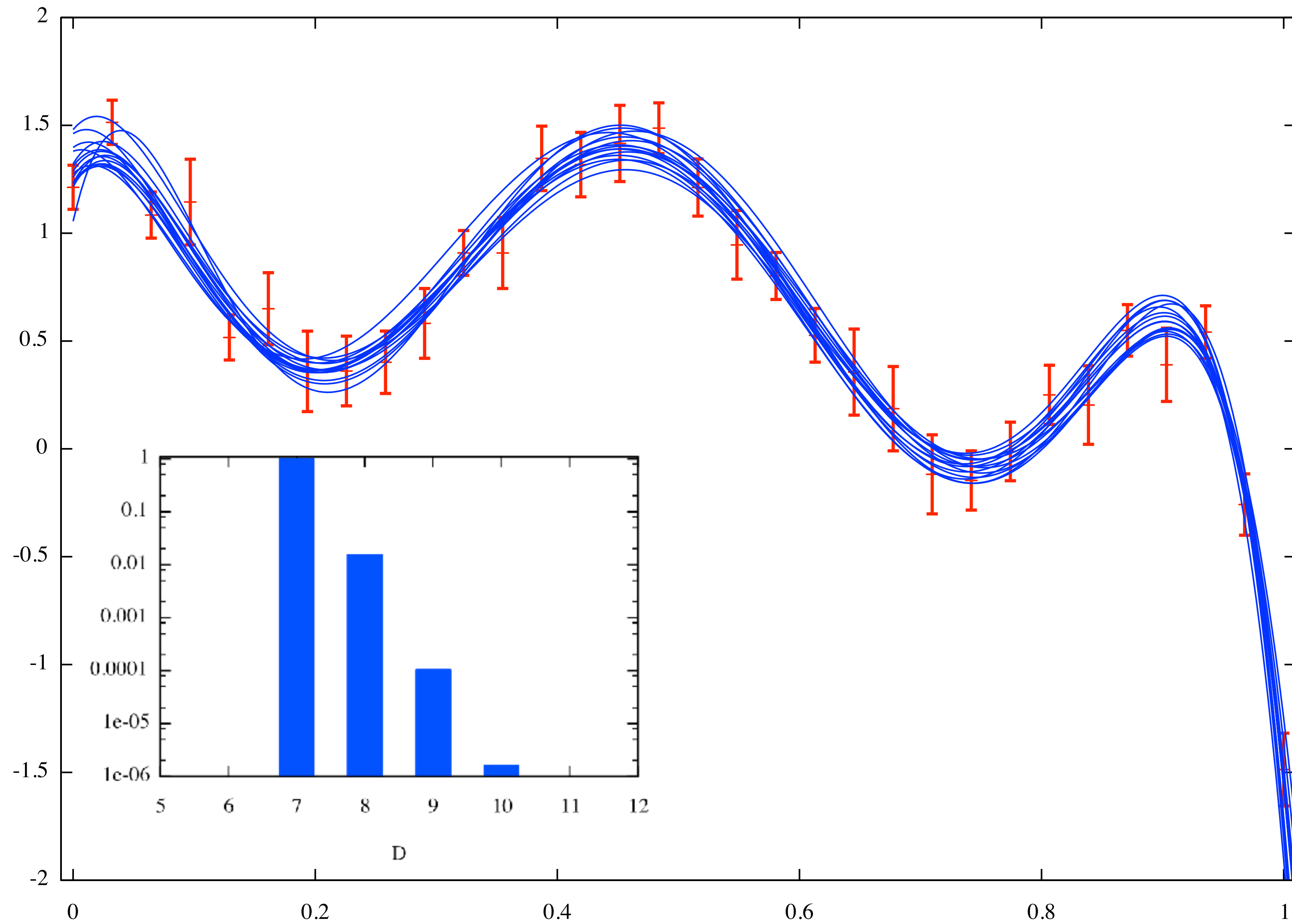








# Trans-dimensional Markov Chain Monte Carlo



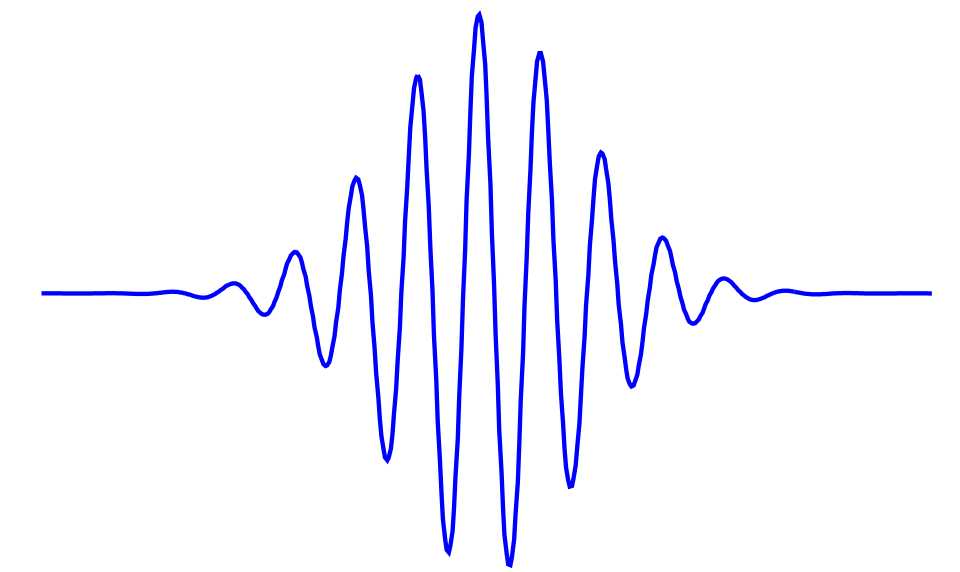


# BayesWave

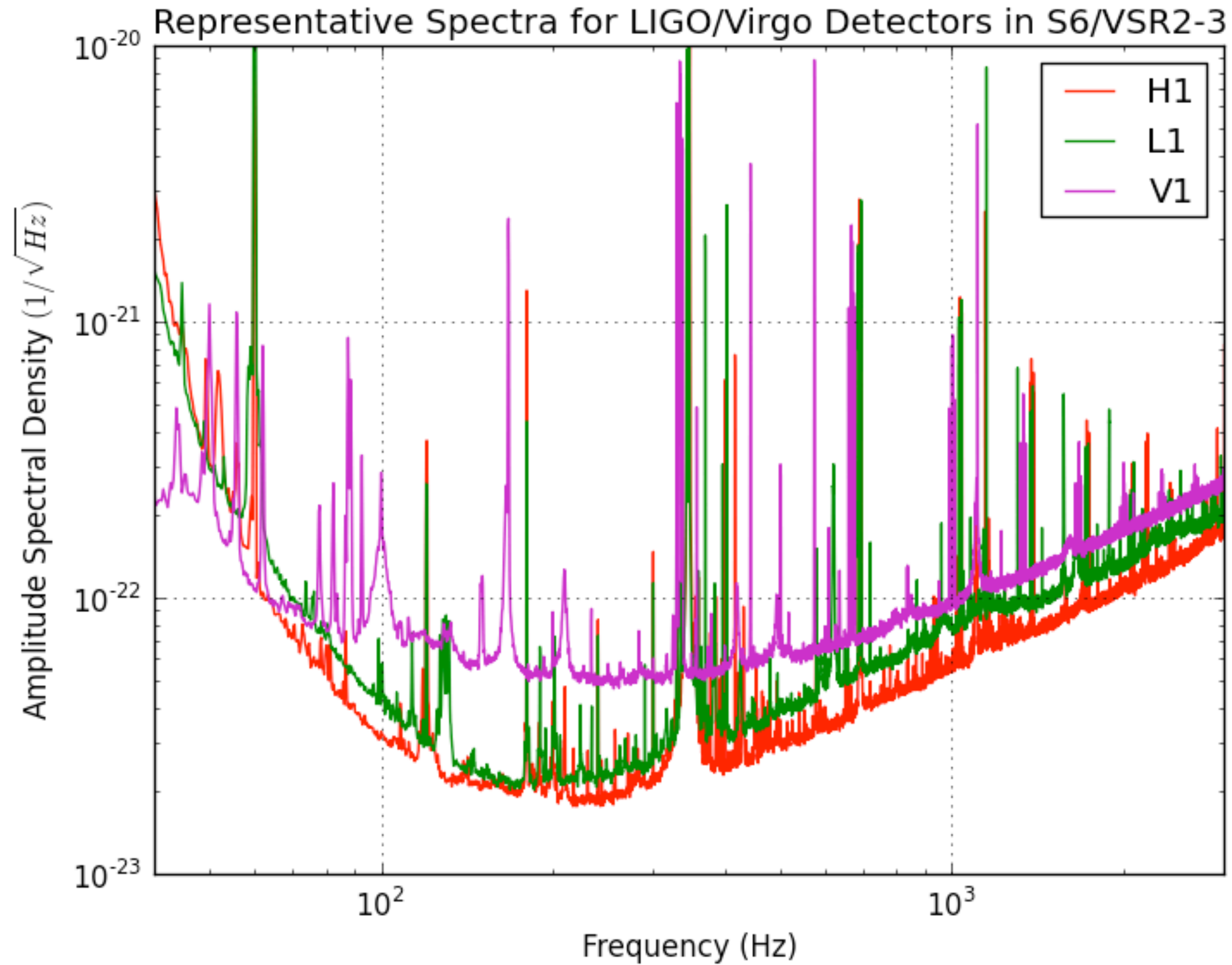
Cornish & Littenberg 2015

Ellis & Cornish 2016

- **Bayesian** model selection
  - Three part model (signal, glitches, gaussian noise)
  - Trans-dimensional Markov Chain Monte Carlo
- **Wavelet** decomposition
  - Glitch & GW modeled by wavelets
  - Number, amplitude, quality and TF location of wavelets varies

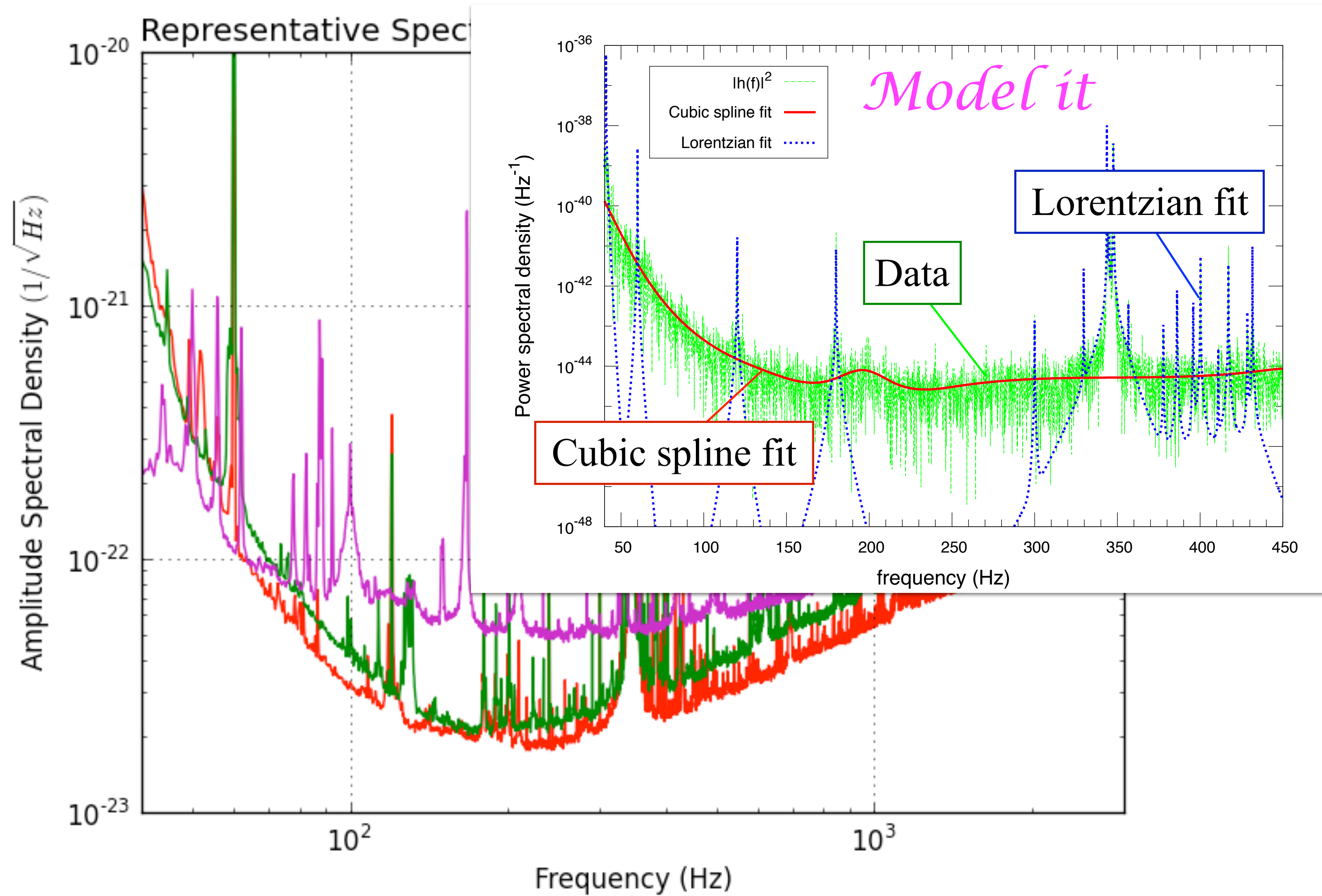


# Lines and a drifting noise floor



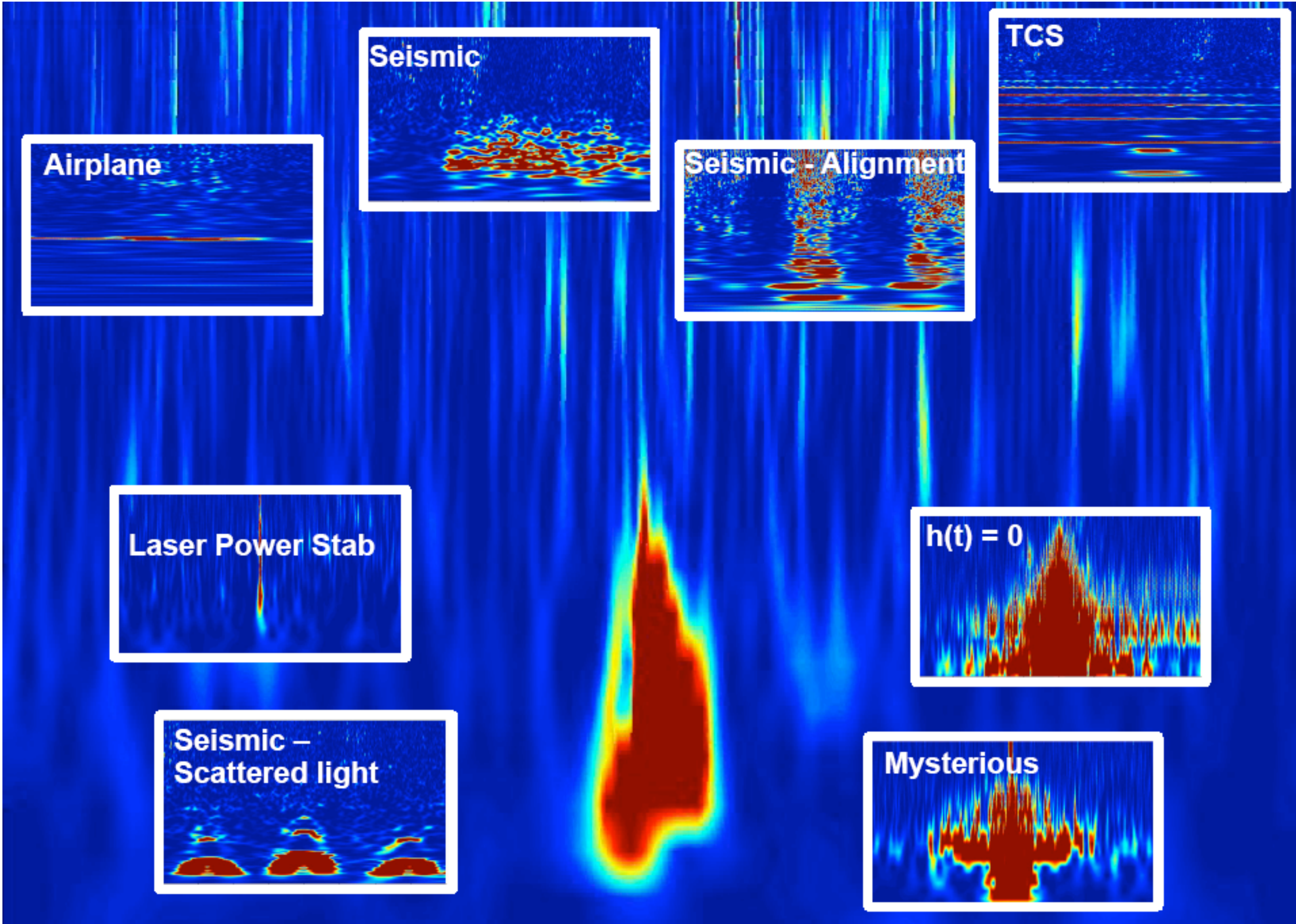


# Lines and a drifting noise floor



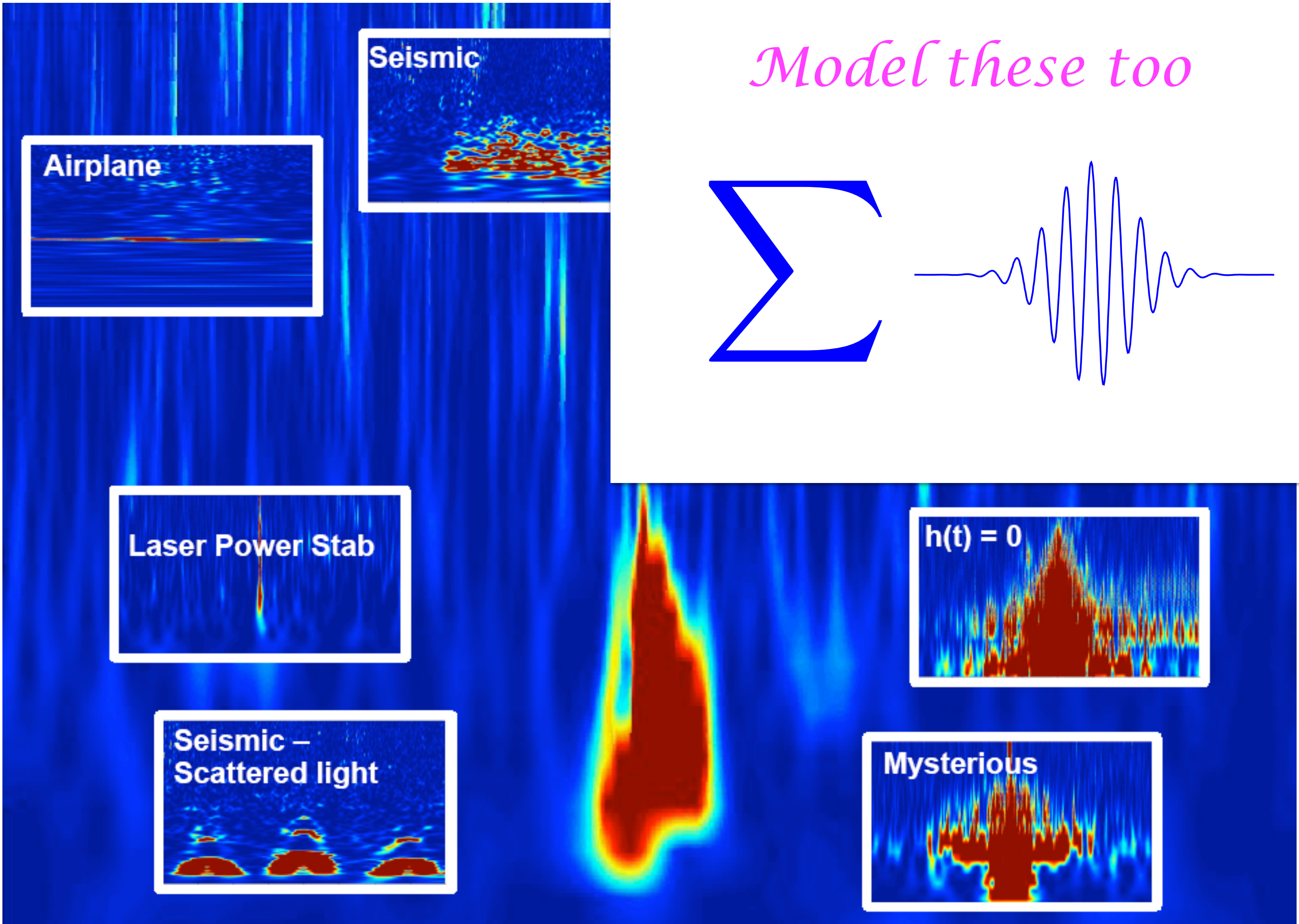


# Glitches

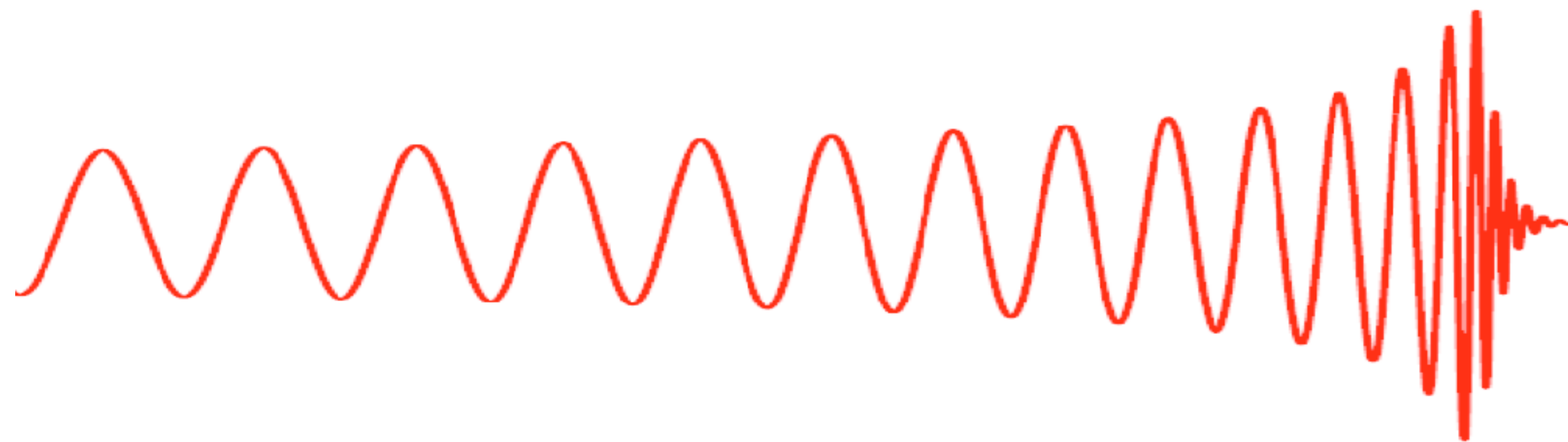




# Glitches



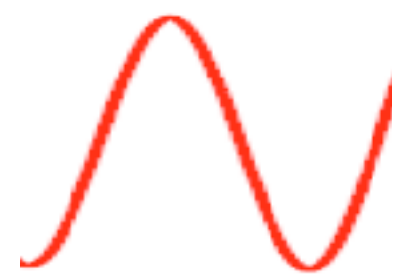
# Gravitational Waves



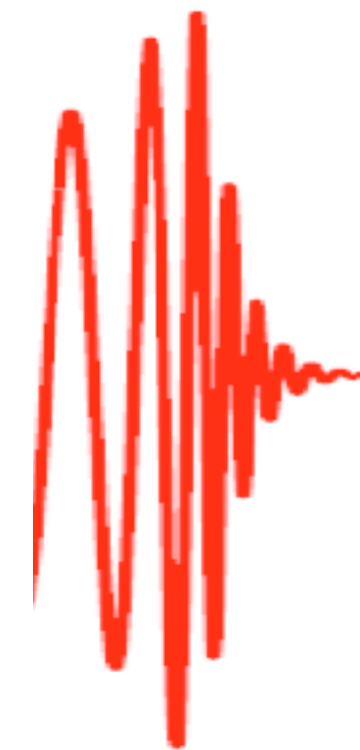
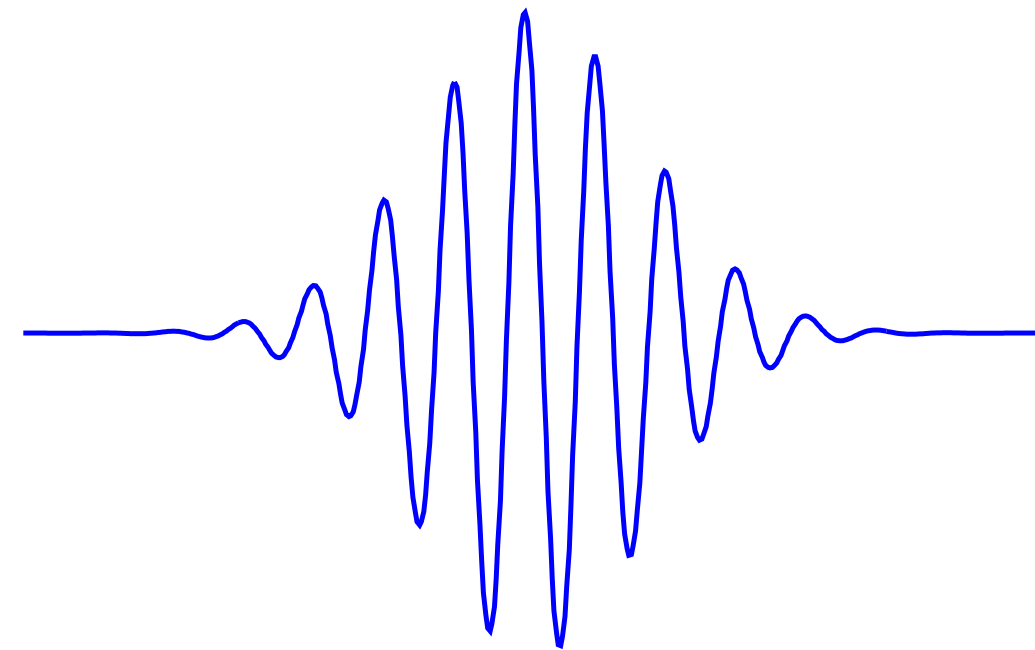


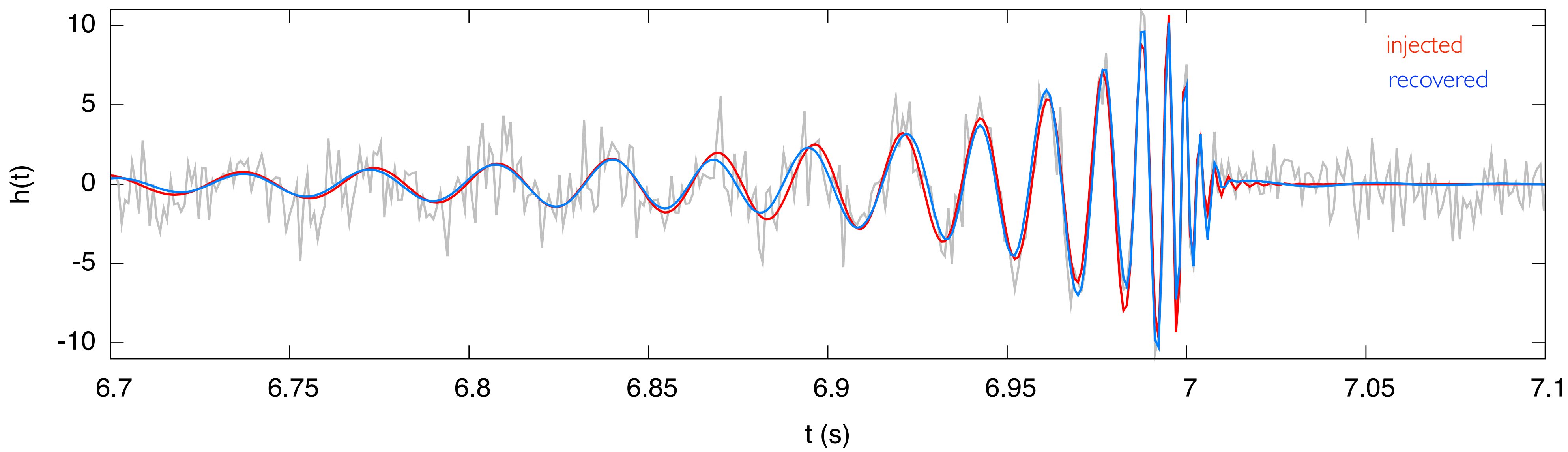
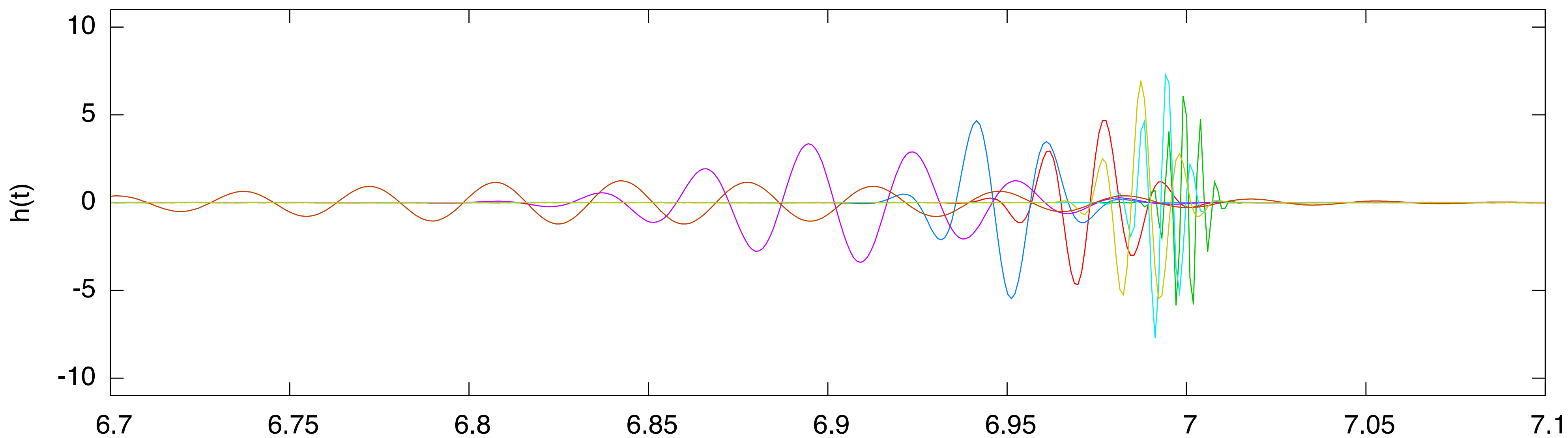
# Gravitational Waves

*and model these*



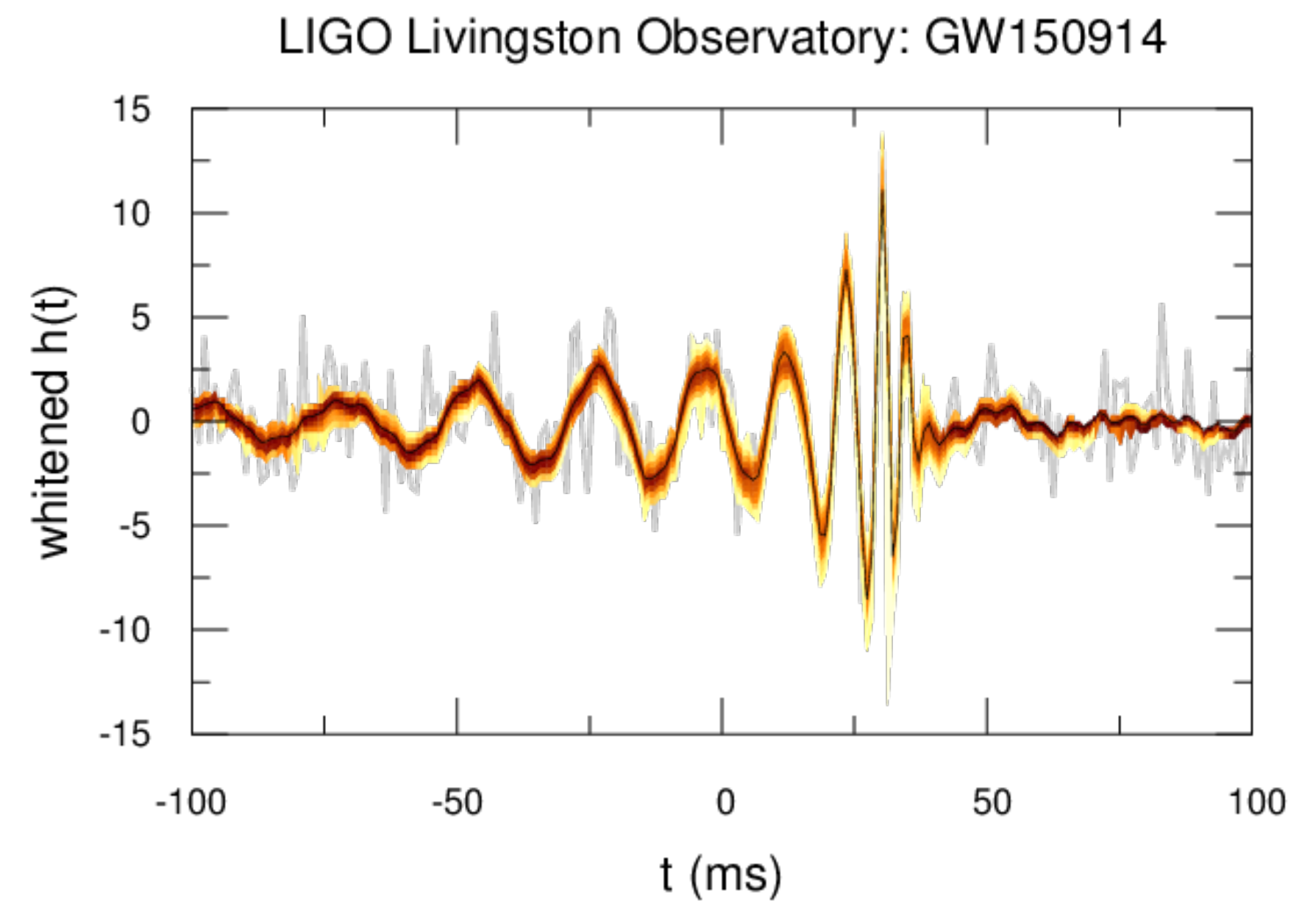
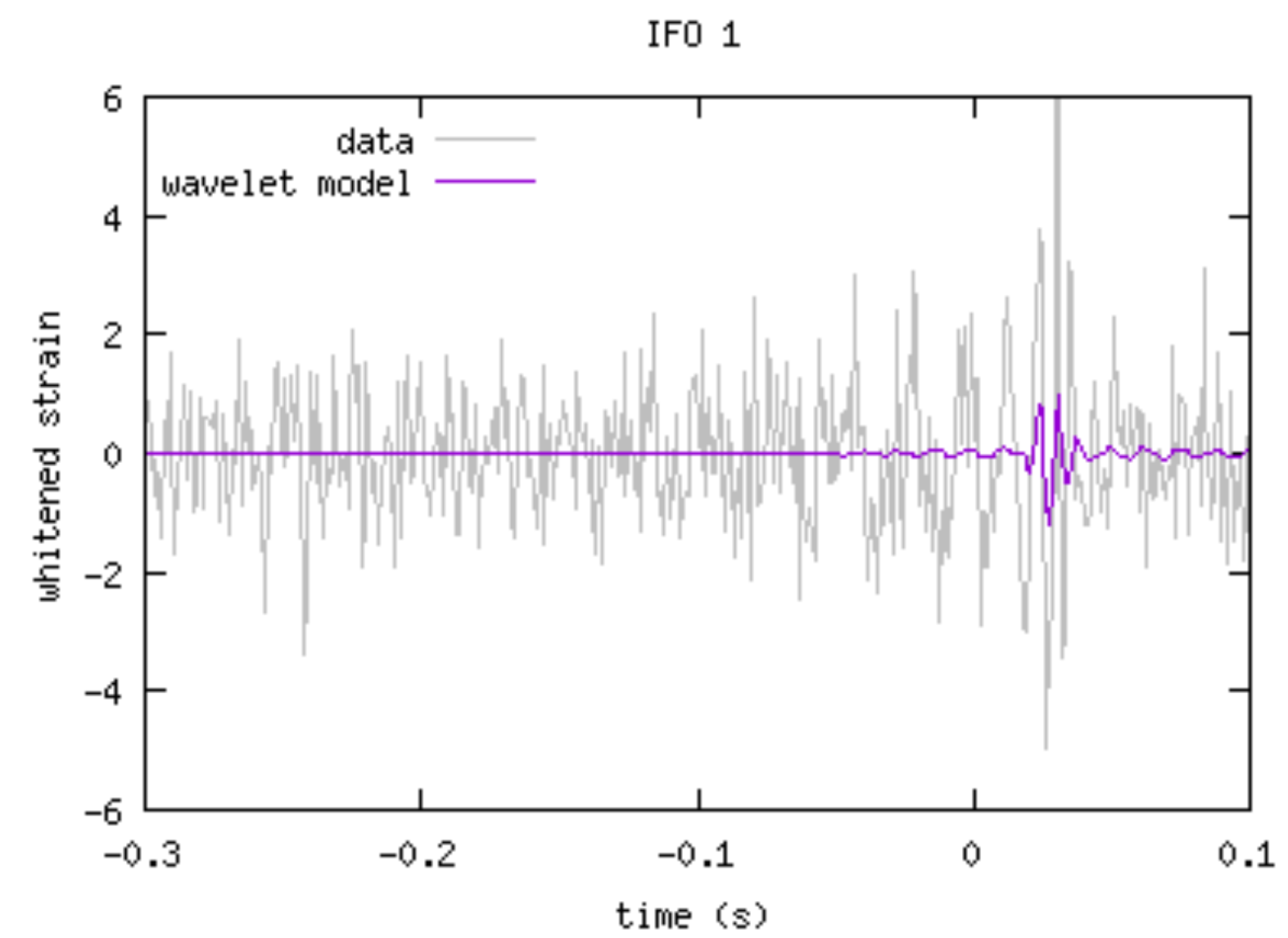
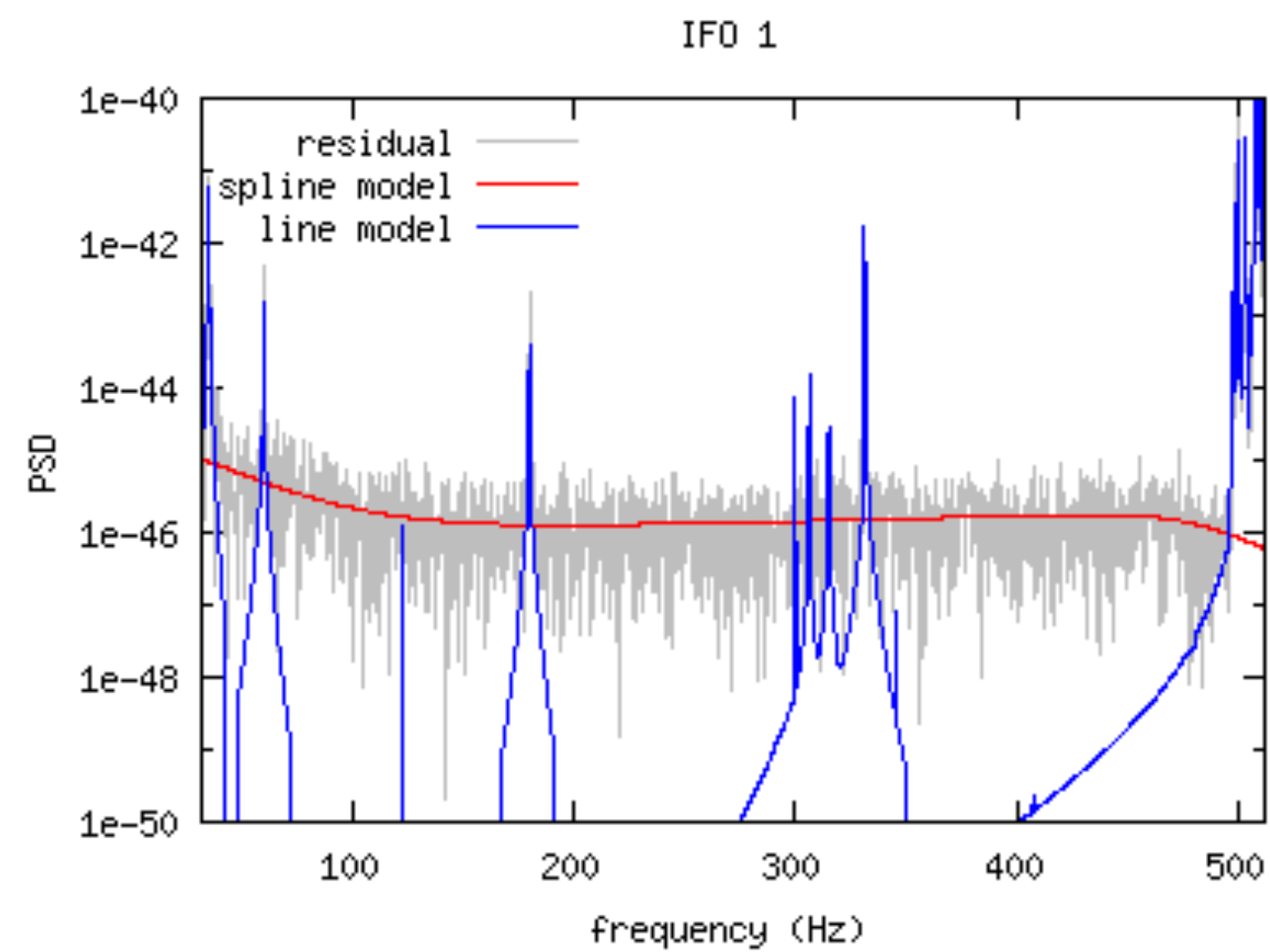
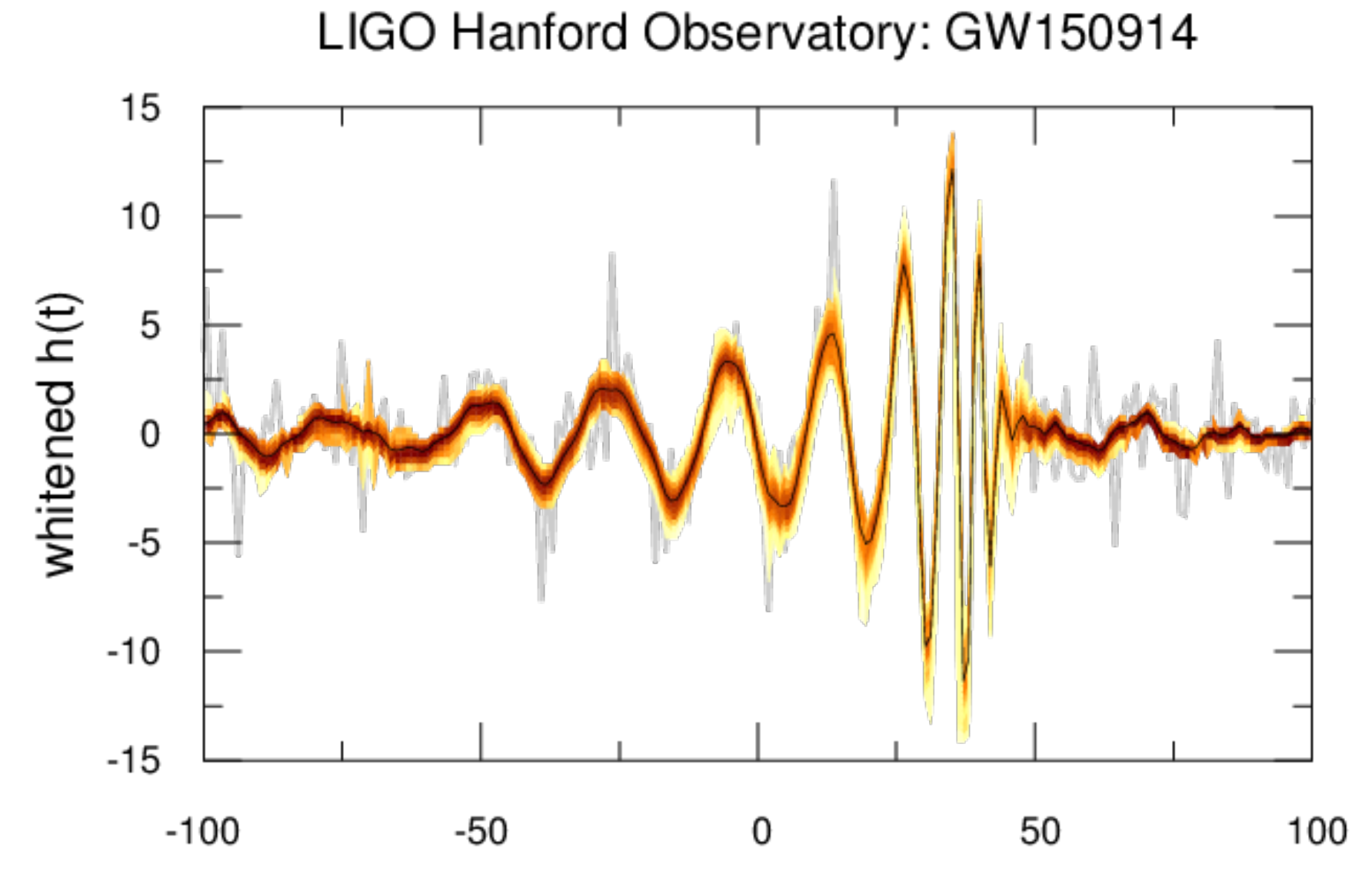
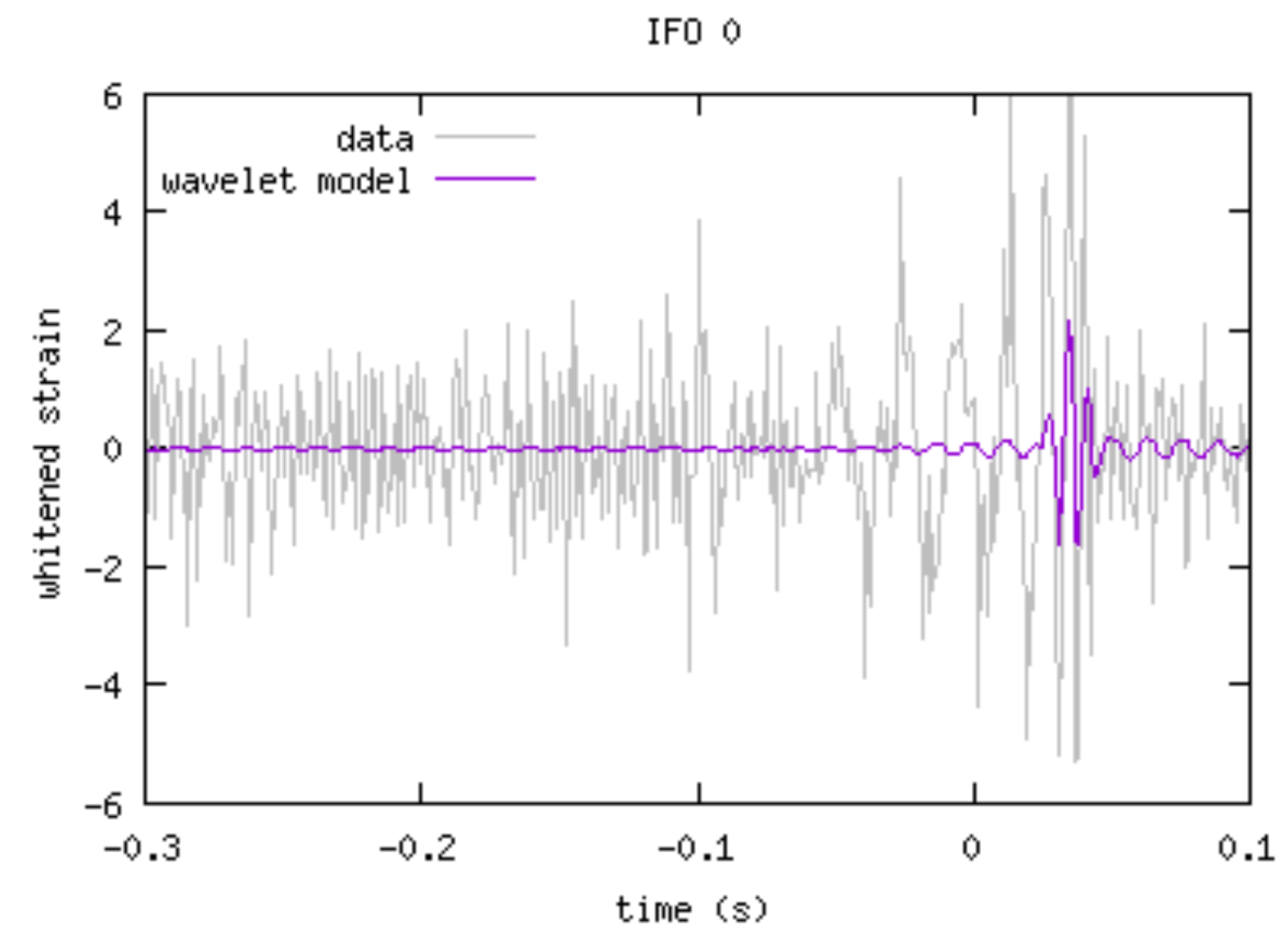
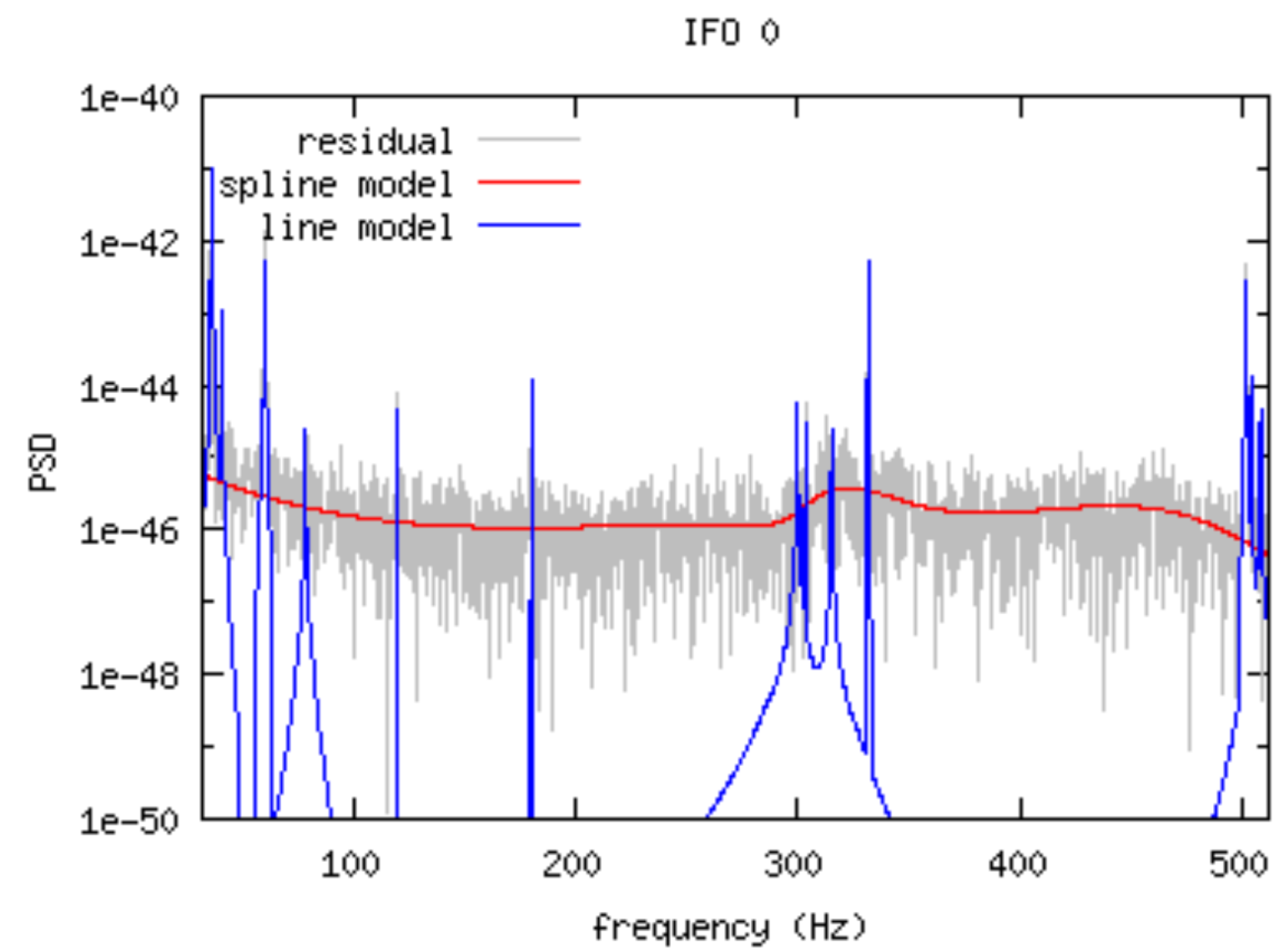
$\Sigma$



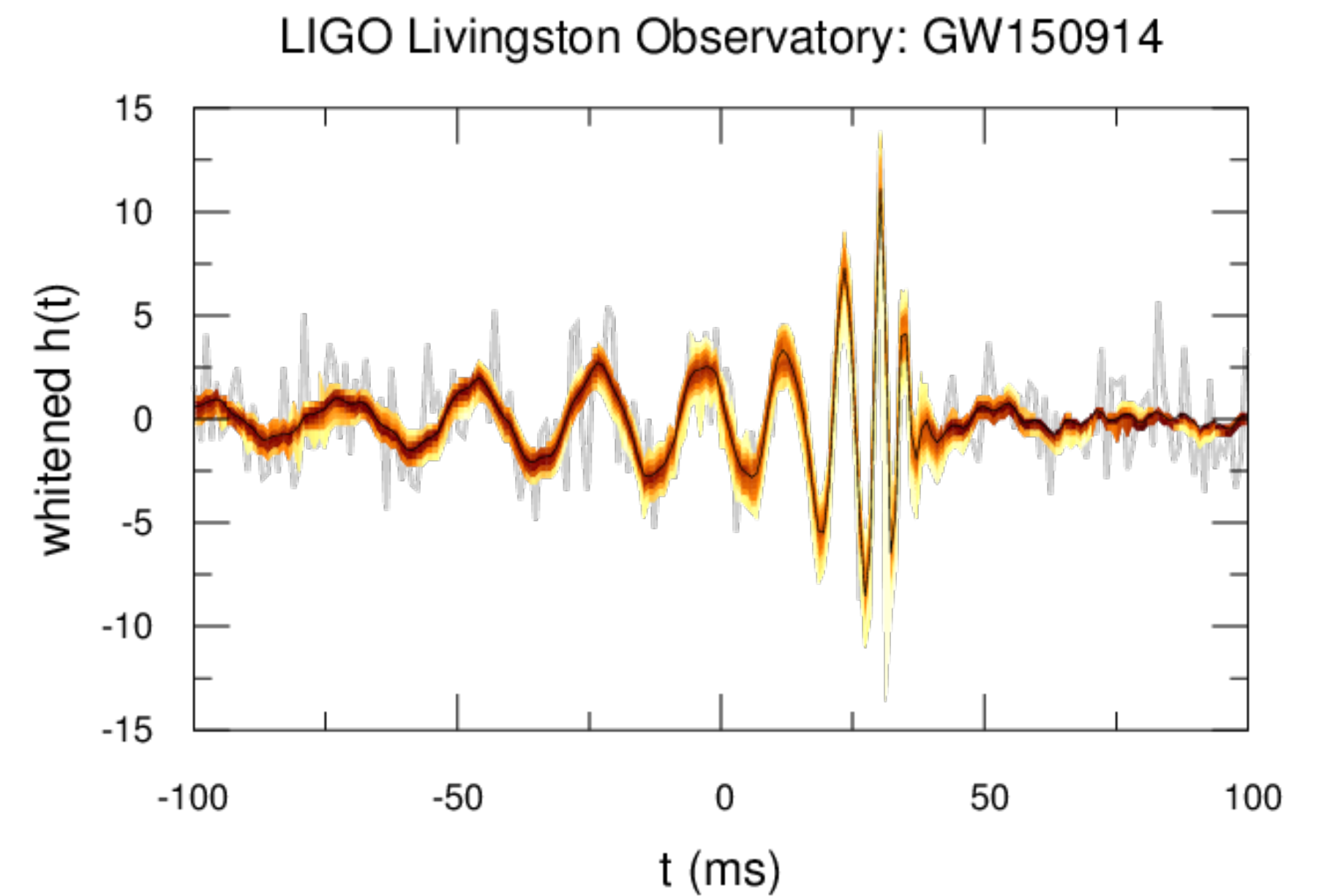
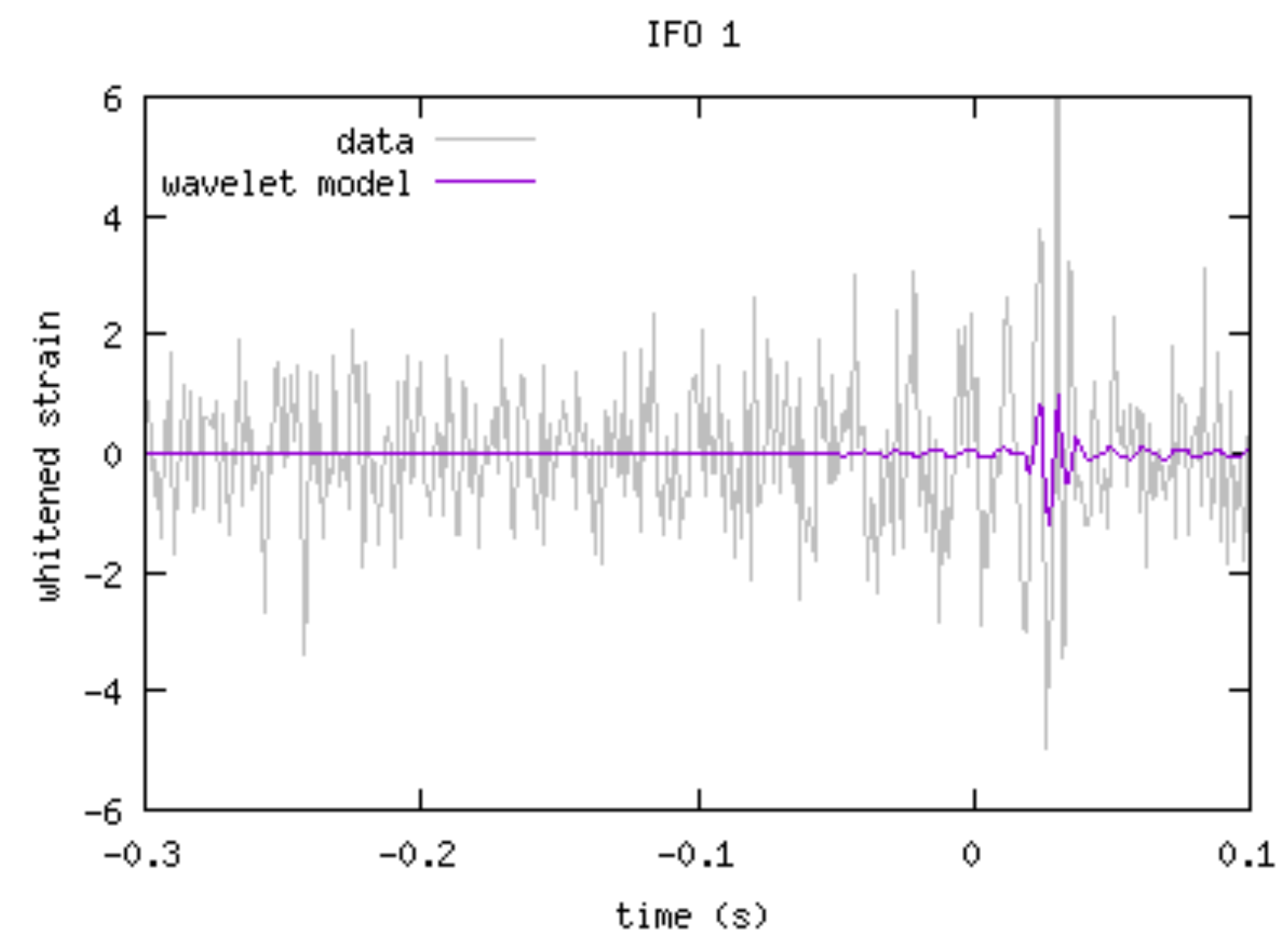
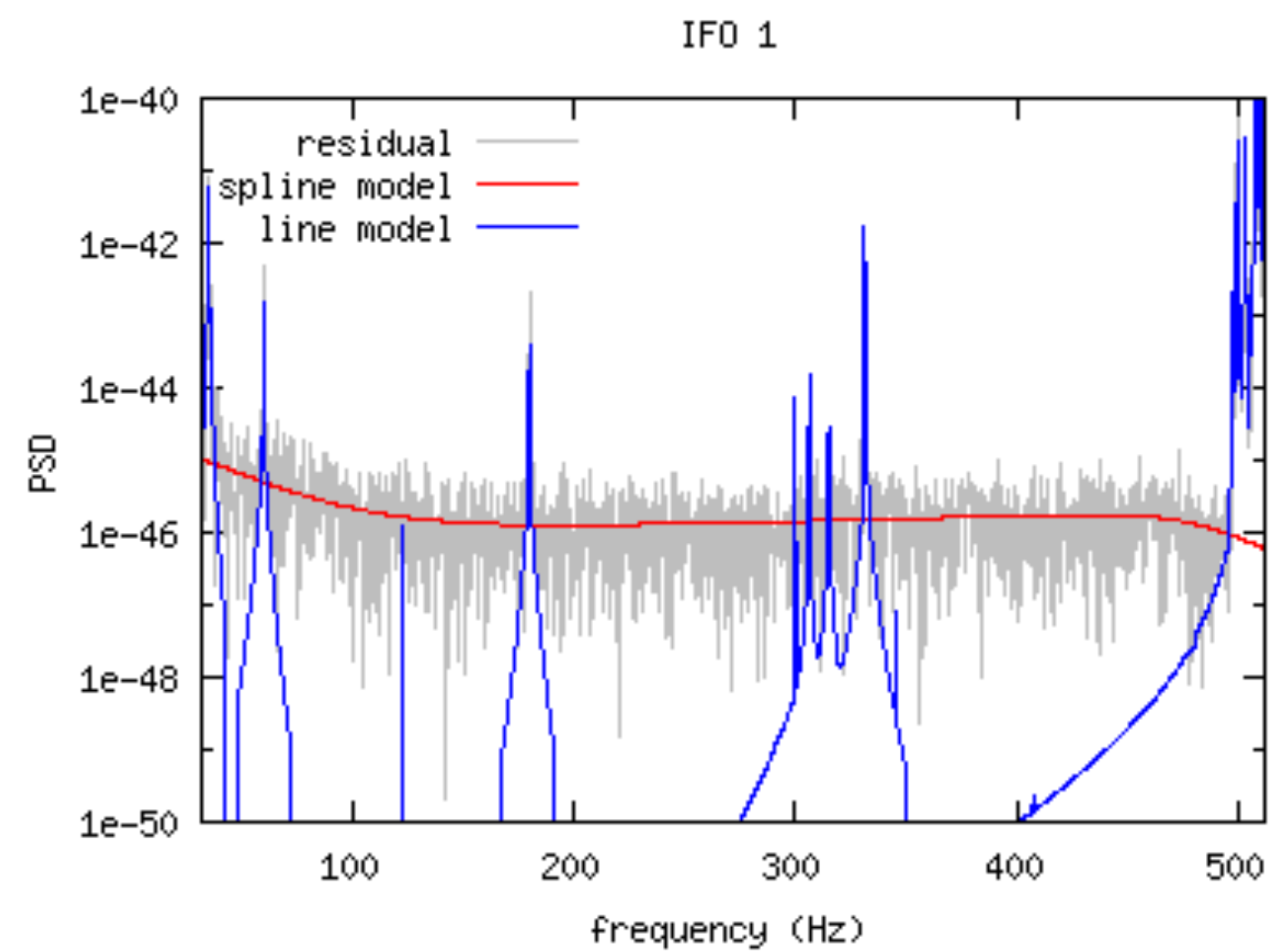
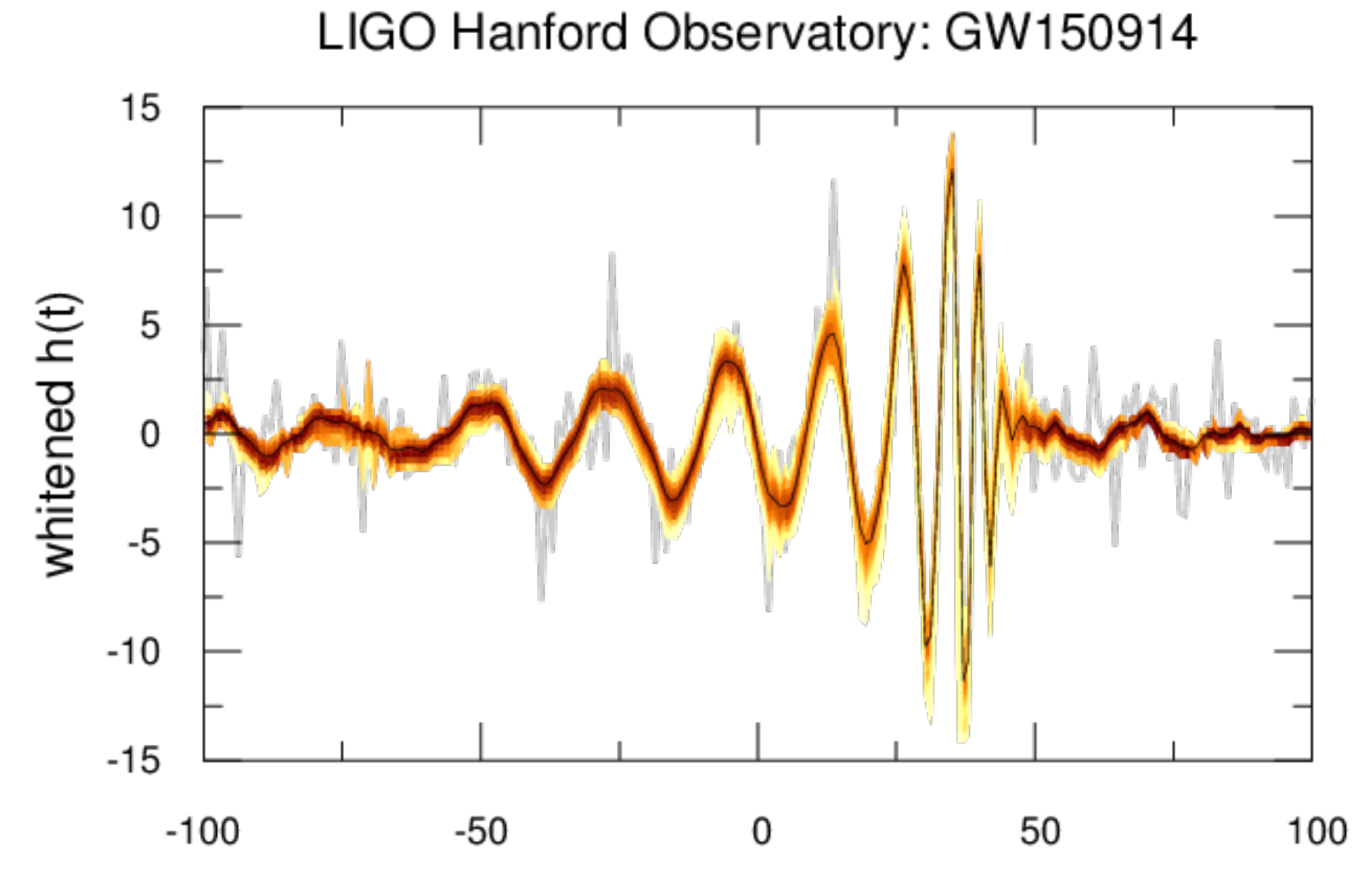
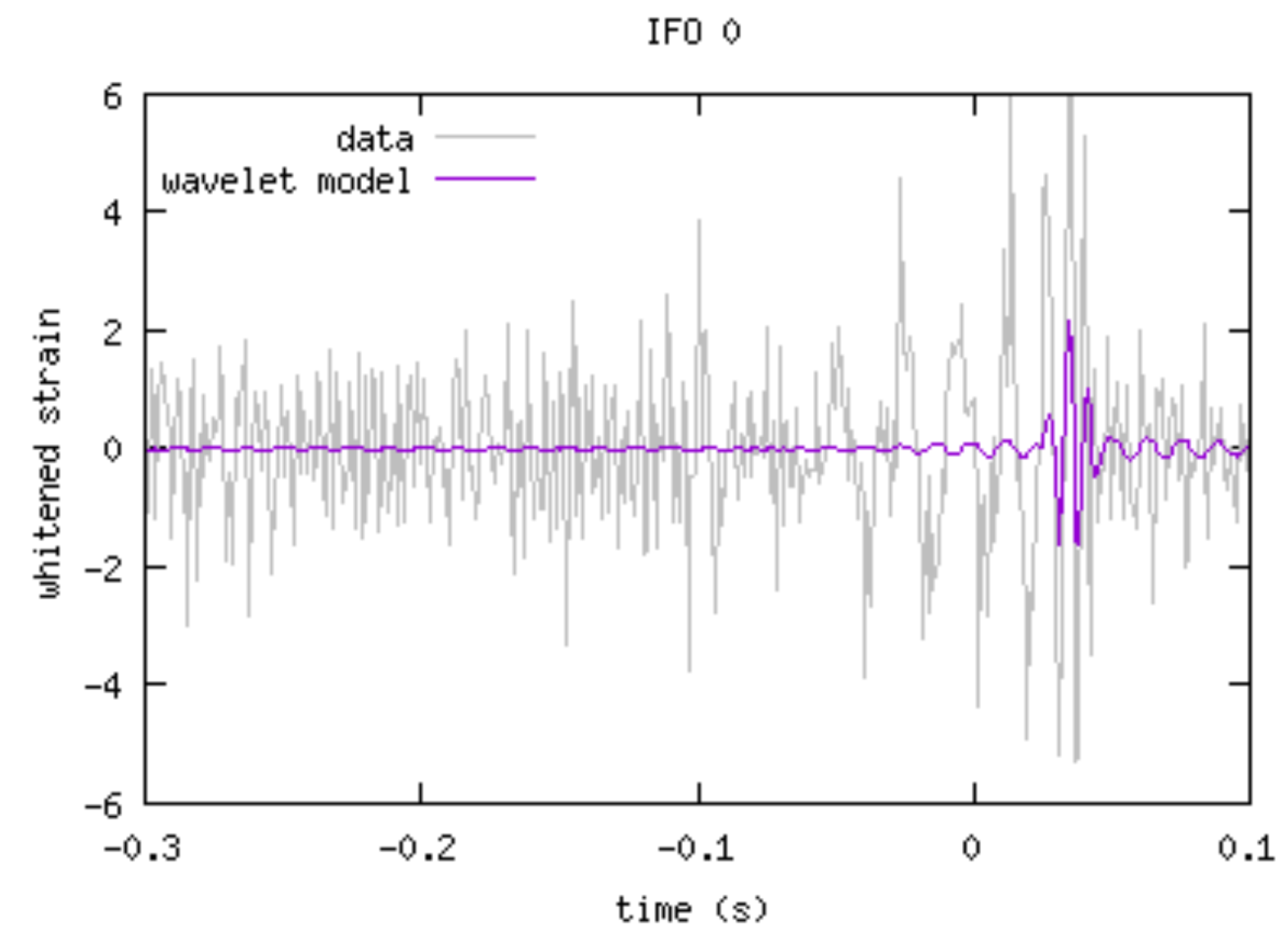
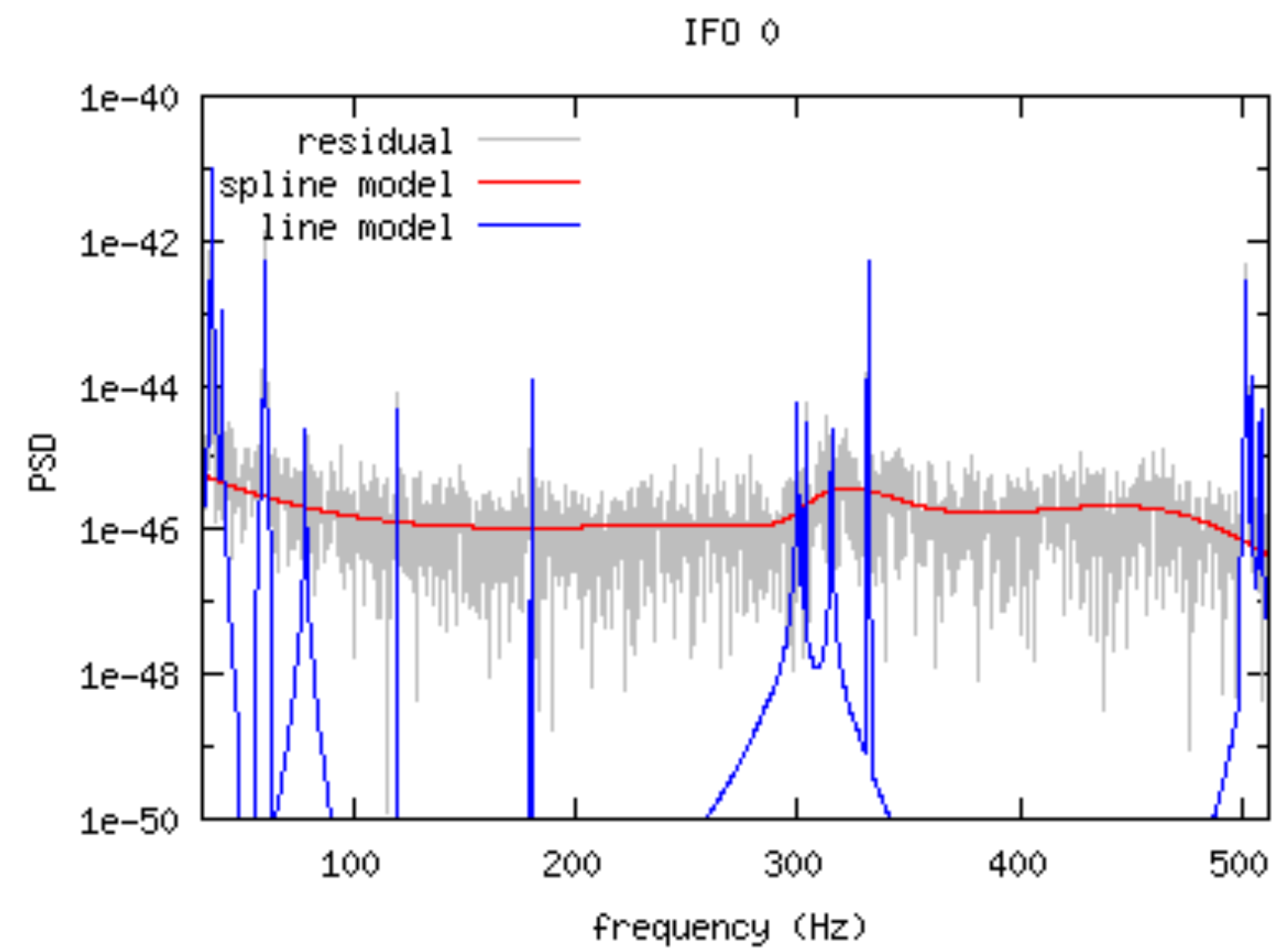




# Reconstructing GW150914 with wavelets

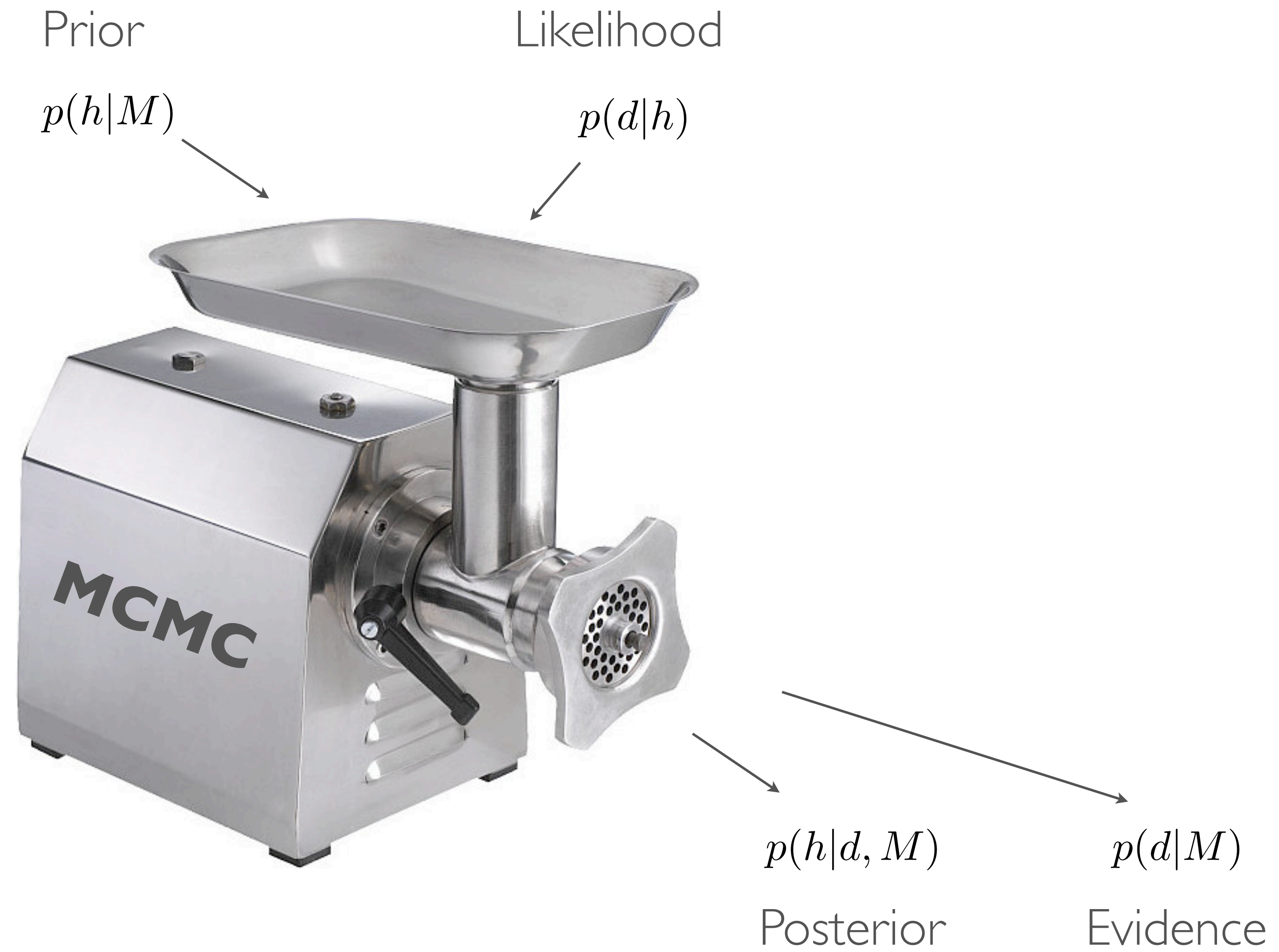


# Reconstructing GW150914 with wavelets

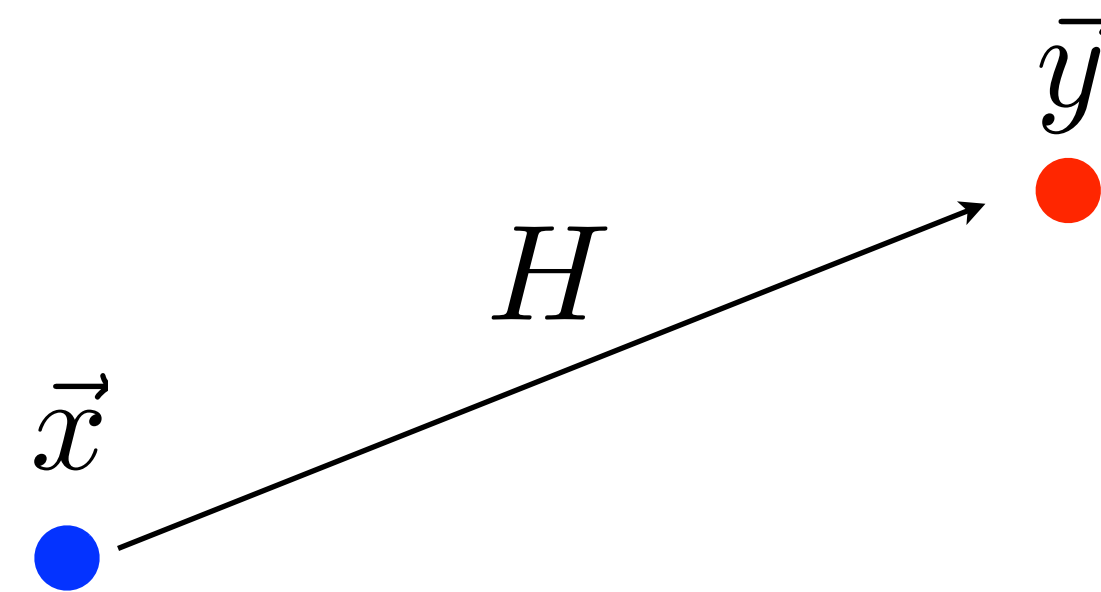




# Bayesian Inference



# Markov Chain Monte Carlo



Yields PDF  $p(\vec{x}|d)$  for parameters  $\vec{x}$  given data  $d$

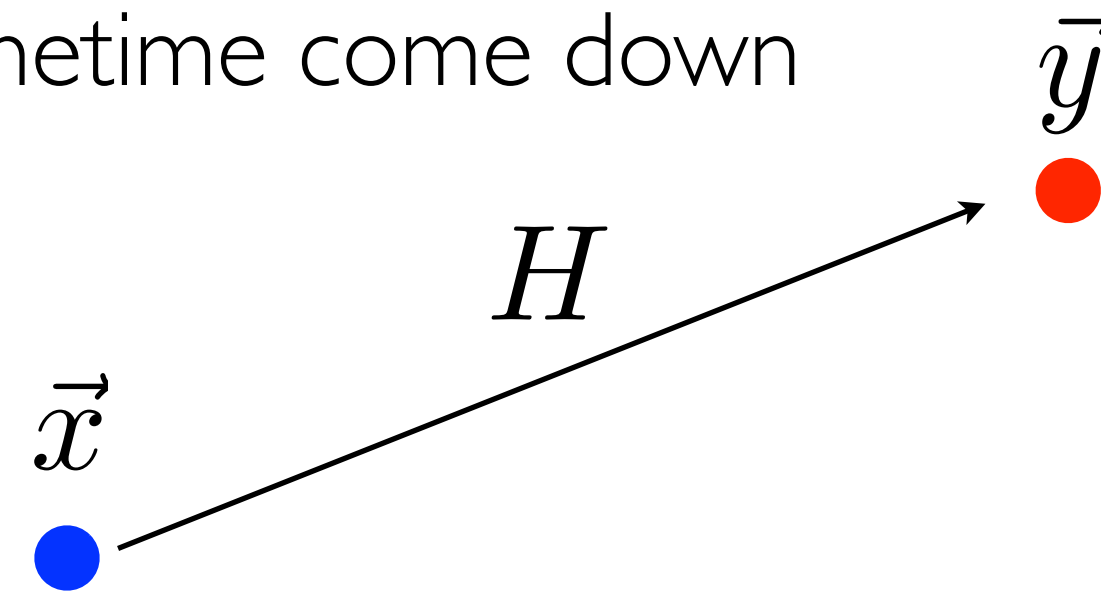
$$H = \min \left( 1, \frac{p(\bar{y})p(d|\bar{y})q(\vec{x}|\bar{y})}{p(\vec{x})p(d|\vec{x})q(\bar{y}|\vec{x})} \right)$$

Transition Probability  
(Metropolis-Hastings)



# Markov Chain Monte Carlo

Always go up,  
Sometime come down



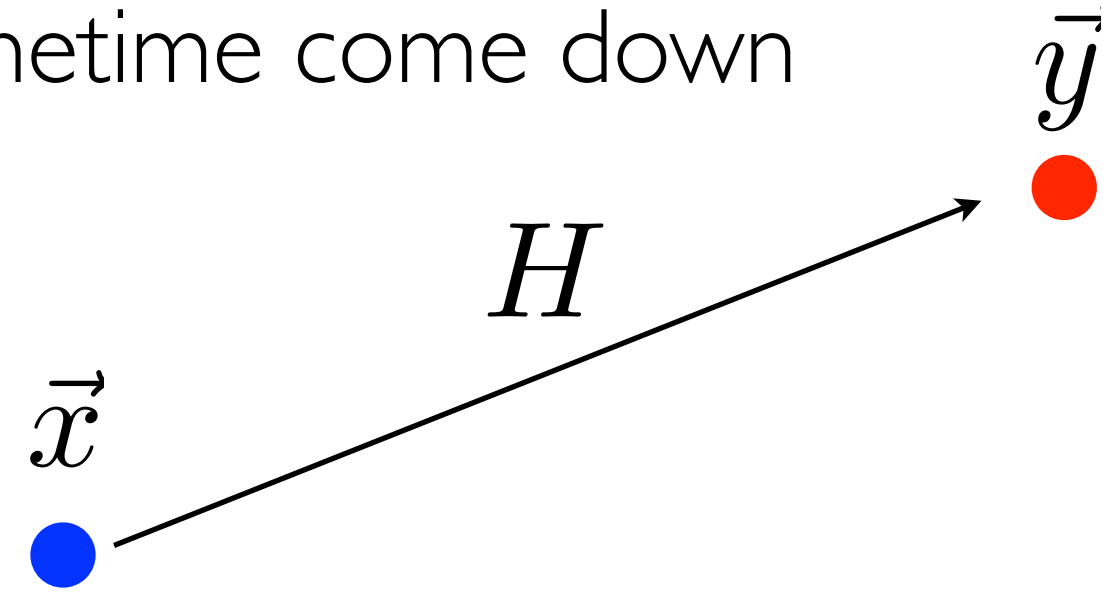
Yields PDF  $p(\vec{x}|d)$  for parameters  $\vec{x}$  given data  $d$

$$H = \min \left( 1, \frac{p(\bar{y})p(d|\bar{y})q(\vec{x}|\bar{y})}{p(\vec{x})p(d|\vec{x})q(\bar{y}|\vec{x})} \right)$$

Transition Probability  
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# Markov Chain Monte Carlo

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Yields PDF  $p(\vec{x}|d)$  for parameters  $\vec{x}$  given data  $d$

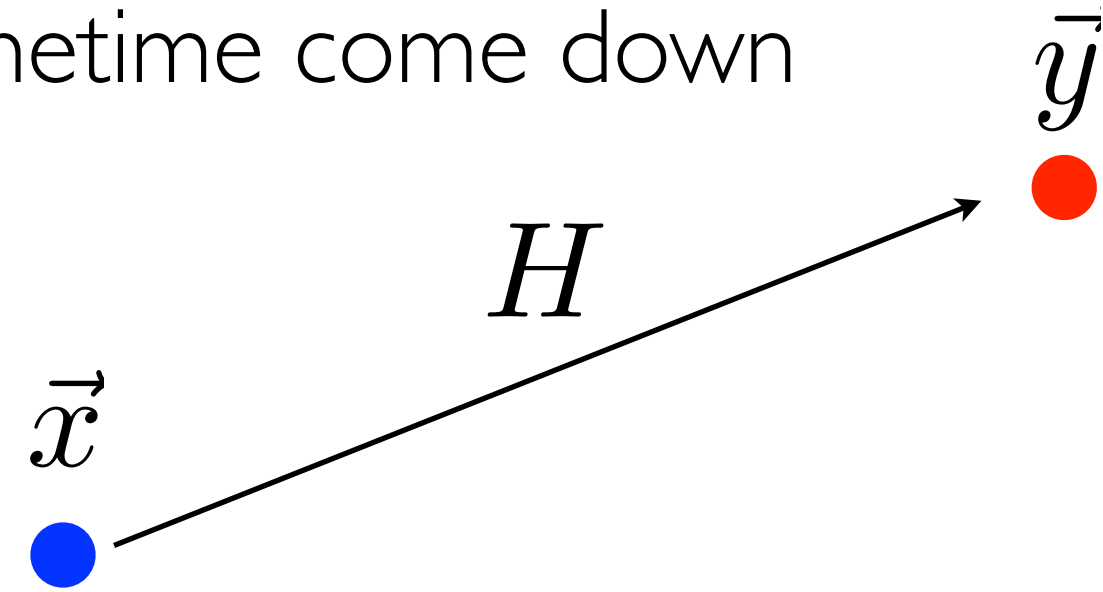
$$H = \min \left( 1, \frac{p(\vec{y})p(d|\vec{y})q(\vec{x}|\vec{y})}{p(\vec{x})p(d|\vec{x})q(\vec{y}|\vec{x})} \right)$$

Prior

Transition Probability  
(Metropolis-Hastings)

# Markov Chain Monte Carlo

Always go up,  
Sometime come down



Yields PDF  $p(\vec{x}|d)$  for parameters  $\vec{x}$  given data  $d$

$$H = \min \left( 1, \frac{p(\bar{y})p(d|\bar{y})q(\vec{x}|\bar{y})}{p(\vec{x})p(d|\vec{x})q(\bar{y}|\vec{x})} \right)$$

Prior

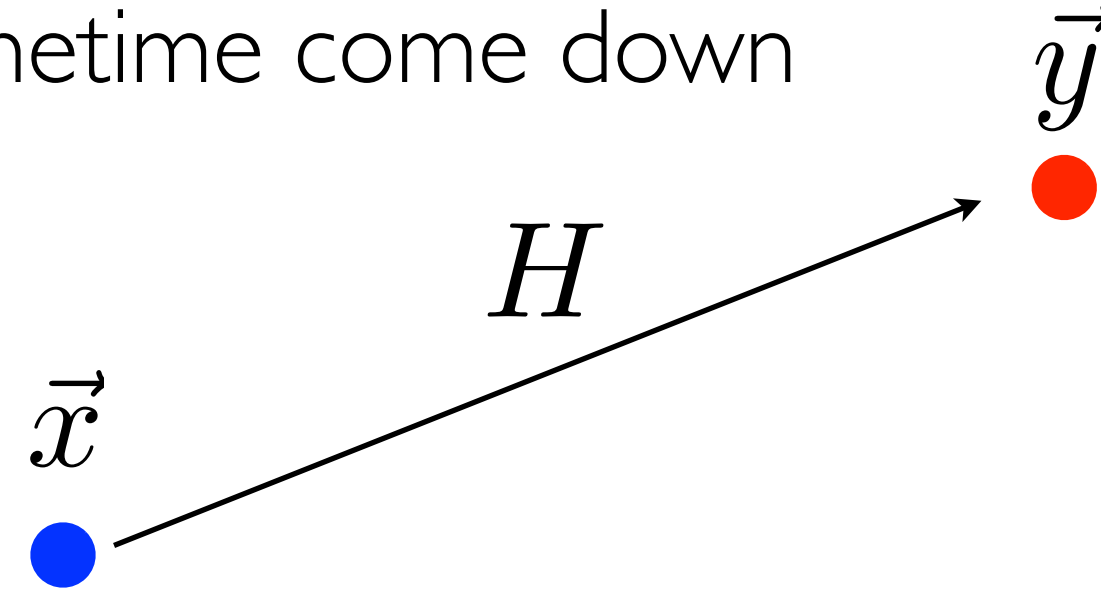
Likelihood

Transition Probability  
(Metropolis-Hastings)



# Markov Chain Monte Carlo

Always go up,  
Sometime come down



Yields PDF  $p(\vec{x}|d)$  for parameters  $\vec{x}$  given data  $d$

$$H = \min \left( 1, \frac{p(\bar{y})p(d|\bar{y})q(\vec{x}|\bar{y})}{p(\vec{x})p(d|\vec{x})q(\bar{y}|\vec{x})} \right)$$

Prior

Likelihood

Proposal

Transition Probability  
(Metropolis-Hastings)

# Markov Chain Monte Carlo

The choice of jump proposal  $q(\vec{y}|\vec{x})$  is key to convergence

Convergence to the target distribution has two facets:

- Burn-in (finding the dominant modes of the posterior)
- Mixing (exploring the dominant modes of the posterior)

The perfect proposal distribution is the posterior distribution itself,  $q(\vec{y}|\vec{x}) = p(\vec{y}|d)$ , since then

$$\begin{aligned} H &= \min \left( 1, \frac{p(\vec{y})p(d|\vec{y})p(\vec{x}|d)}{p(\vec{x})p(d|\vec{x})p(\vec{y}|d)} \right) \\ &= 1 \end{aligned}$$

But if we knew the posterior distribution in advance there would be no need for the MCMC procedure! Instead we seek ways to approximate the posterior.

# A MCMC Recipe

## Ingredients:

Local posterior approximation

Global likelihood maps

Differential evolution proposals

Parallel tempering

## Directions:

Mix all the proposals together. Check consistency by recovering the prior and diagonal PP plots. Results are ready when distributions are stationary.



# Proposal Distributions

## Local posterior approximation

Quadratic approximation to the posterior using the augmented Fisher Information Matrix

$$q(\vec{y}|\vec{x}) = \frac{1}{\sqrt{\det(2\pi\mathbf{K}^{-1})}} e^{-\frac{1}{2} K_{ij} (x^i - y^i)(x^j - y^j)}$$

Propose jumps along eigendirections of  $\mathbf{K}$ , scaled by eigenvalues

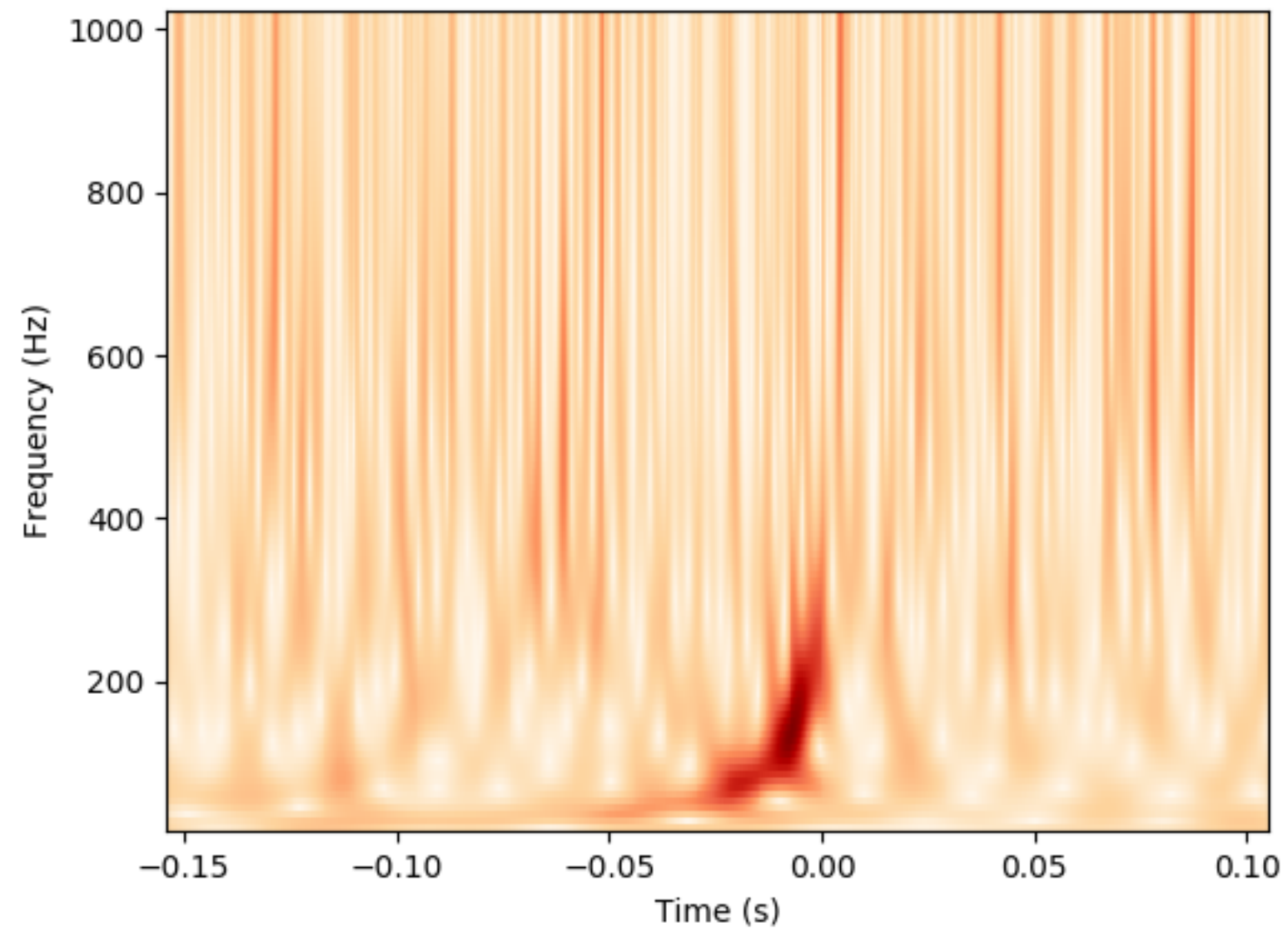
## Global likelihood maps

Use a Non-Markovian Pilot search (hill climbers, simulated annealing, genetic algorithms etc) to crudely map the posterior/likelihood and use this as a proposal distribution for a Markovian follow-up [Littenberg & Cornish, PRD 80, 063007, (2009)]

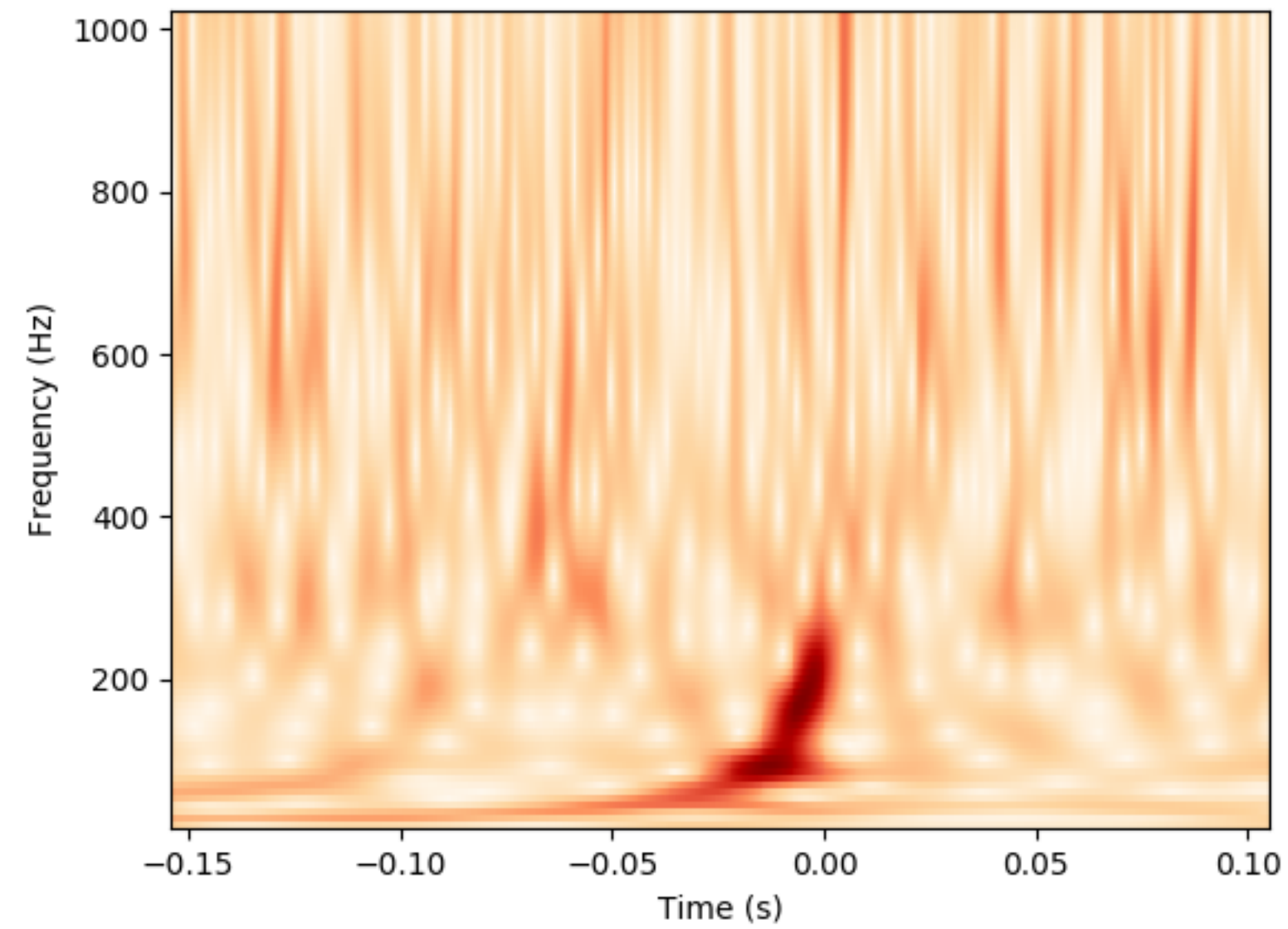
Time-frequency maps, Maximized likelihood maps

# BayesWave Global Map Proposal

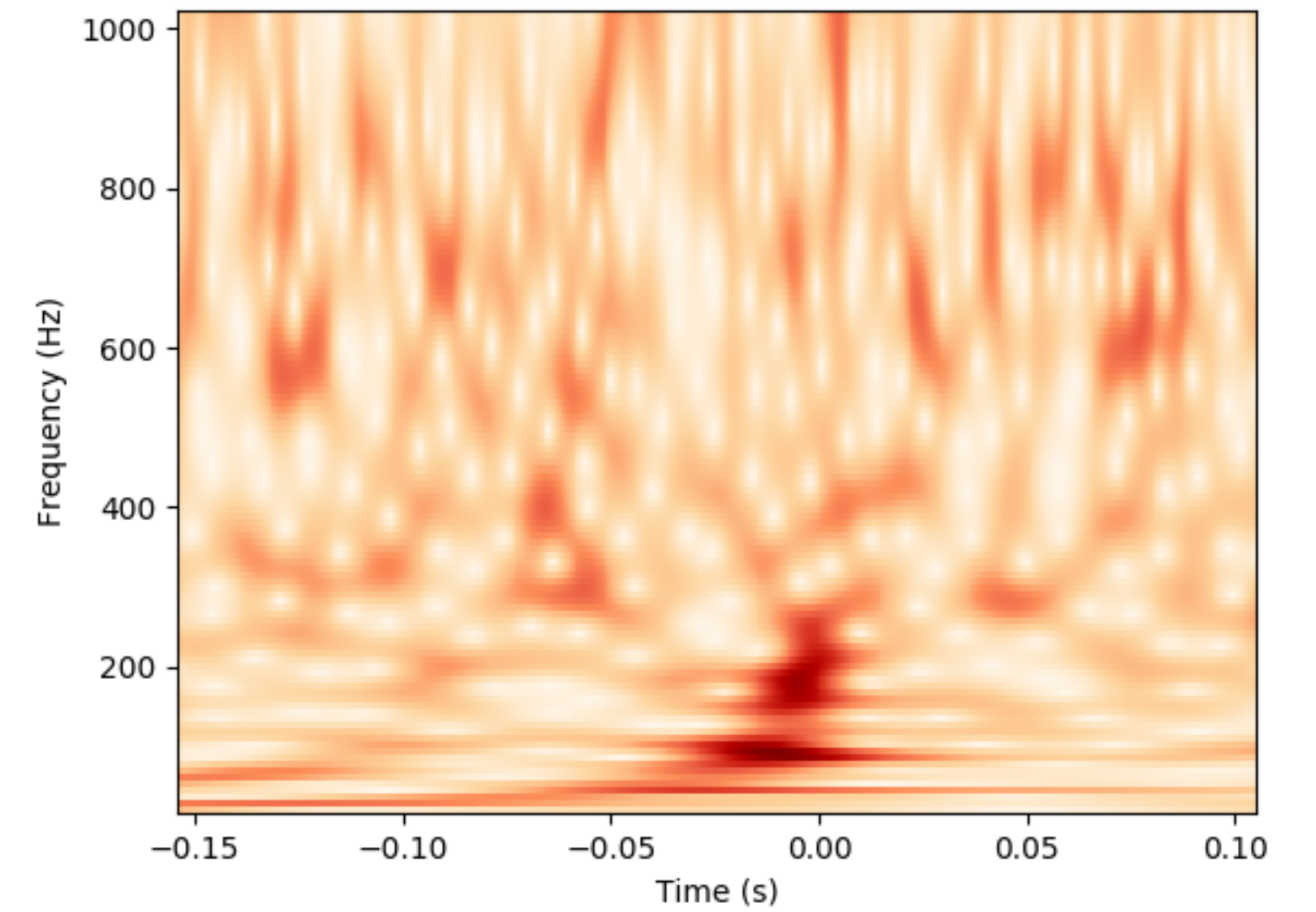
Spectrogram of median data waveform in L1  
, Q=4



Spectrogram of median data waveform in L1  
, Q=8

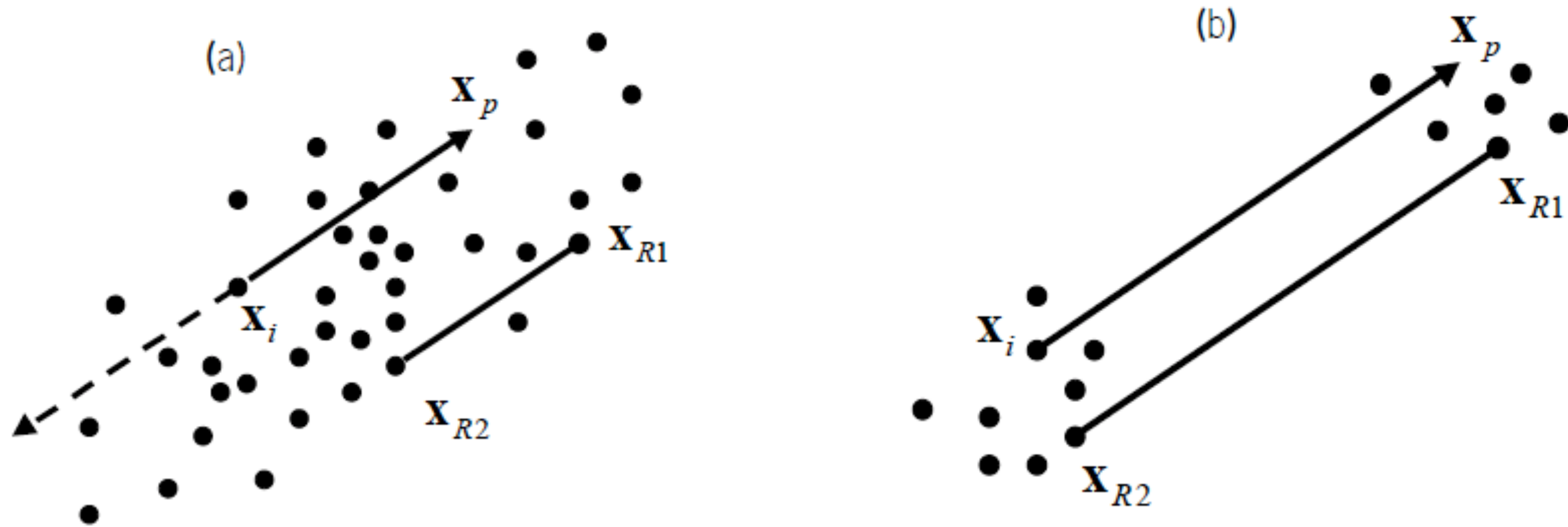


Spectrogram of median data waveform in L1  
, Q=16



# Proposal Distributions

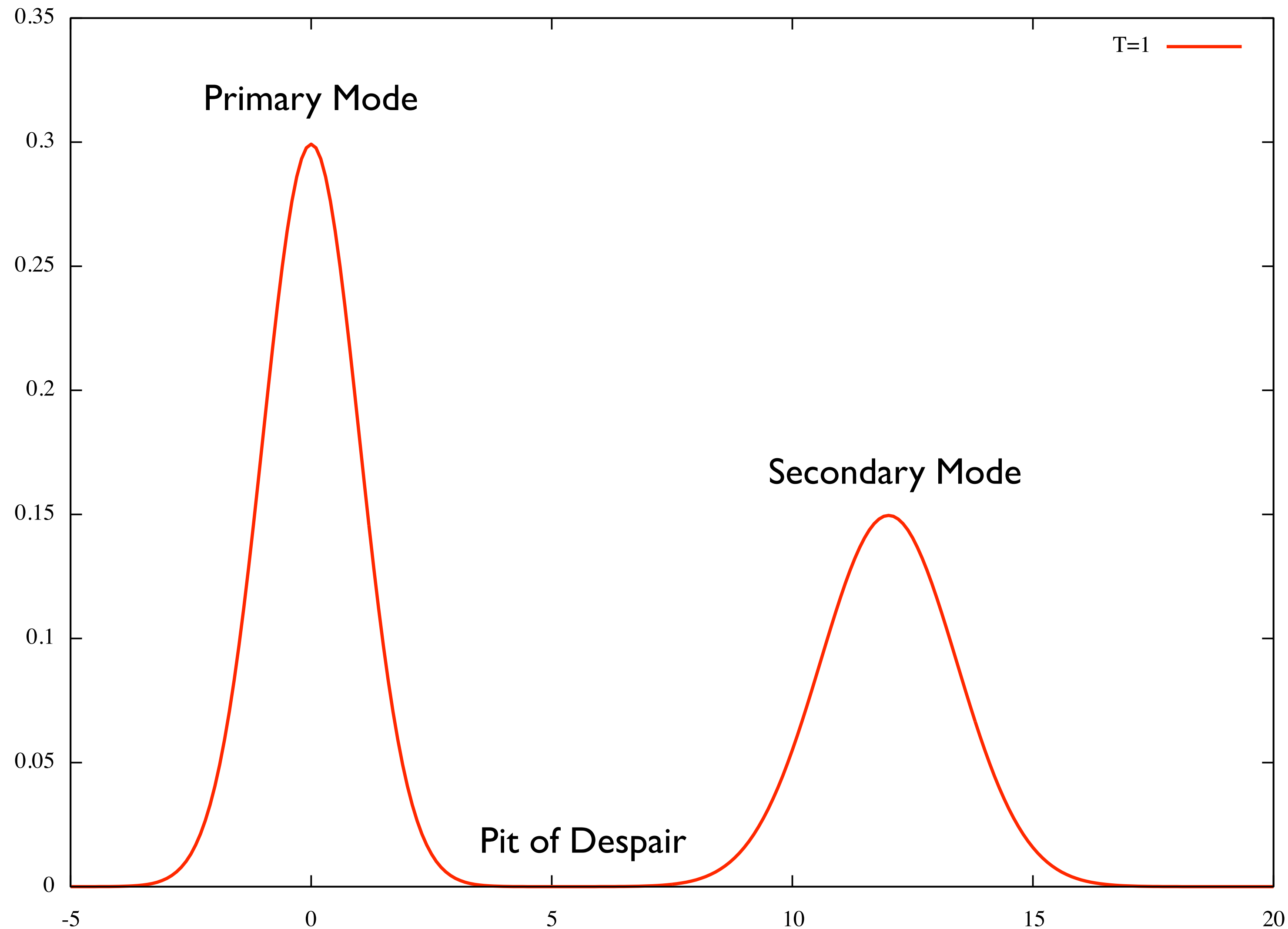
Differential evolution [Braak (2005)]





# Parallel Tempering

[Swendsen & Wang, 1986]



Ordinary MCMC techniques side-step the need to compute the evidence. PT uses multiple, coupled chains to improve mixing, and also allows the evidence to be computed.

Explore tempered posterior

$$\pi(\vec{\lambda}|\mathbf{d})_T = p(\mathbf{d}|\vec{\lambda})^{1/T} p(\vec{\lambda})$$

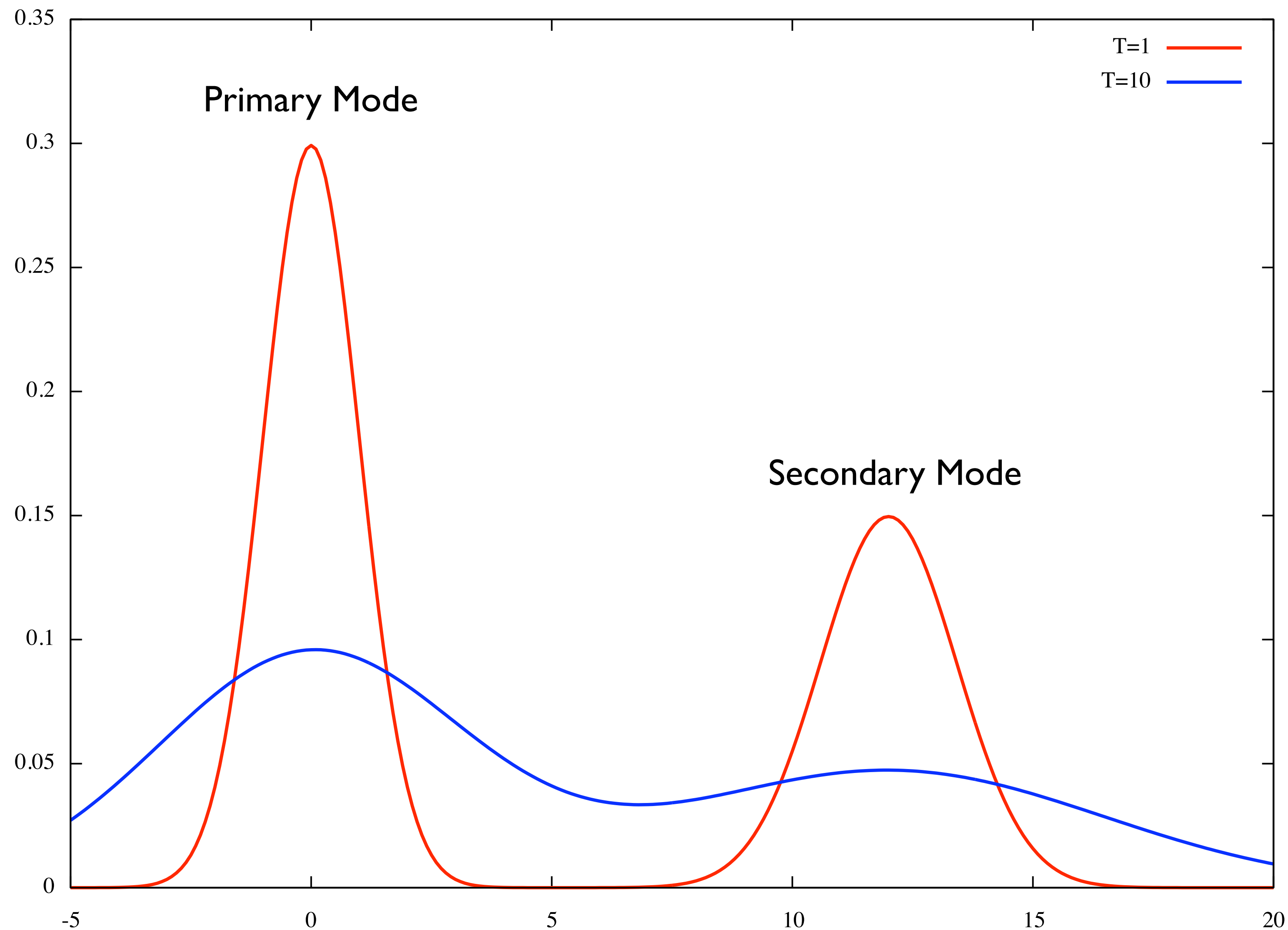
Compute model evidence

$$\log p(\mathbf{d}) = \int_0^1 \mathbb{E}[\log p(\mathbf{d}|\vec{\lambda})]_{\beta} d\beta$$

(Here  $\beta = \frac{1}{T}$ )

# Parallel Tempering

[Swendsen & Wang, 1986]



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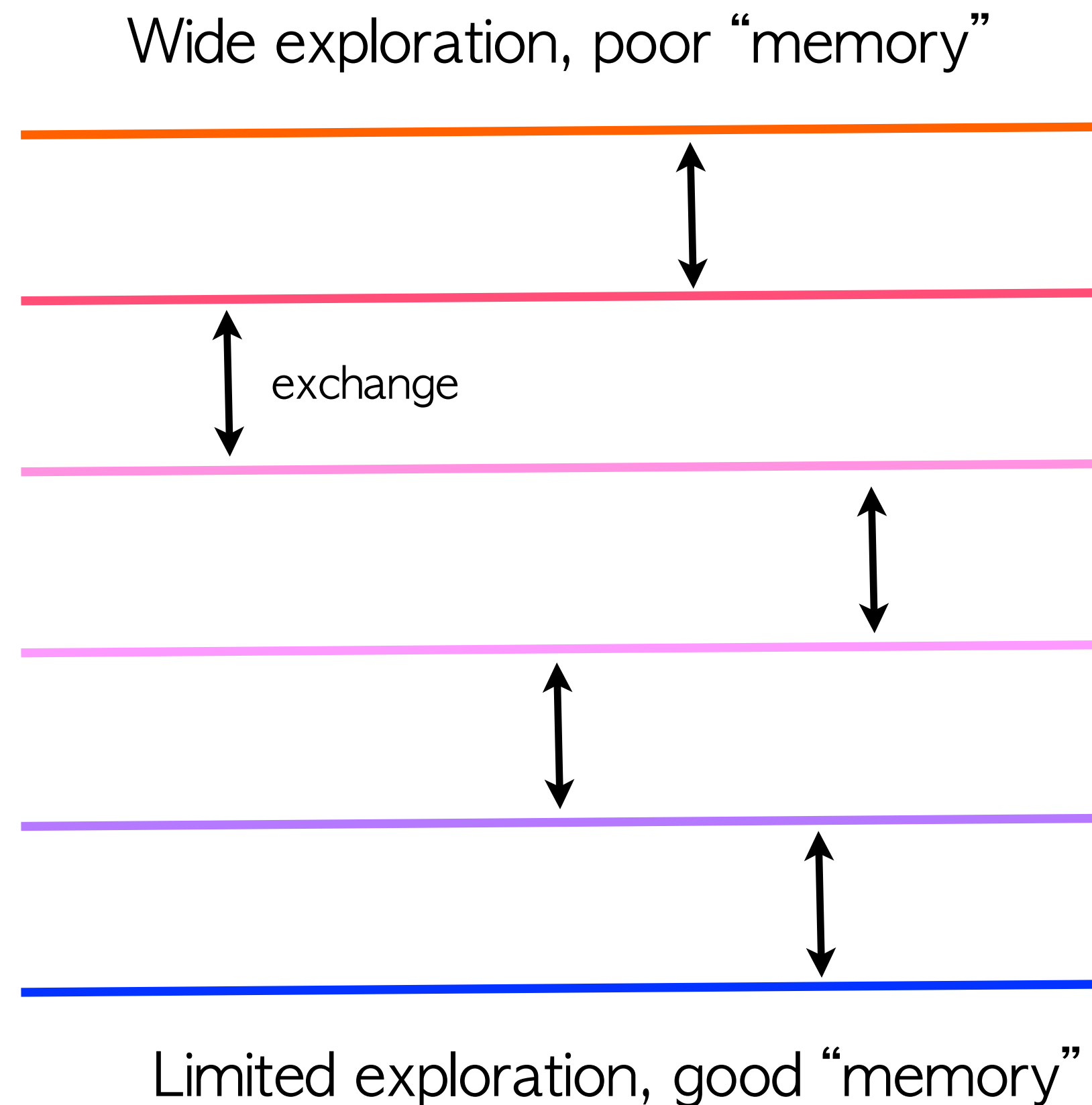
$$\pi(\vec{\lambda}|\mathbf{d})_T = p(\mathbf{d}|\vec{\lambda})^{1/T} p(\vec{\lambda})$$

Compute model evidence

$$\log p(\mathbf{d}) = \int_0^1 \mathbb{E}[\log p(\mathbf{d}|\vec{\lambda})]_{\beta} d\beta$$

(Here  $\beta = \frac{1}{T}$ )

# Parallel Tempering



Inter-chain transition probability

$$H = \min \left( 1, \frac{\pi(\vec{\lambda}_{j+1} | \mathbf{d})_{T_j} \pi(\vec{\lambda}_j | \mathbf{d})_{T_{j+1}}}{\pi(\vec{\lambda}_j | \mathbf{d})_{T_j} \pi(\vec{\lambda}_{j+1} | \mathbf{d})_{T_{j+1}}} \right)$$

Good solutions sink down ladder and get stored



# Parallel Tempering - Temperature Spacing

$$\ln L_T = \ln(p(\mathbf{d}|\vec{\lambda})^{1/T}) = -\frac{1}{2T}(\mathbf{d} - \mathbf{h}(\vec{\lambda})|\mathbf{d} - \mathbf{h}(\vec{\lambda})) \approx -\frac{\Gamma_{ij}\Delta\lambda^i\Delta\lambda^j}{2T}$$

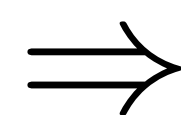
Coordinate  
transformation:

$$\ln L_T \approx -\frac{\delta_{ij}\theta^i\theta^j}{2T} \quad \Rightarrow \quad p(\ln L_T) = \frac{(-\ln L)^{D/2-1}}{\Gamma(\frac{D}{2})T^{D/2}} e^{\ln L/T}$$

$$\mathbb{E}[\ln L_T] = -\frac{DT}{2} \quad \text{Var}[\ln L_T] = \frac{DT^2}{2}$$

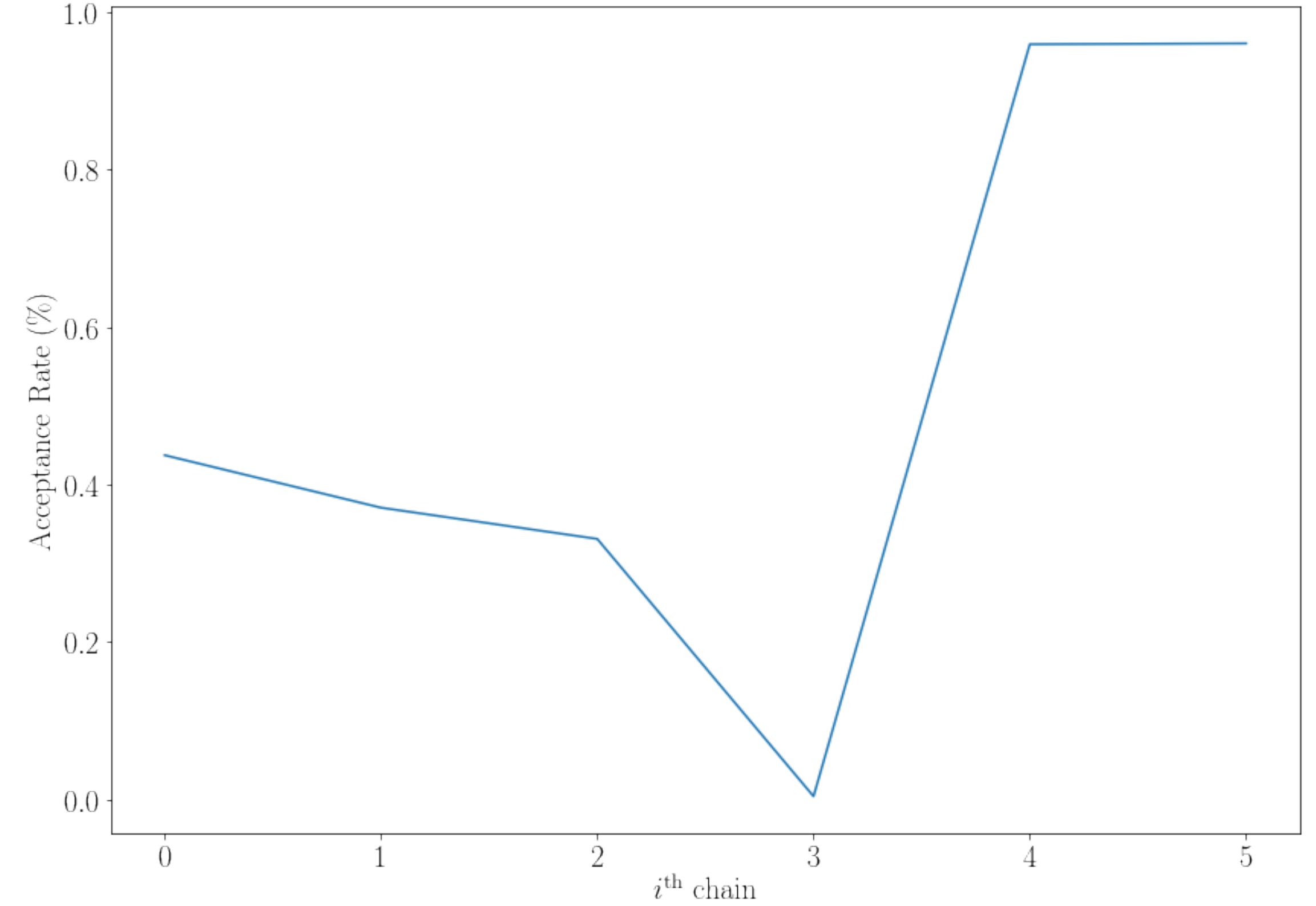
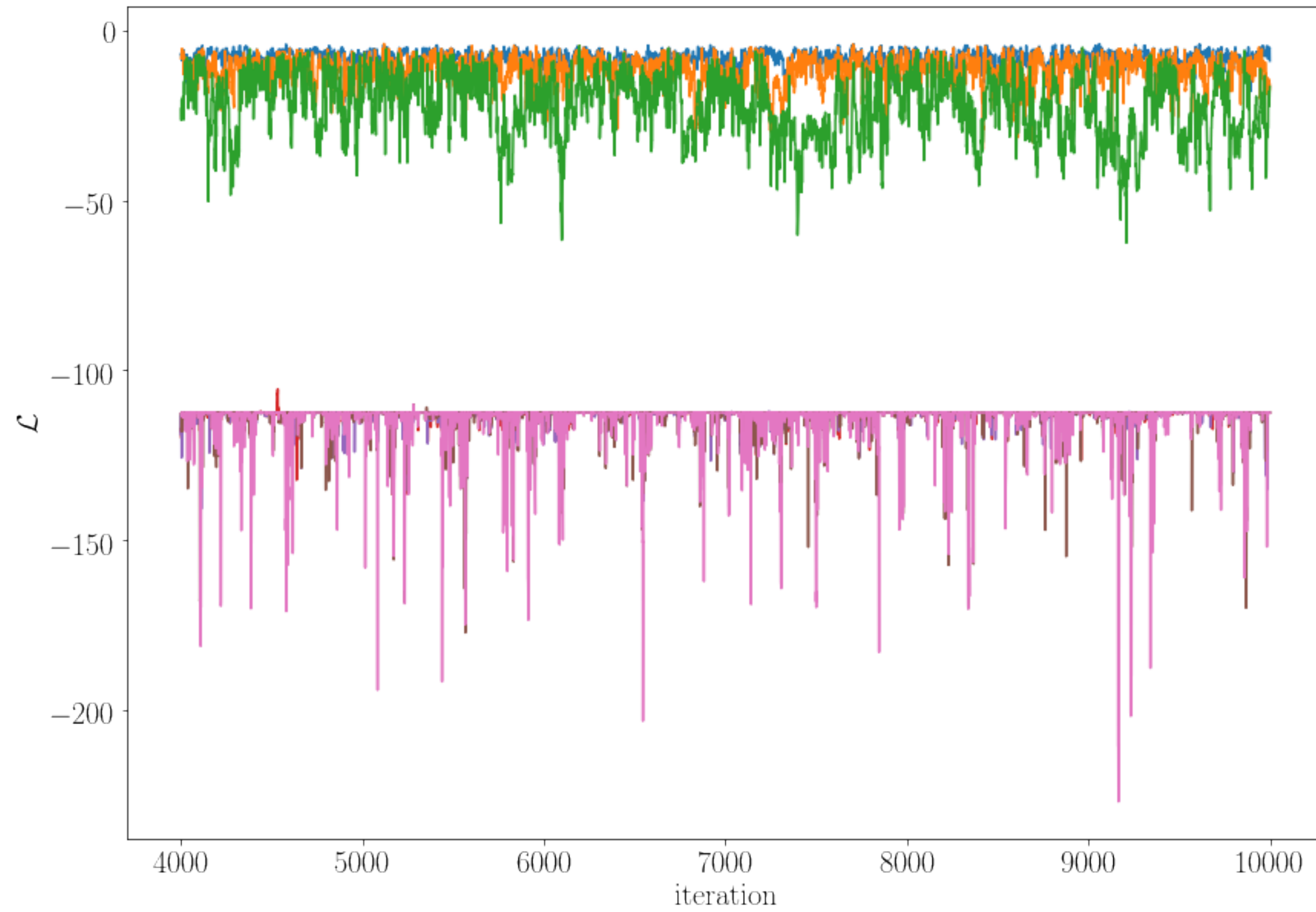
Scaled distance  
between chains:

$$\frac{\mathbb{E}[\ln L_{T_i}] - \mathbb{E}[\ln L_{T_{i+1}}]}{\sqrt{\text{Var}[\ln L_{T_i}]}} = \frac{\Delta T}{T} \sqrt{\frac{D}{2}}$$



Uniform acceptance of exchange for logarithmically spaced temperature ladder. Larger dimension models require closer temperature spacing.

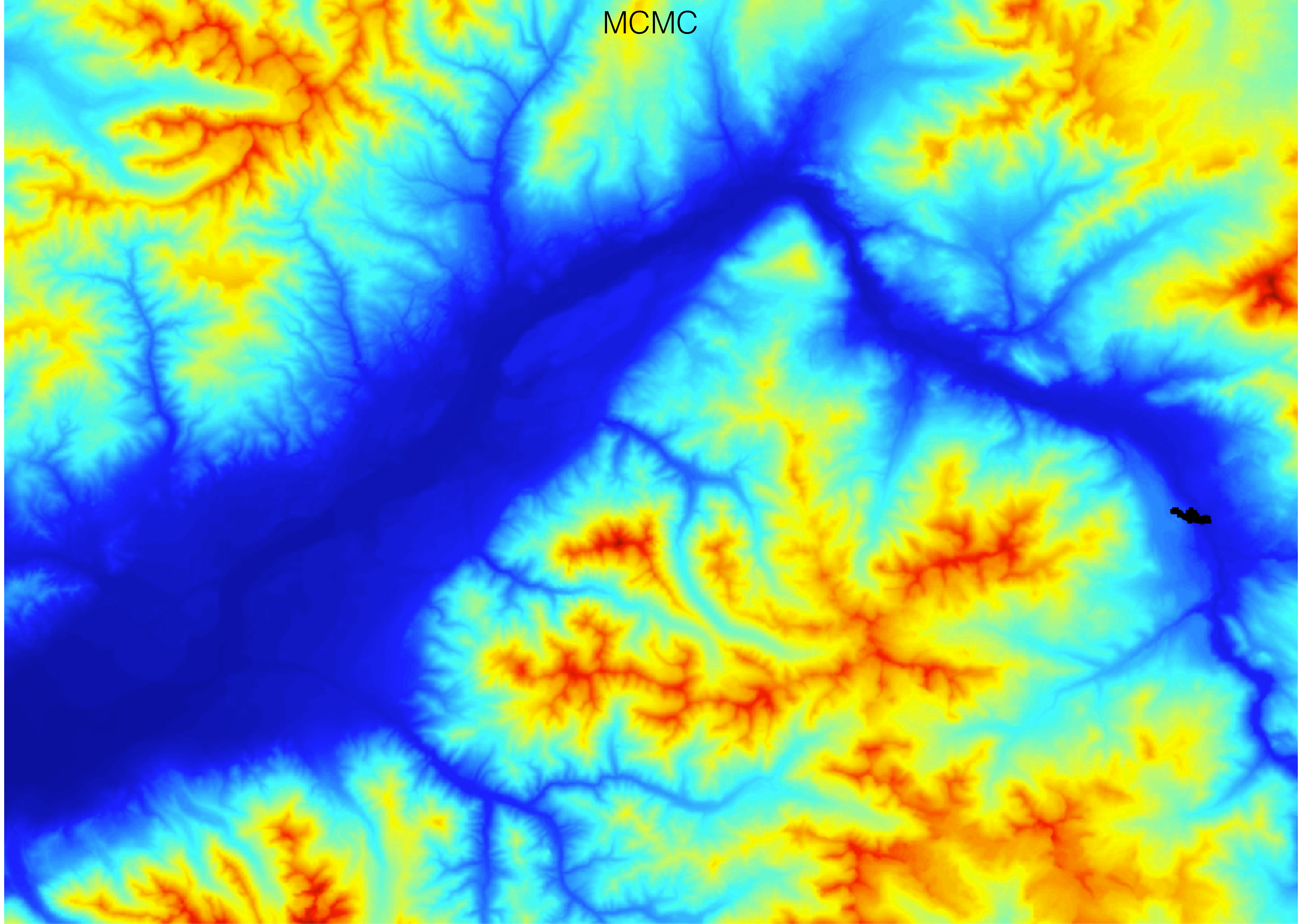
# Parallel Tempering



Need to use dynamic temperature spacing: [Vousden, Farr, Mandel, MNRAS **455** 1919 (2016)]

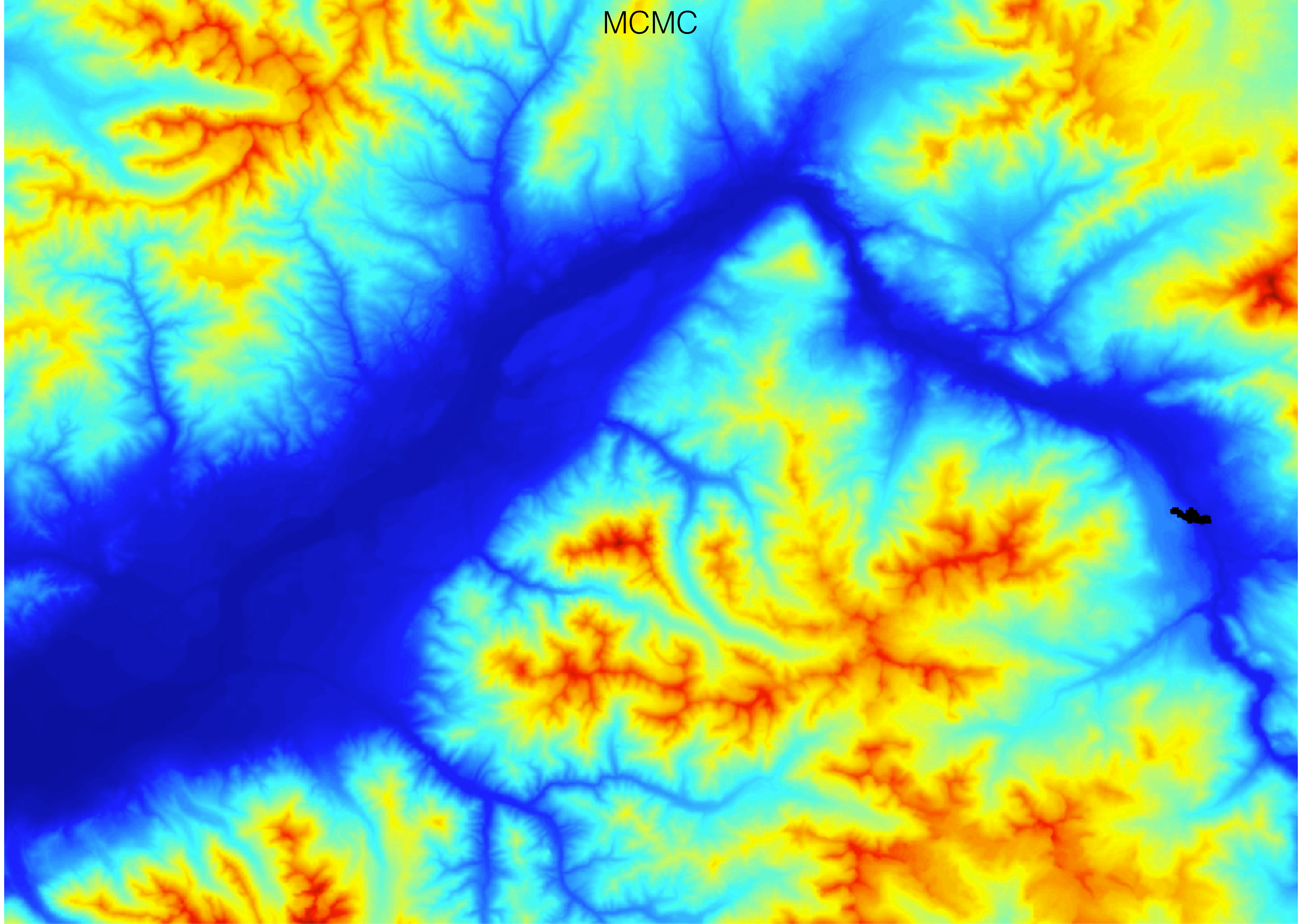


MCMC



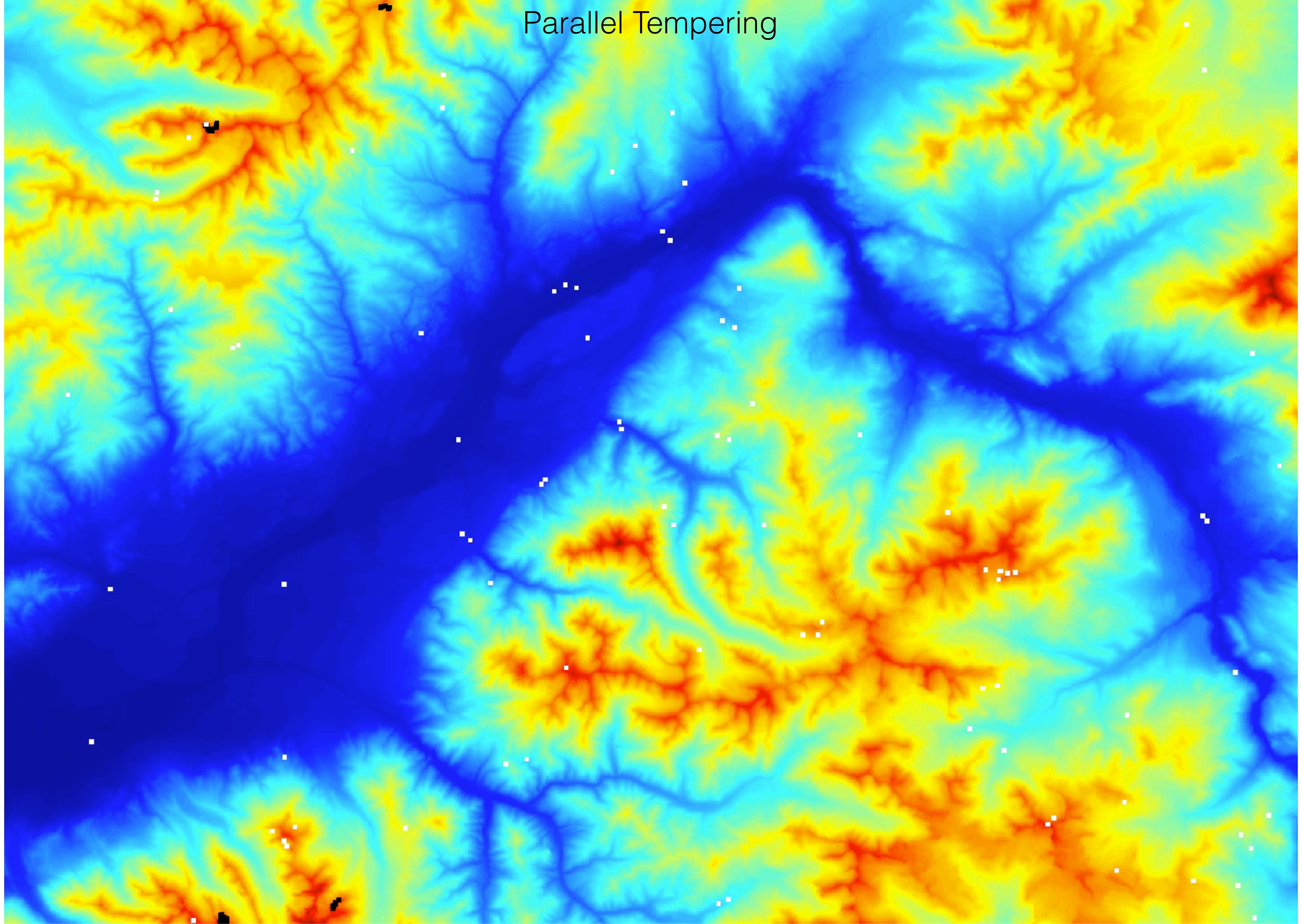


MCMC



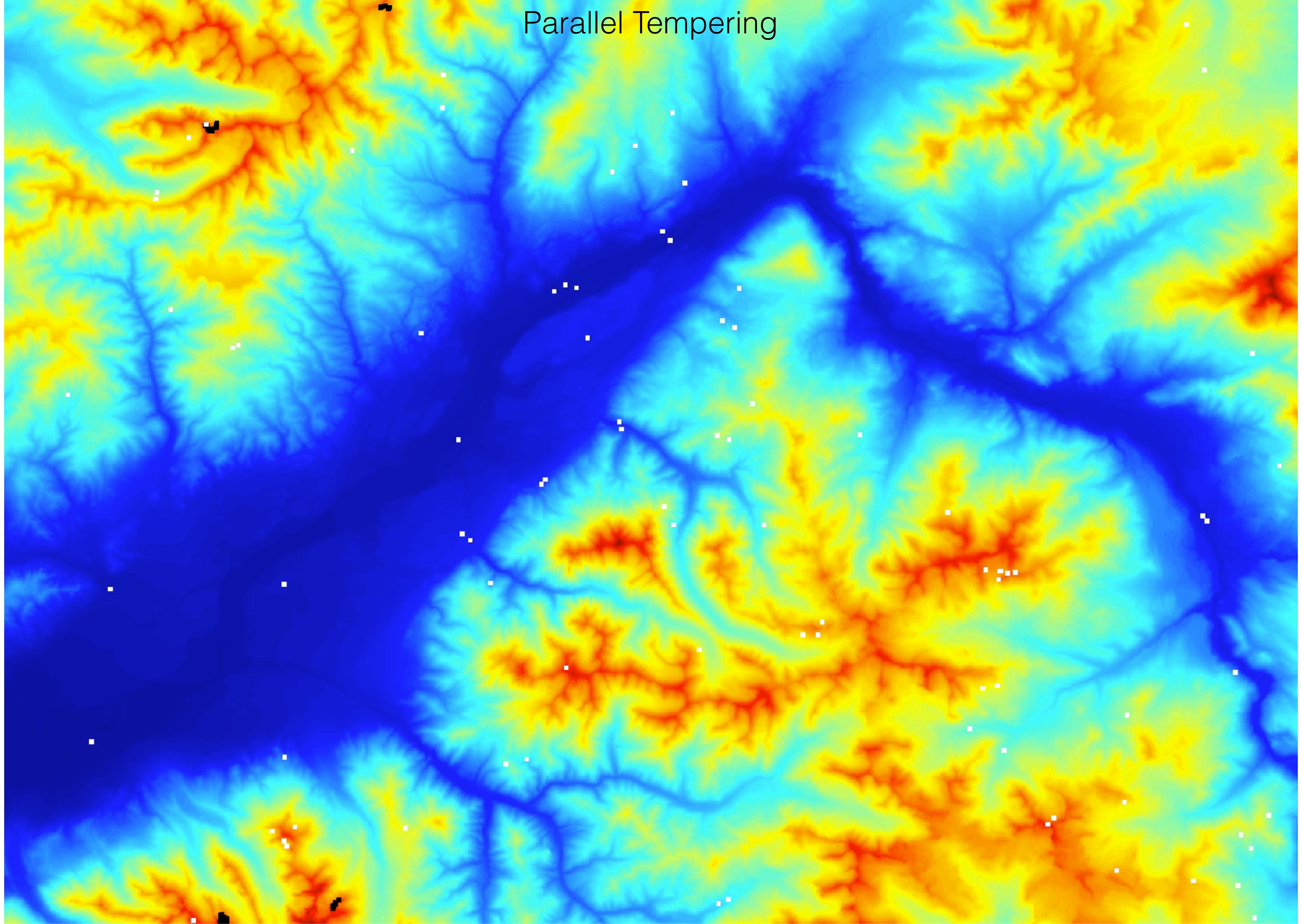


# Parallel Tempering





# Parallel Tempering





# Solving for everything

- Can update one source, or even one parameter, at a time
- Model dimension will grow to  $D \sim 500K$
- Cost scales as some polynomial of the model dimension
- Highly parallel. Can collect samples from thousands of chains
- Parallel tempering ideal for distributed computing - chain swaps can be done asynchronously



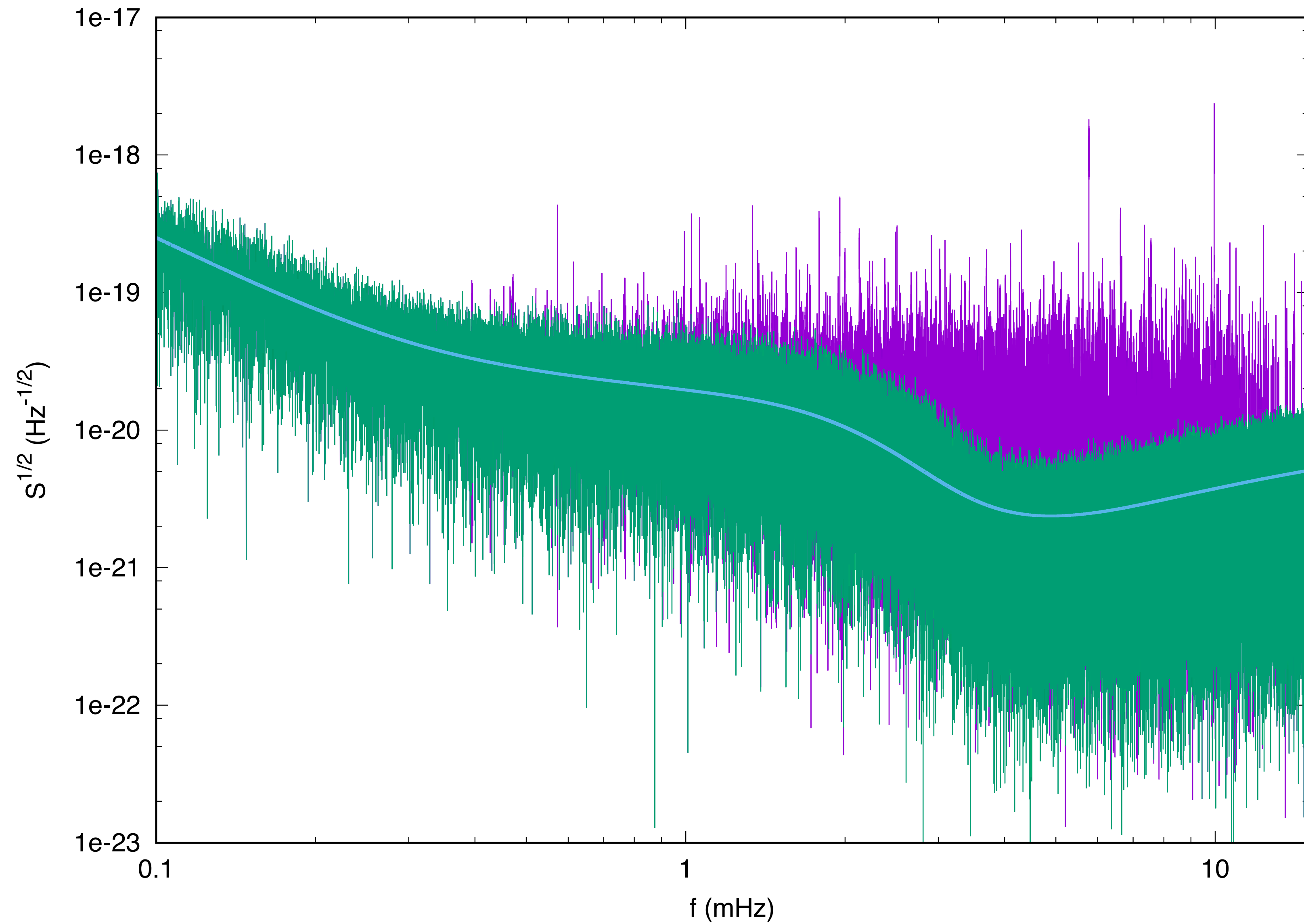


# Return to the galactic binary problem

Travis Robson, Neil Cornish & Tyson Littenberg

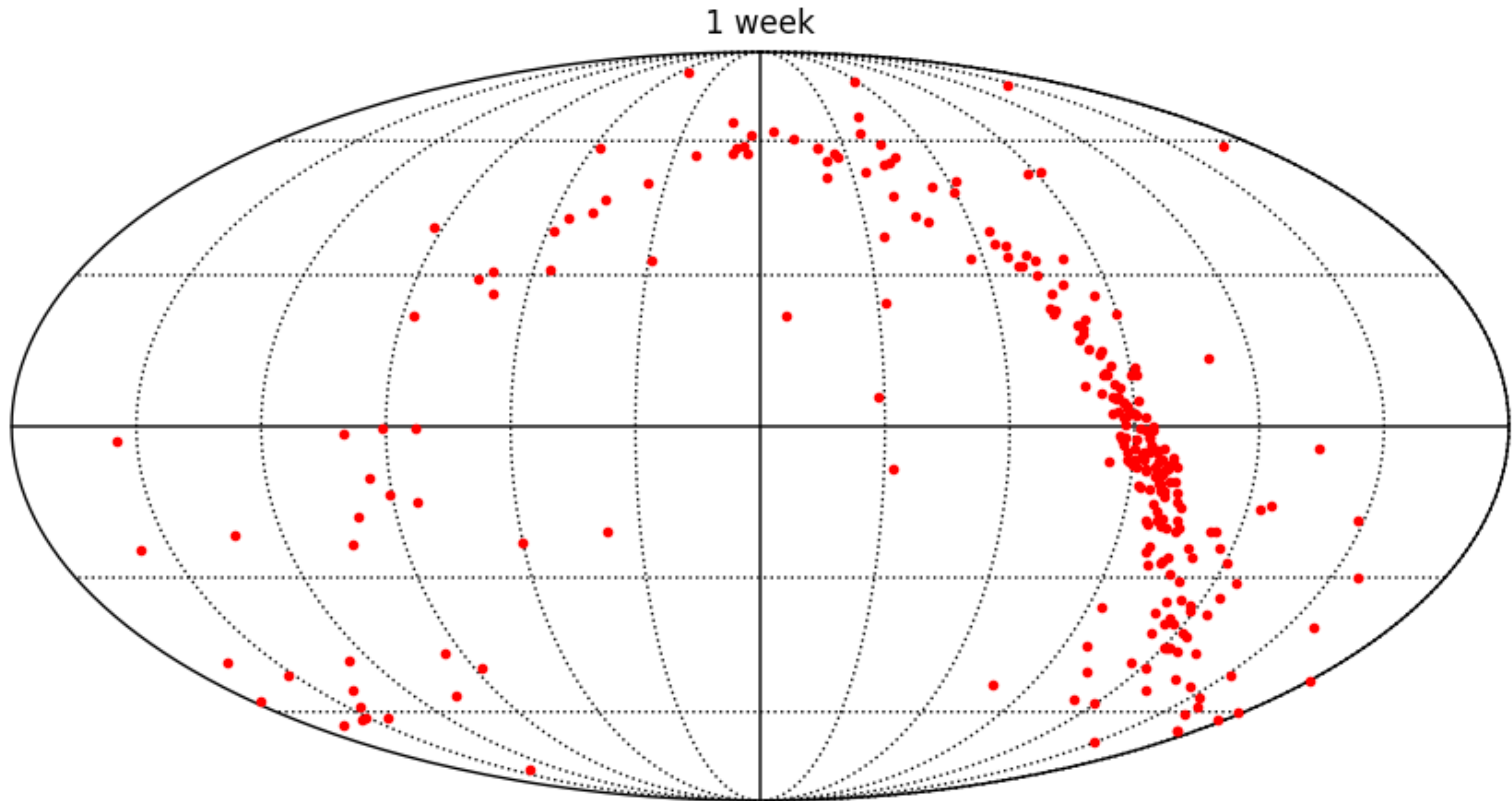
- Uses BayesWave code base (originally developed from LISA GB experience)
- Simultaneous solution for noise and signals
- Time evolving approach = weekly increments
- F-statistic based likelihood map as global proposal

# Galaxy + Instrument noise spectrum, 1 year

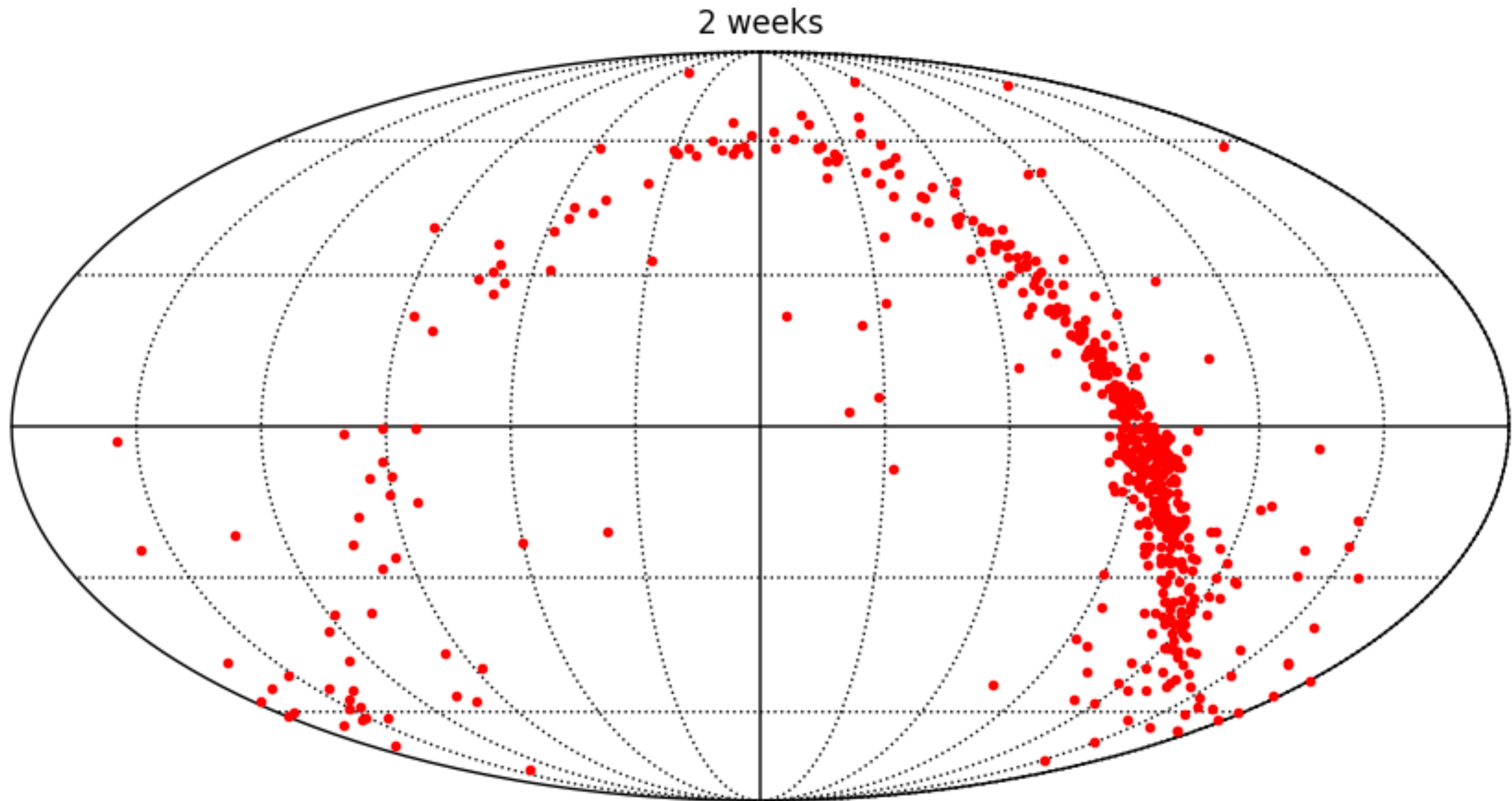




# LISA galaxy catalog over time

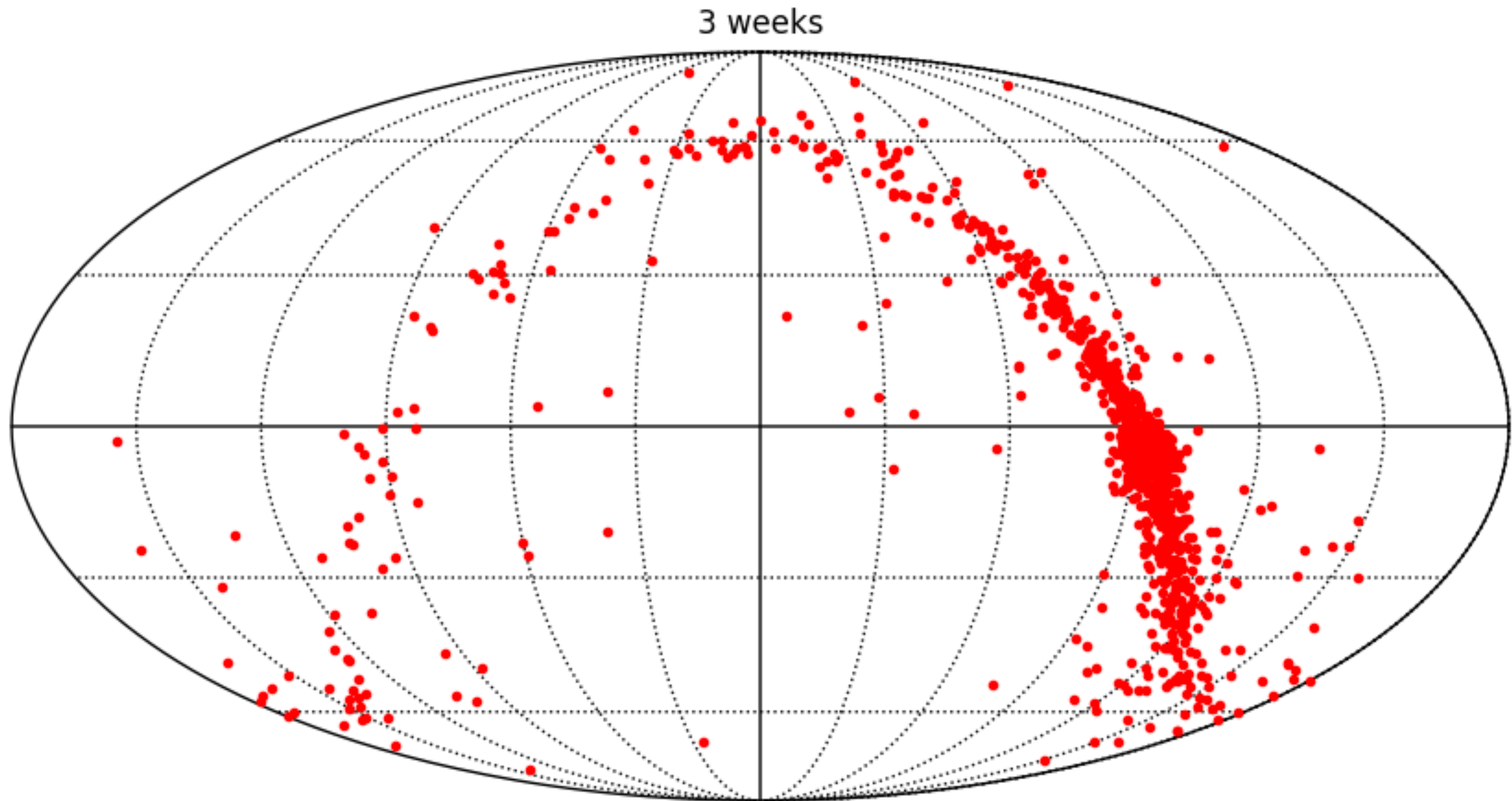


# LISA galaxy catalog over time

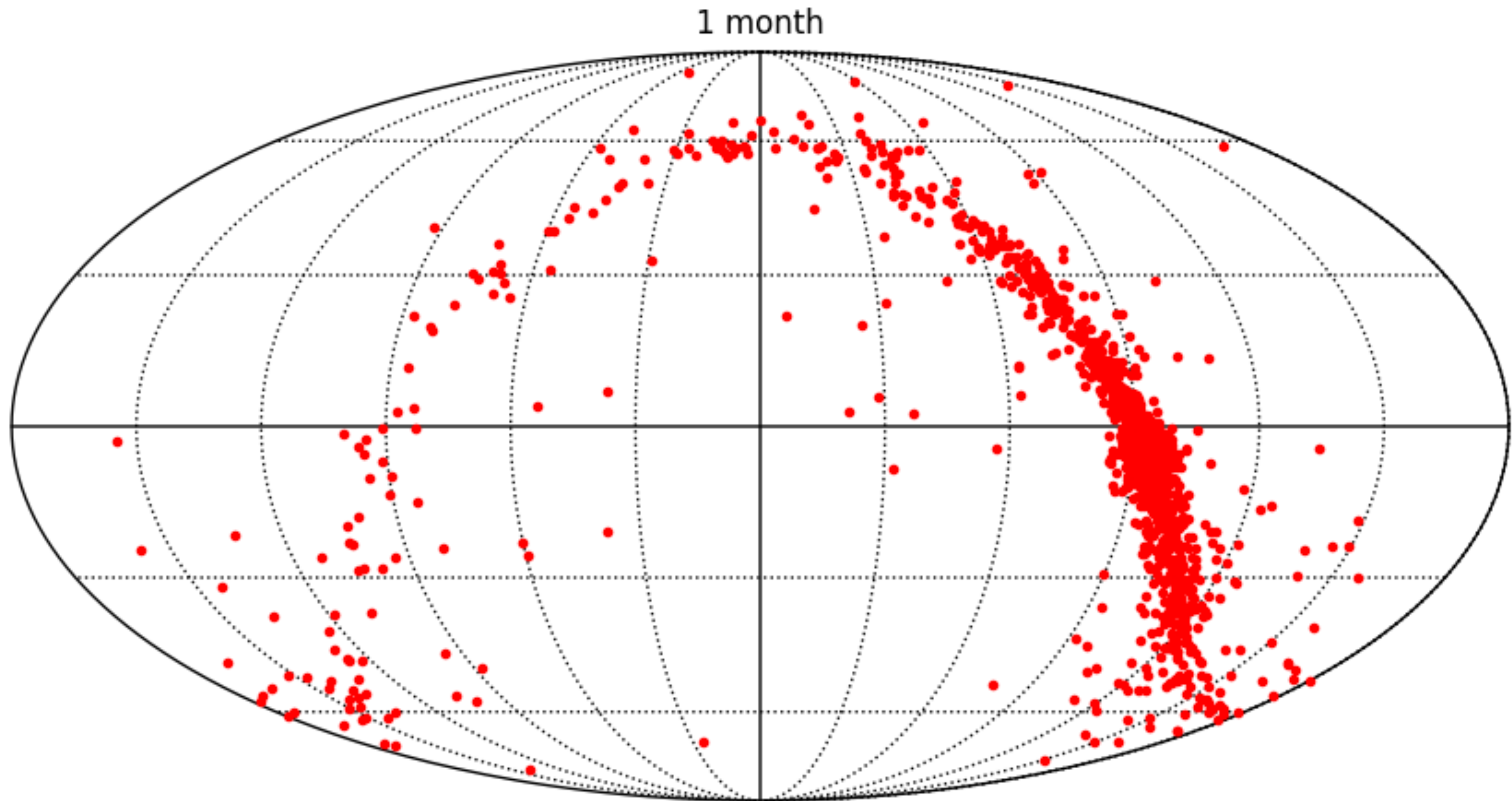




# LISA galaxy catalog over time

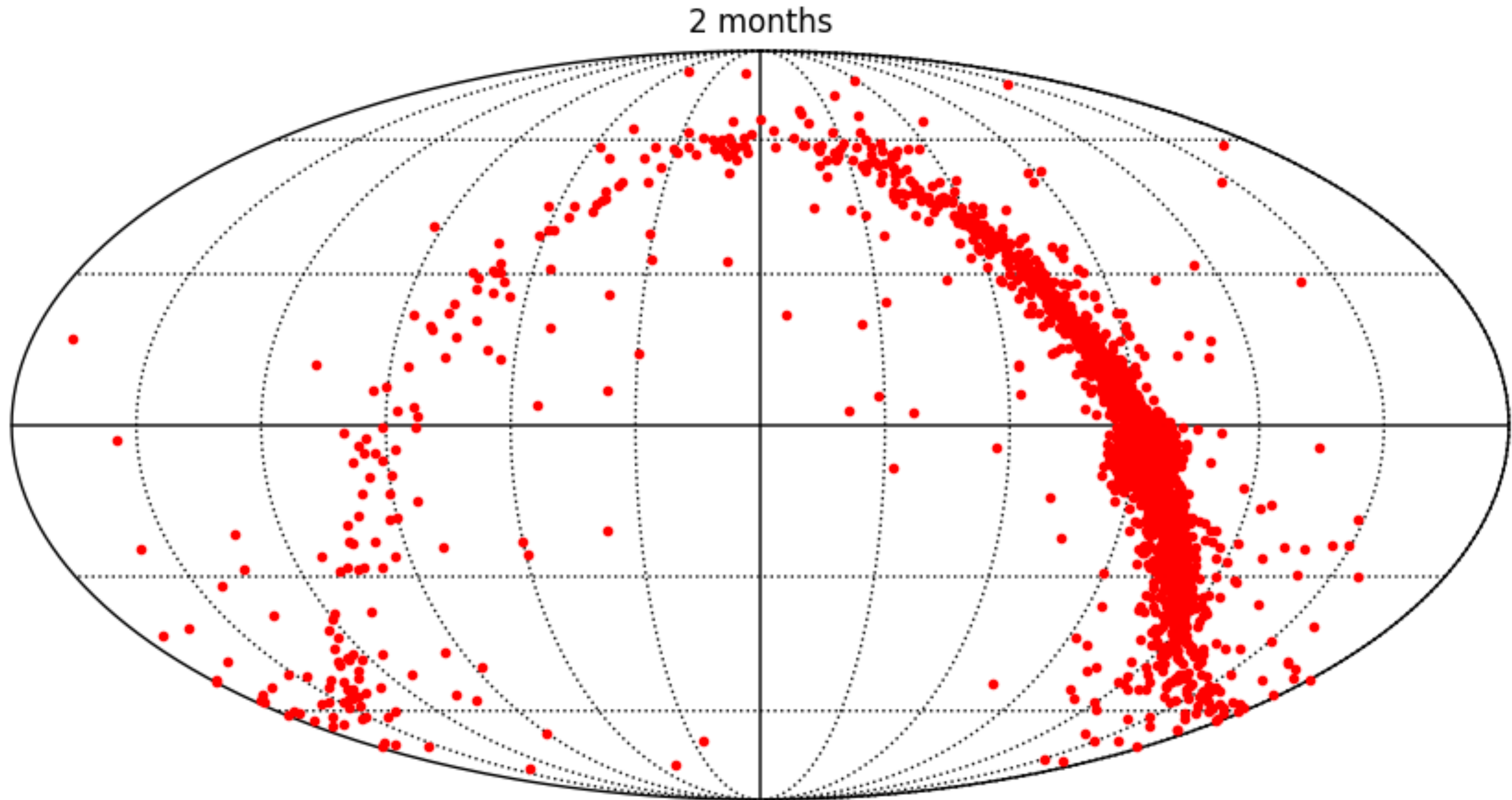


# LISA galaxy catalog over time

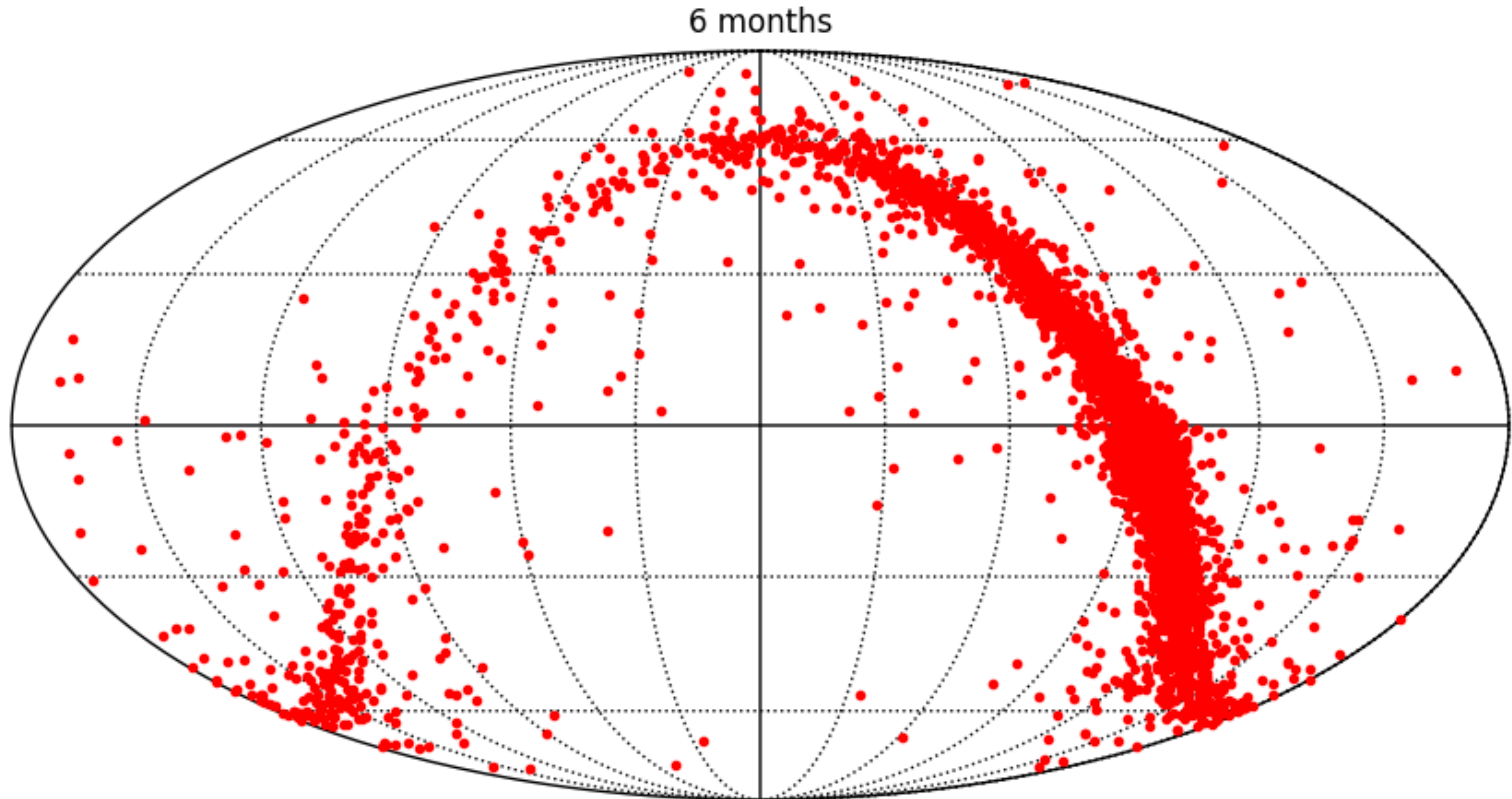




# LISA galaxy catalog over time

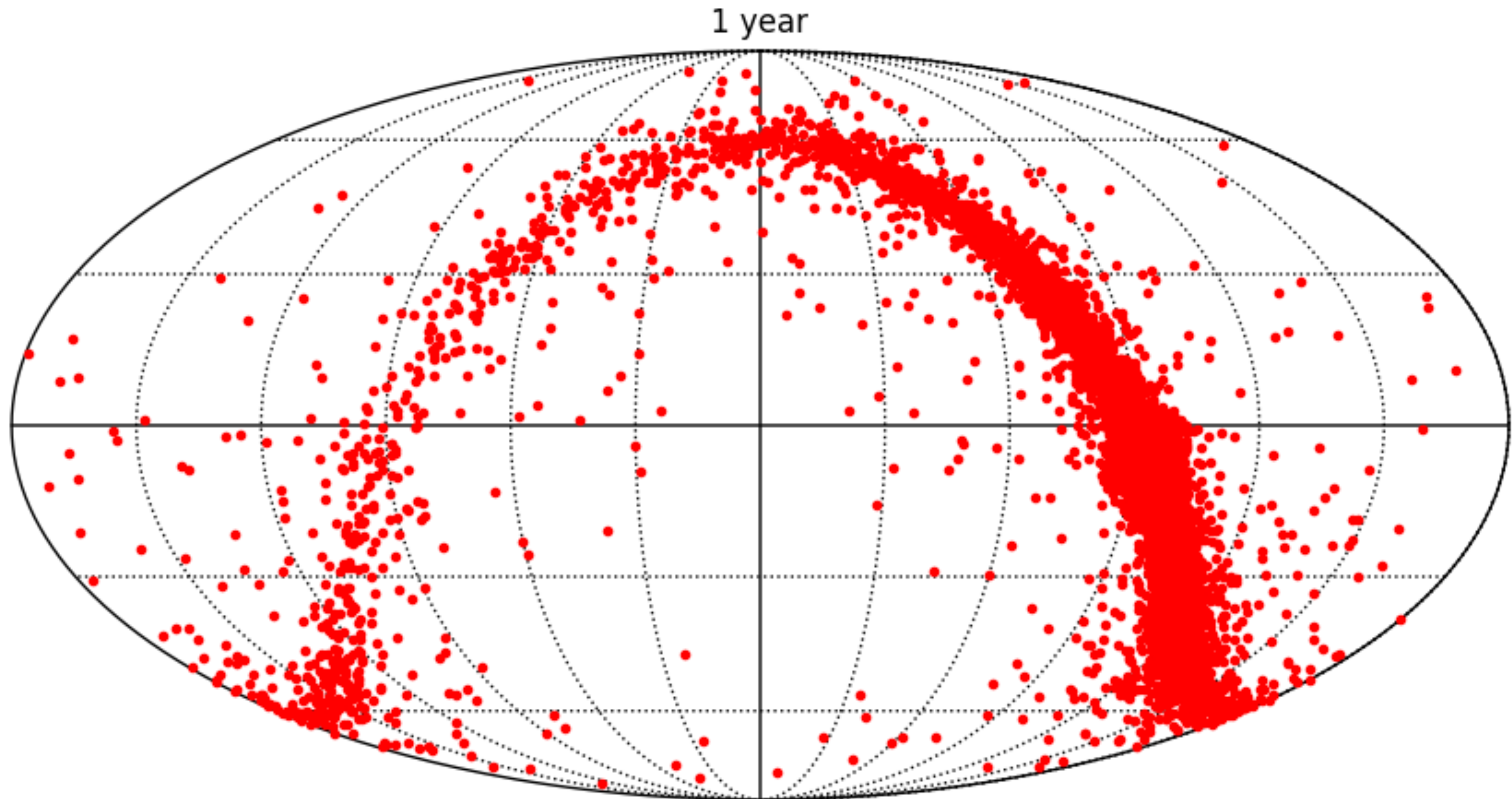


# LISA galaxy catalog over time

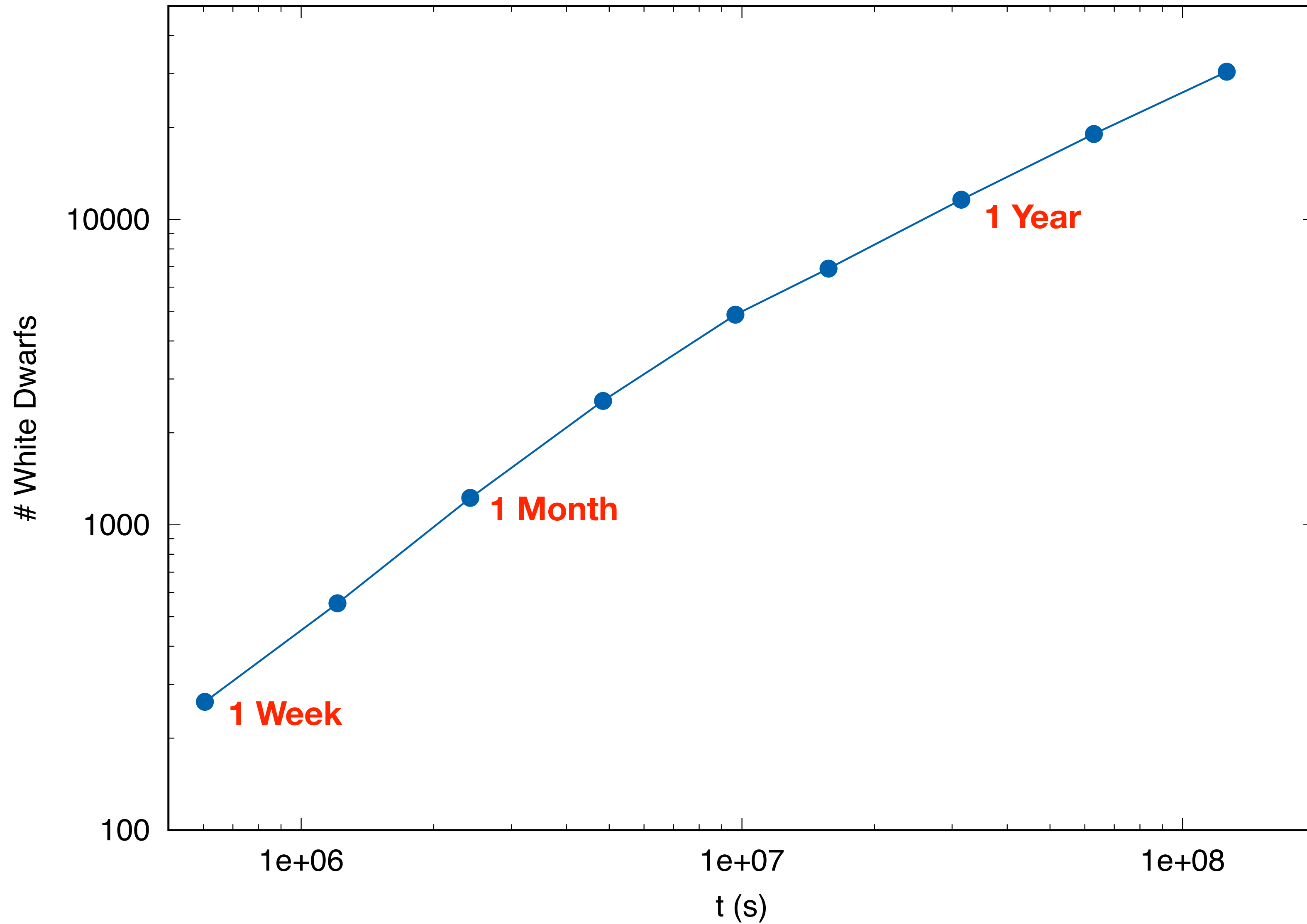




# LISA galaxy catalog over time



# LISA galaxy catalog over time





# Galactic Binaries: F-statistic Likelihood Maps

$$h(t) = \sum_{k=1}^4 a_k(A, \psi, \iota, \psi_0) \hat{h}^k(t, f_0, \dot{f}_0, \theta, \phi)$$

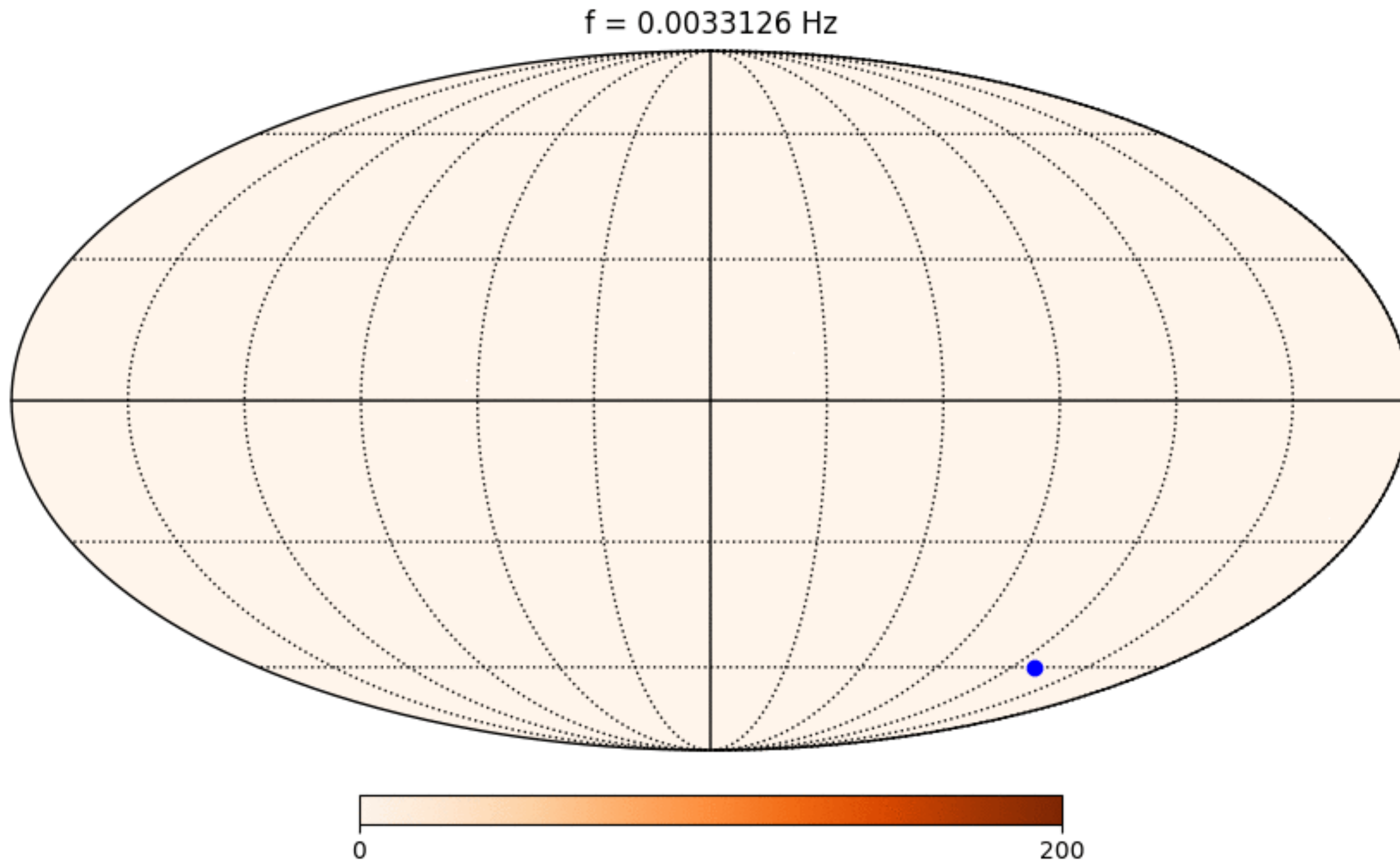
[Jaranowski, Krolak & Schutz, Phys. Rev. D58 063001 (1998)]

$$\mathcal{F} = \max_{(A, \psi, \iota, \psi_0)} \left[ (d|h) - \frac{1}{2}(h|h) \right] = \frac{1}{2} (\hat{h}^i | \hat{h}^j)^{-1} (d | \hat{h}^i) (d | \hat{h}^j)$$

Use maps of  $\mathcal{F}(f_0, \dot{f}_0, \theta, \phi)$  as a global proposal

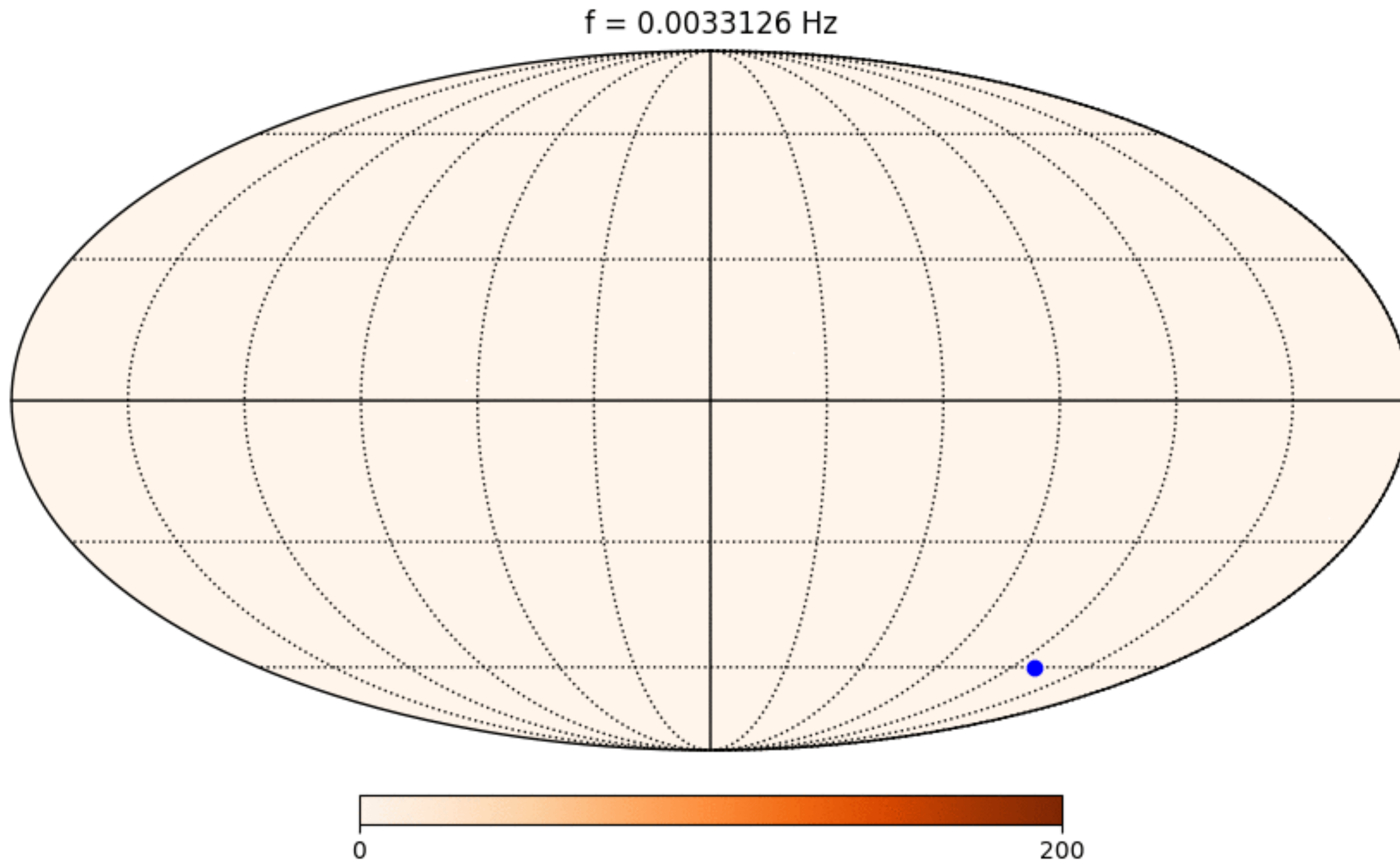
Ignores massive black hole mergers, EMRIs etc. Some overlap with LIGO BHs

# F-statistic map. Single Galactic Binary



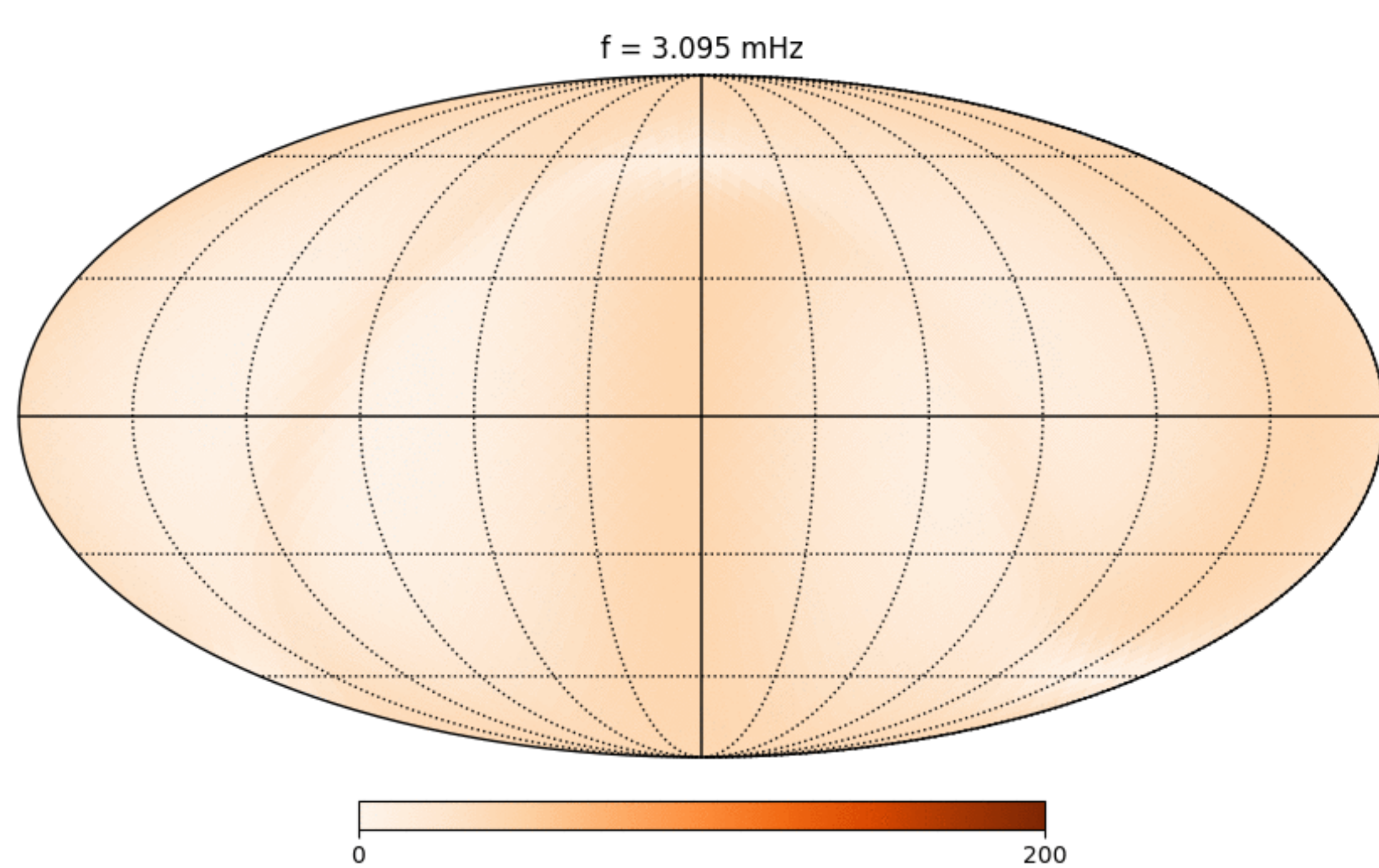


# F-statistic map. Single Galactic Binary

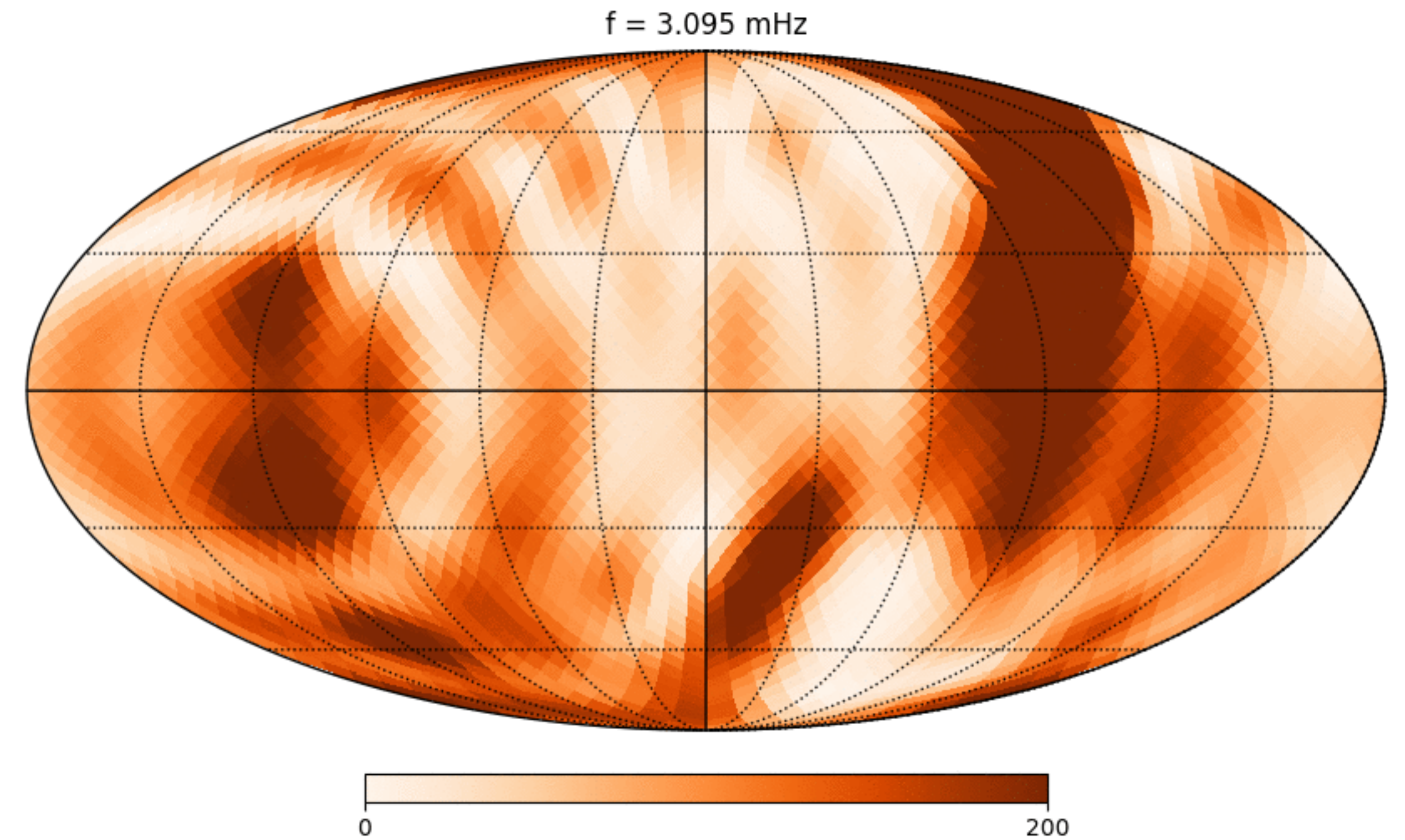




# F-statistic maps: Full galaxy near 3 mHz



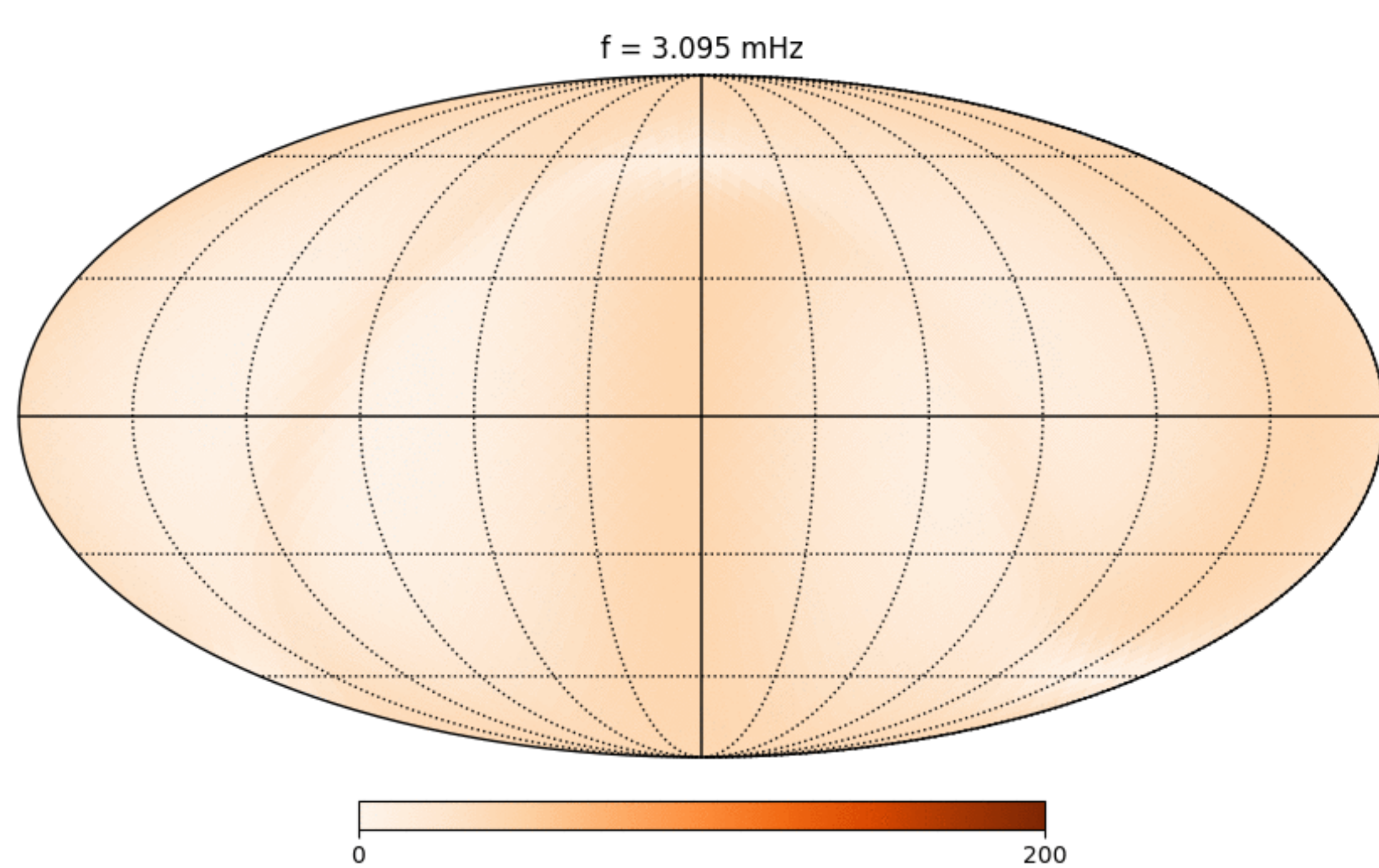
1 - month



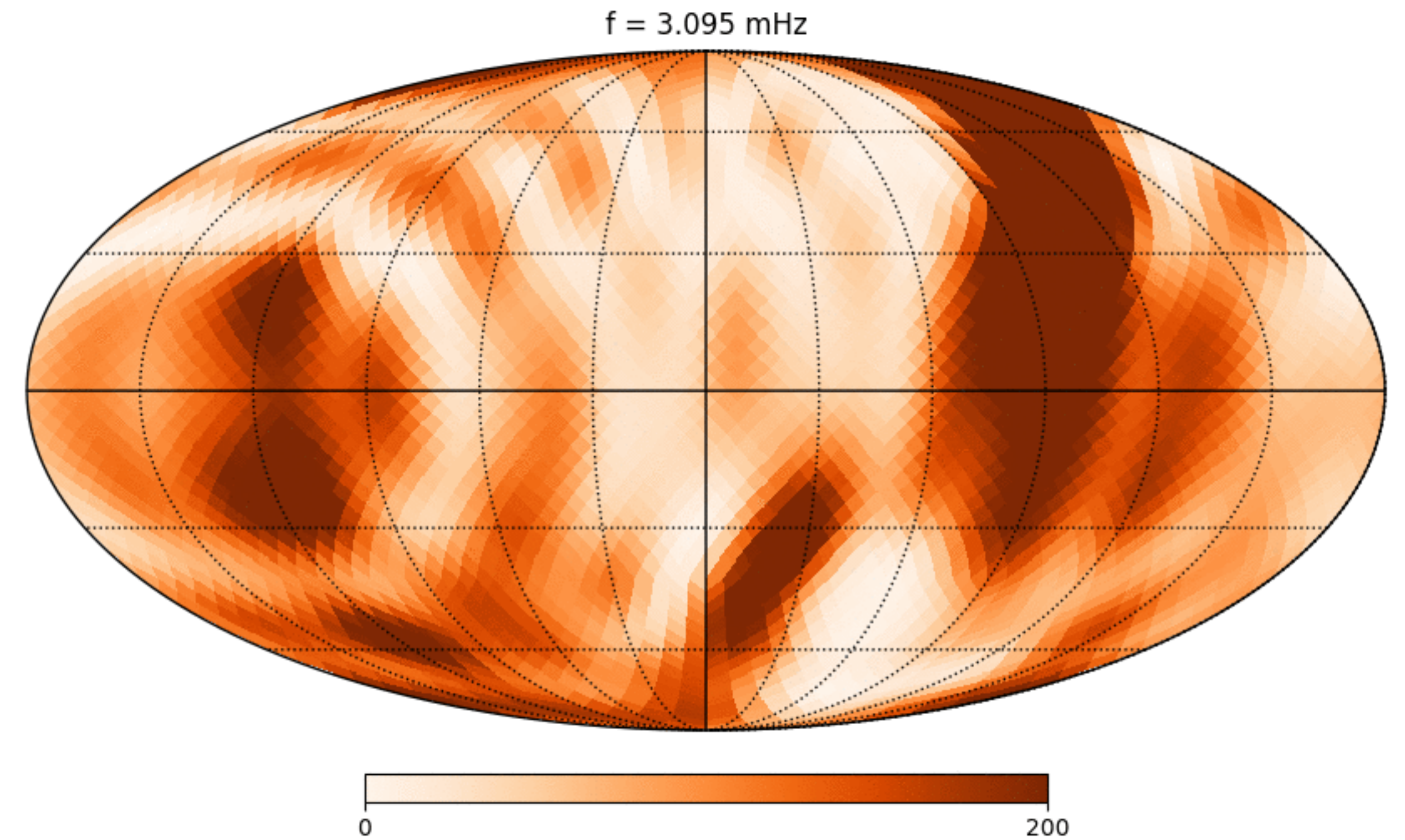
1 - year



# F-statistic maps: Full galaxy near 3 mHz

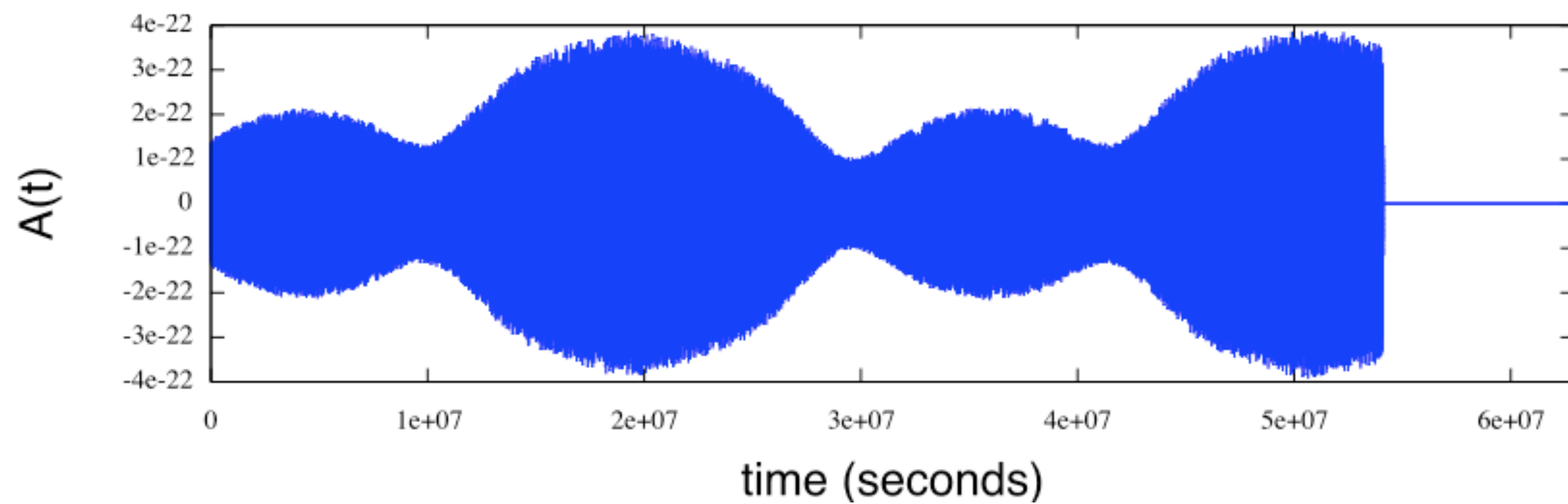
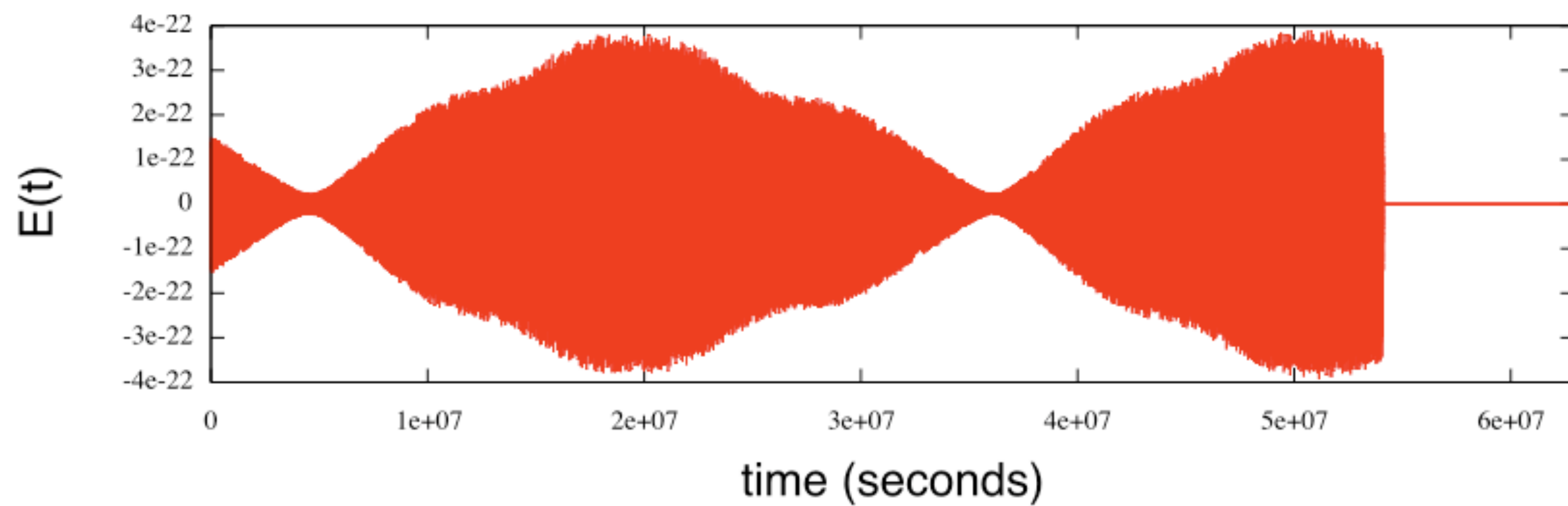


1 - month



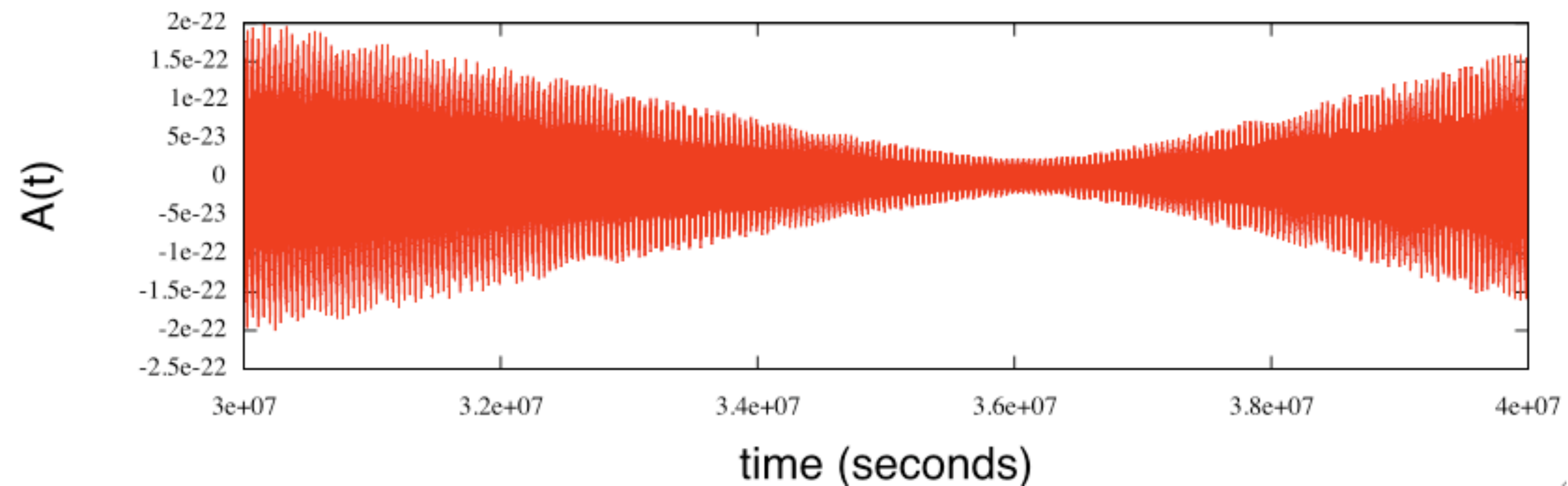
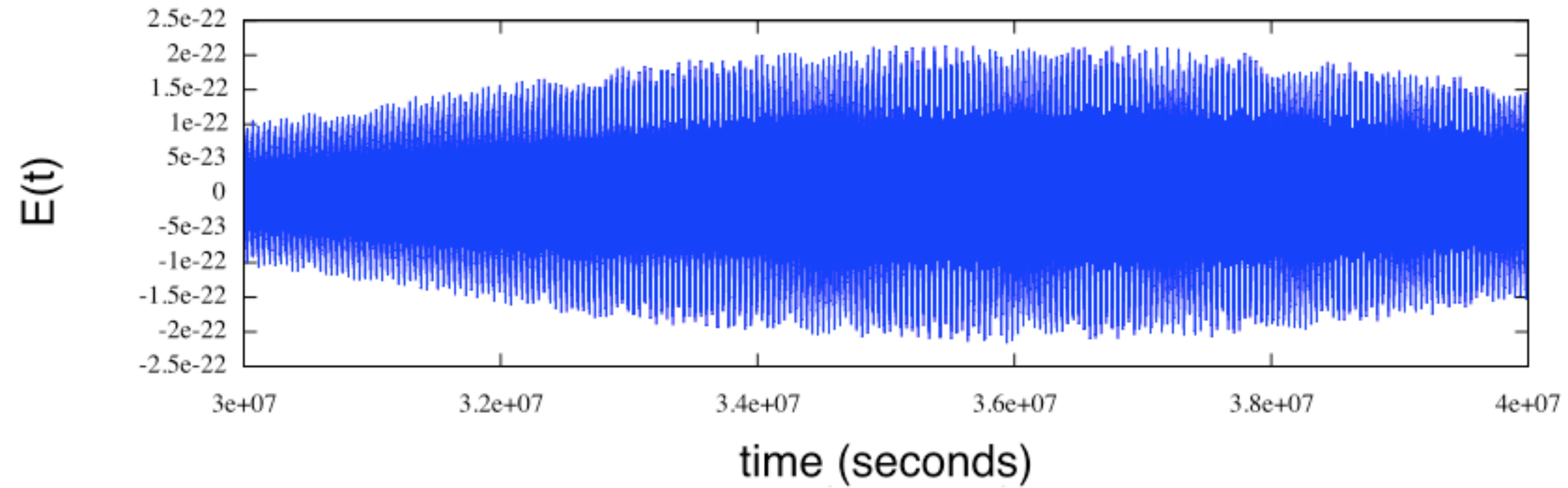
1 - year

# Extreme Mass Ratio Inspirals

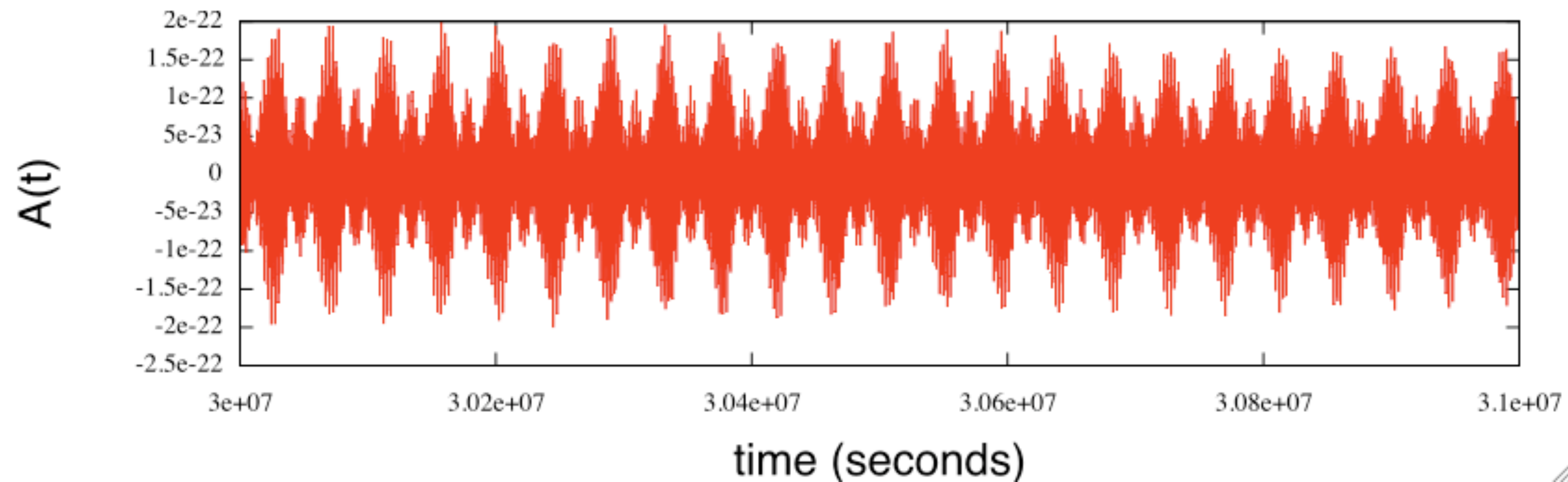
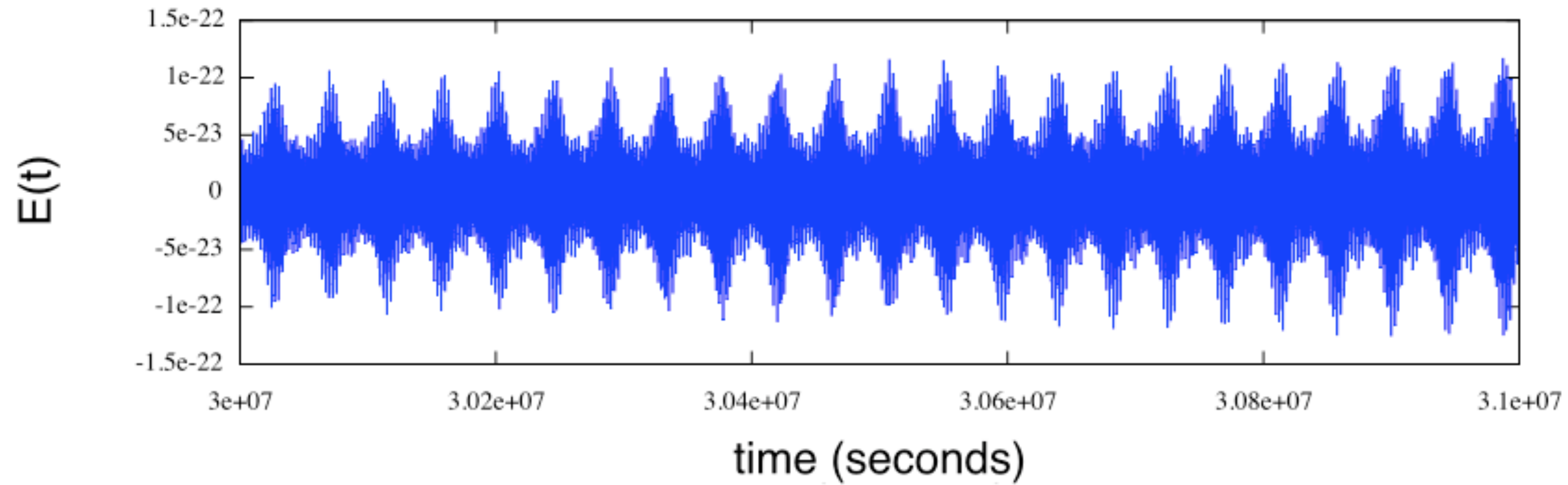




# Extreme Mass Ratio Inspirals

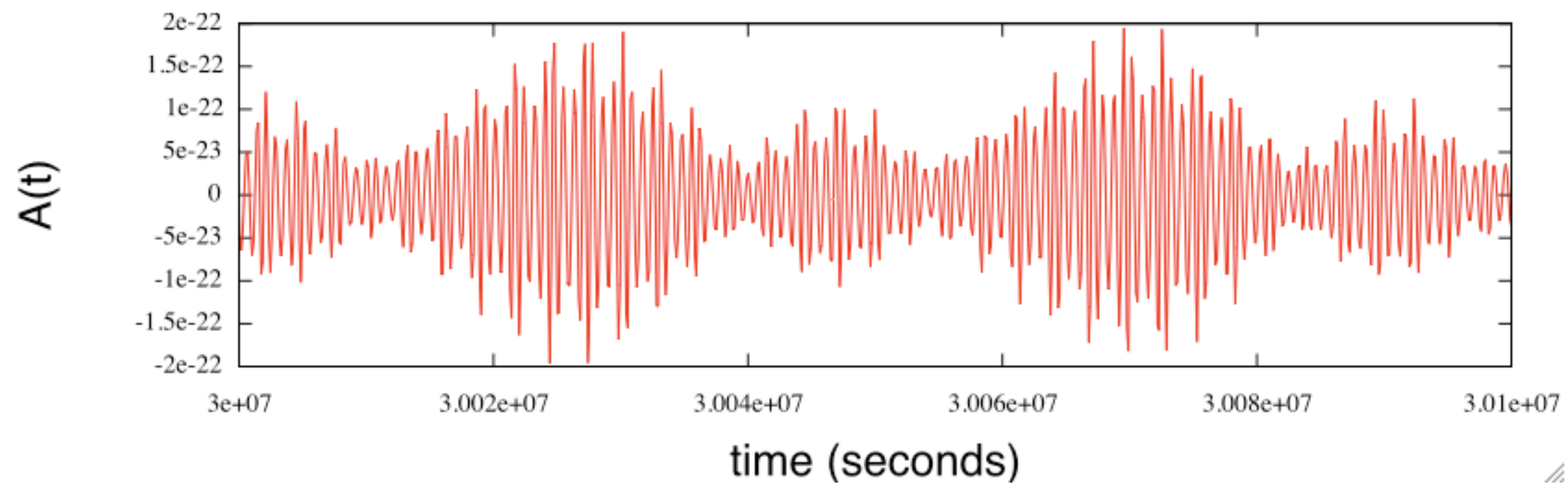
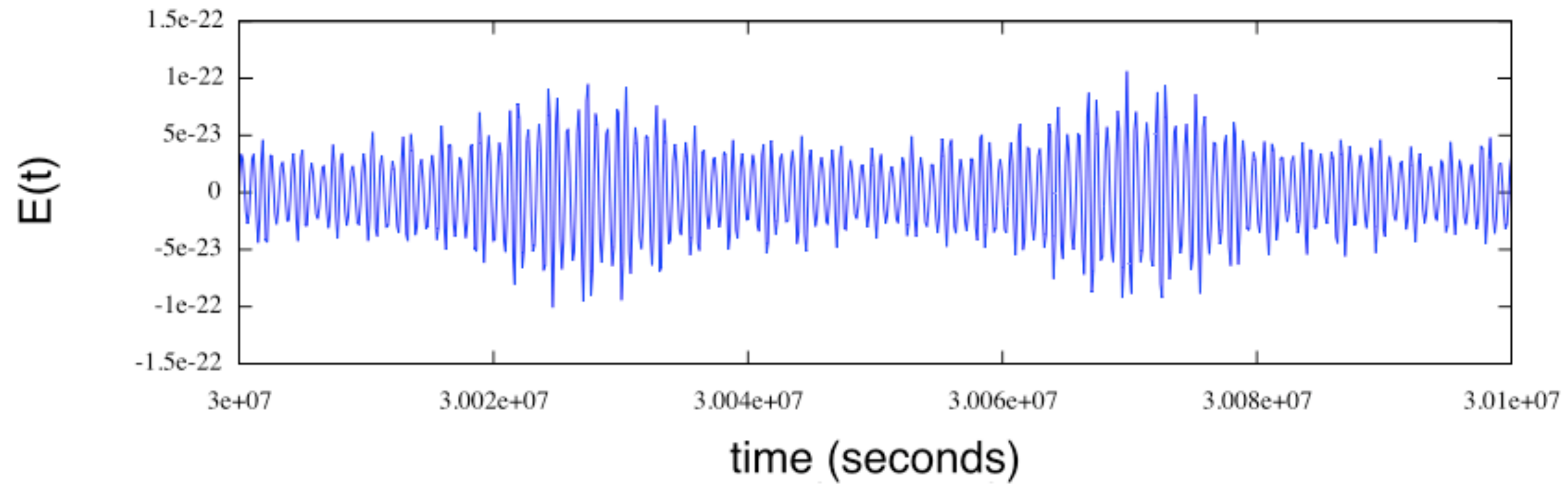


# Extreme Mass Ratio Inspirals



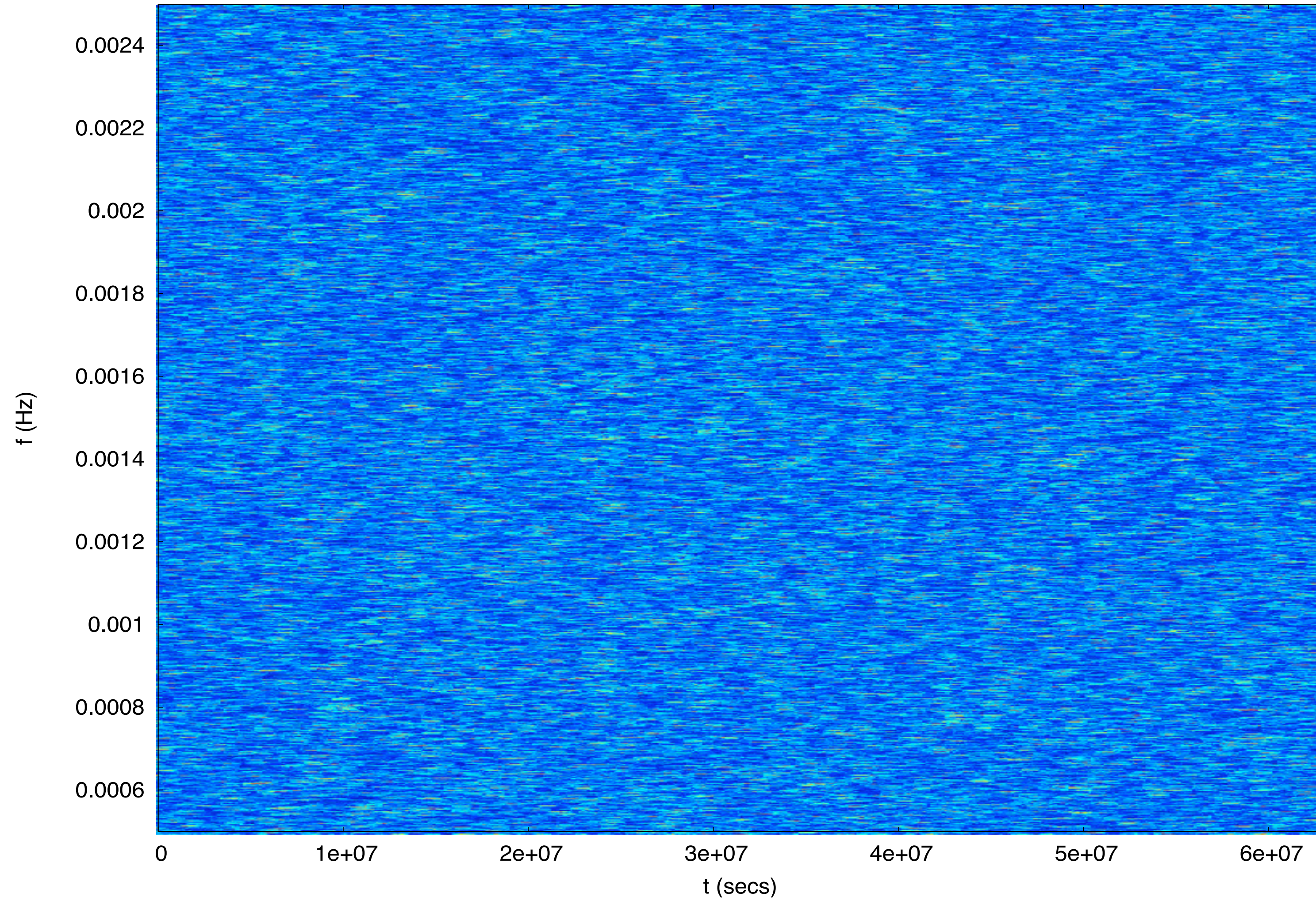


# Extreme Mass Ratio Inspirals



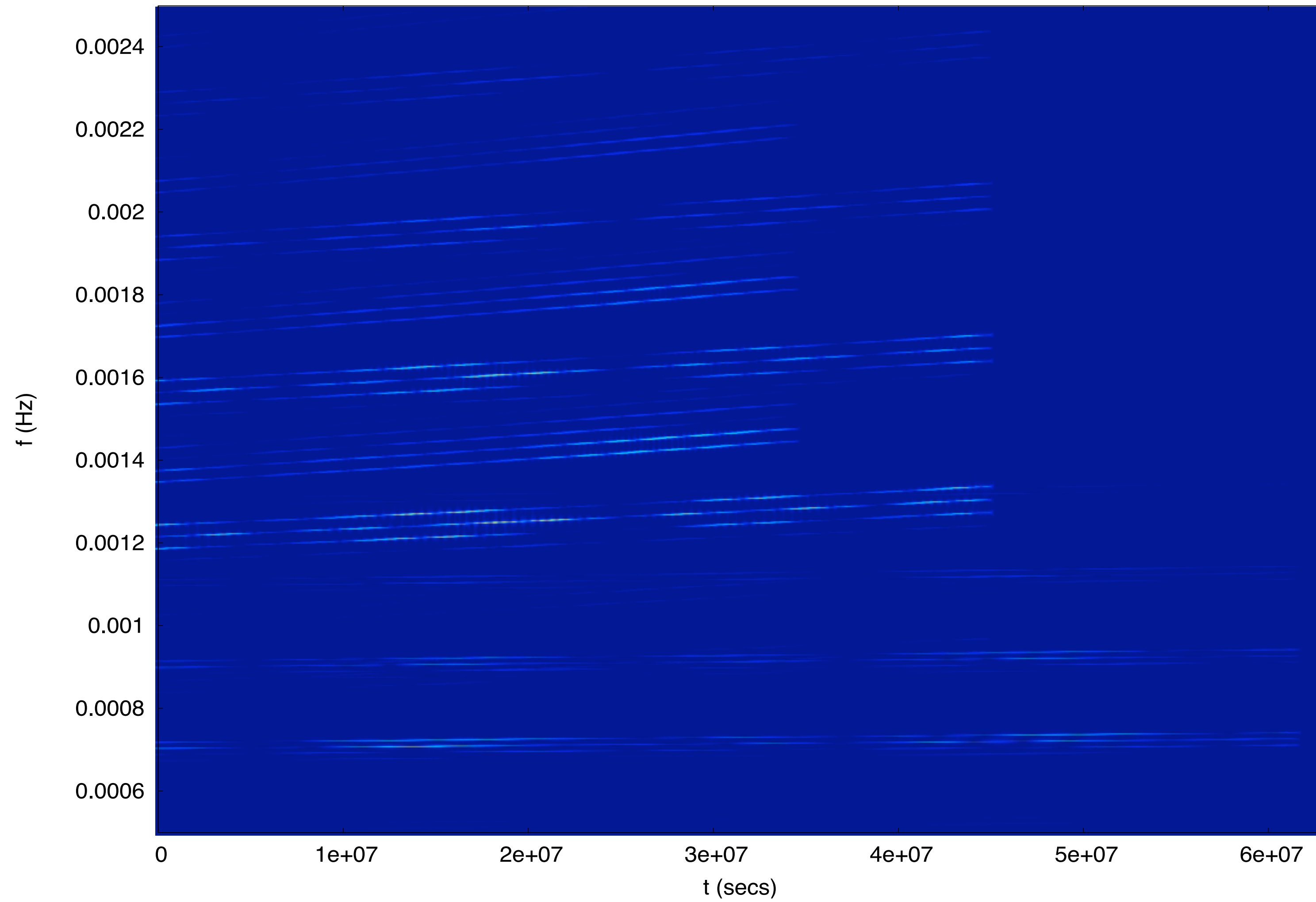


# Extreme Mass Ratio Inspirals

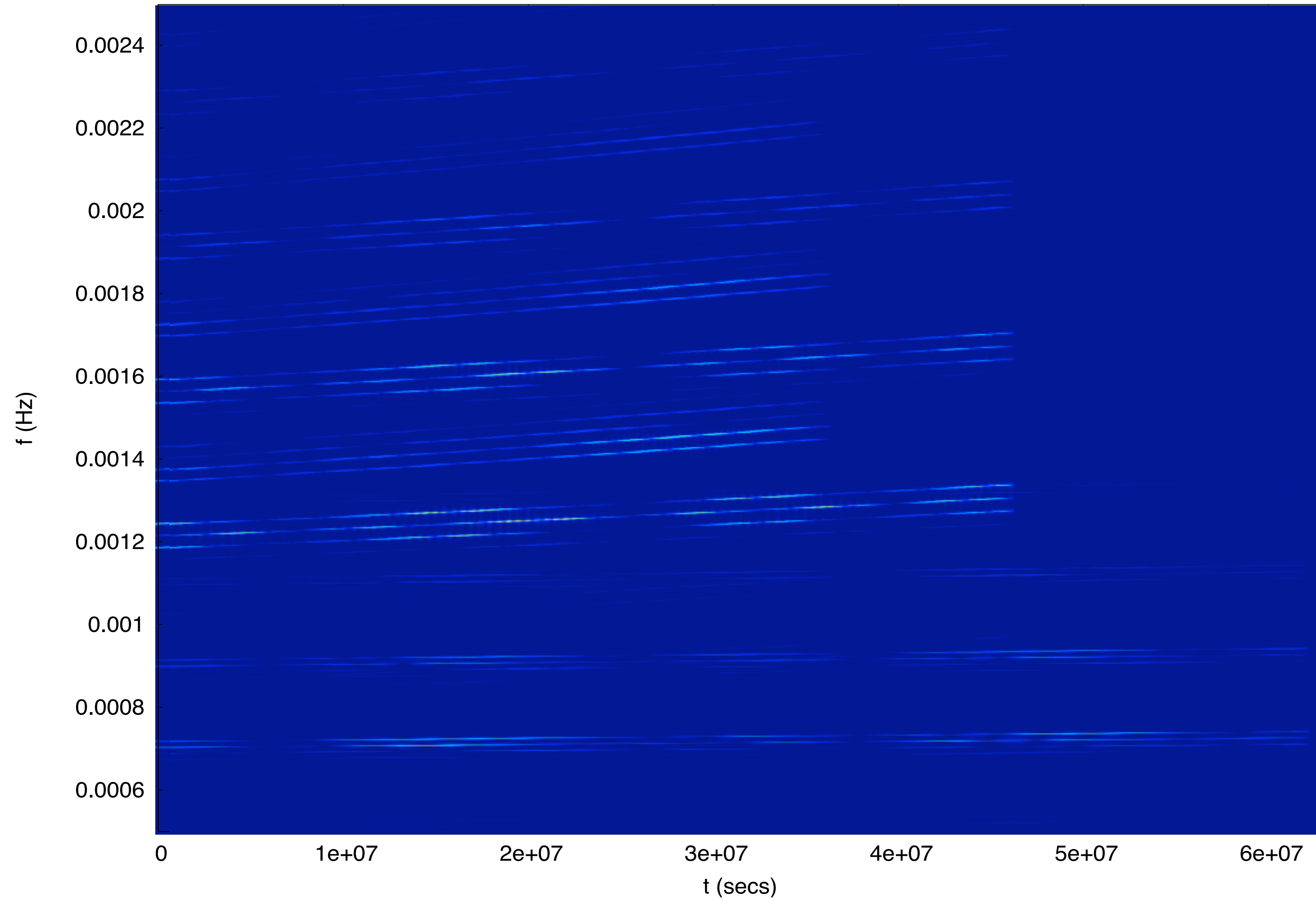




# Extreme Mass Ratio Inspirals



# Extreme Mass Ratio Inspirals

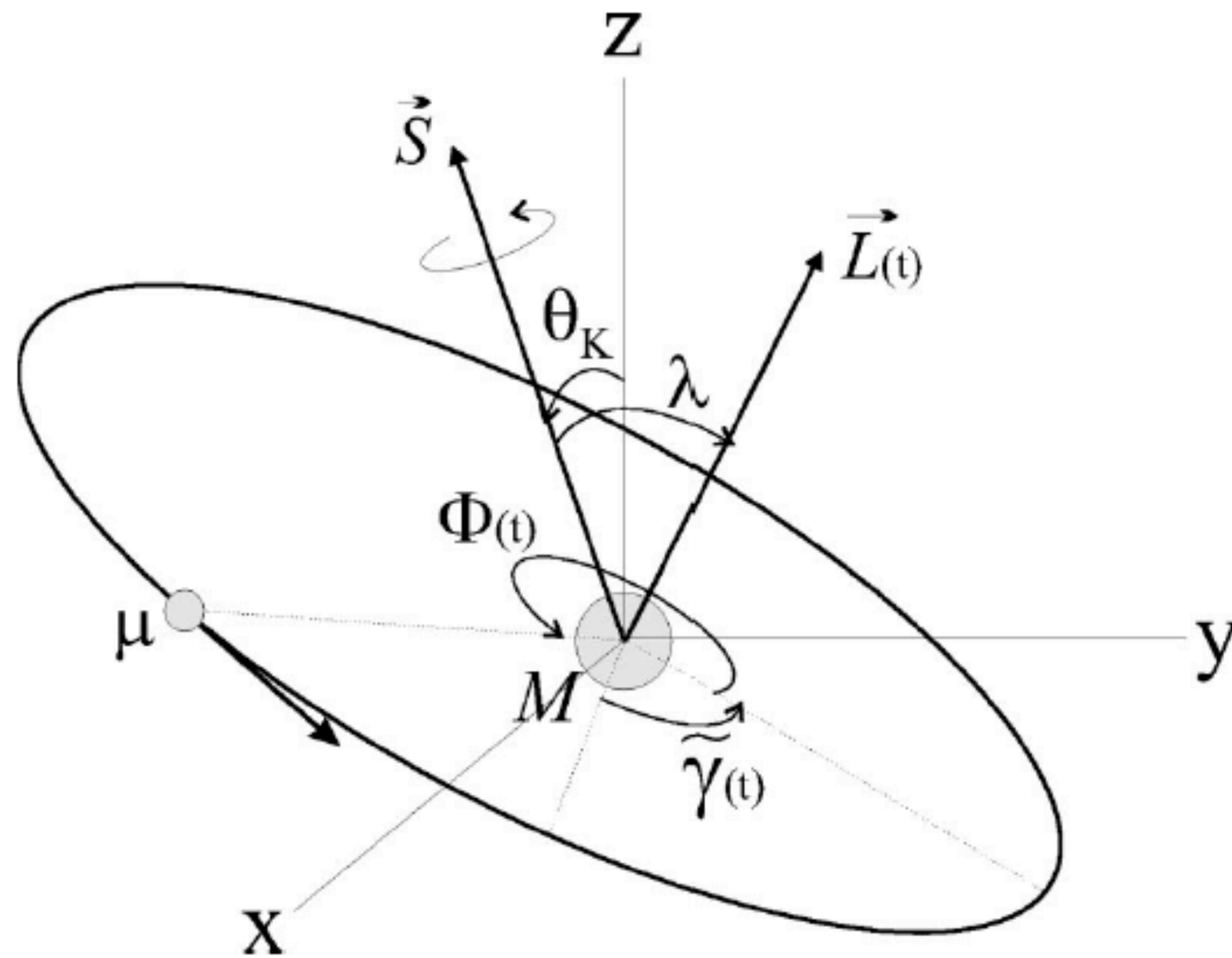




# EMRI Harmonics

$$f_{nmk} = n\nu + m f_{\tilde{\gamma}} + k f_{\alpha}$$

BC Kludge  $m = 2$   $k \in [-2, 2]$



$\nu$  = azimuthal orbital frequency  
 $f_{\tilde{\gamma}}$  = perihelion precession frequency  
 $f_{\alpha}$  = orbital plane precession frequency

# EMRI Harmonics

$$f_{nmk} = n\nu + m f_{\tilde{\gamma}} + k f_{\alpha}$$

BC Kludge  $m = 2$   $k \in [-2, 2]$

$$f_{\tilde{\gamma}} = 3\nu(2\pi\nu M)^{2/3}(1 - e^2)^{-1} \left[ 1 + \frac{1}{4}(2\pi\nu M)^{2/3}(1 - e^2)^{-1}(26 - 15e^2) \right] \\ - 6\nu \cos \lambda (S/M^2)(2\pi M\nu)(1 - e^2)^{-3/2}$$

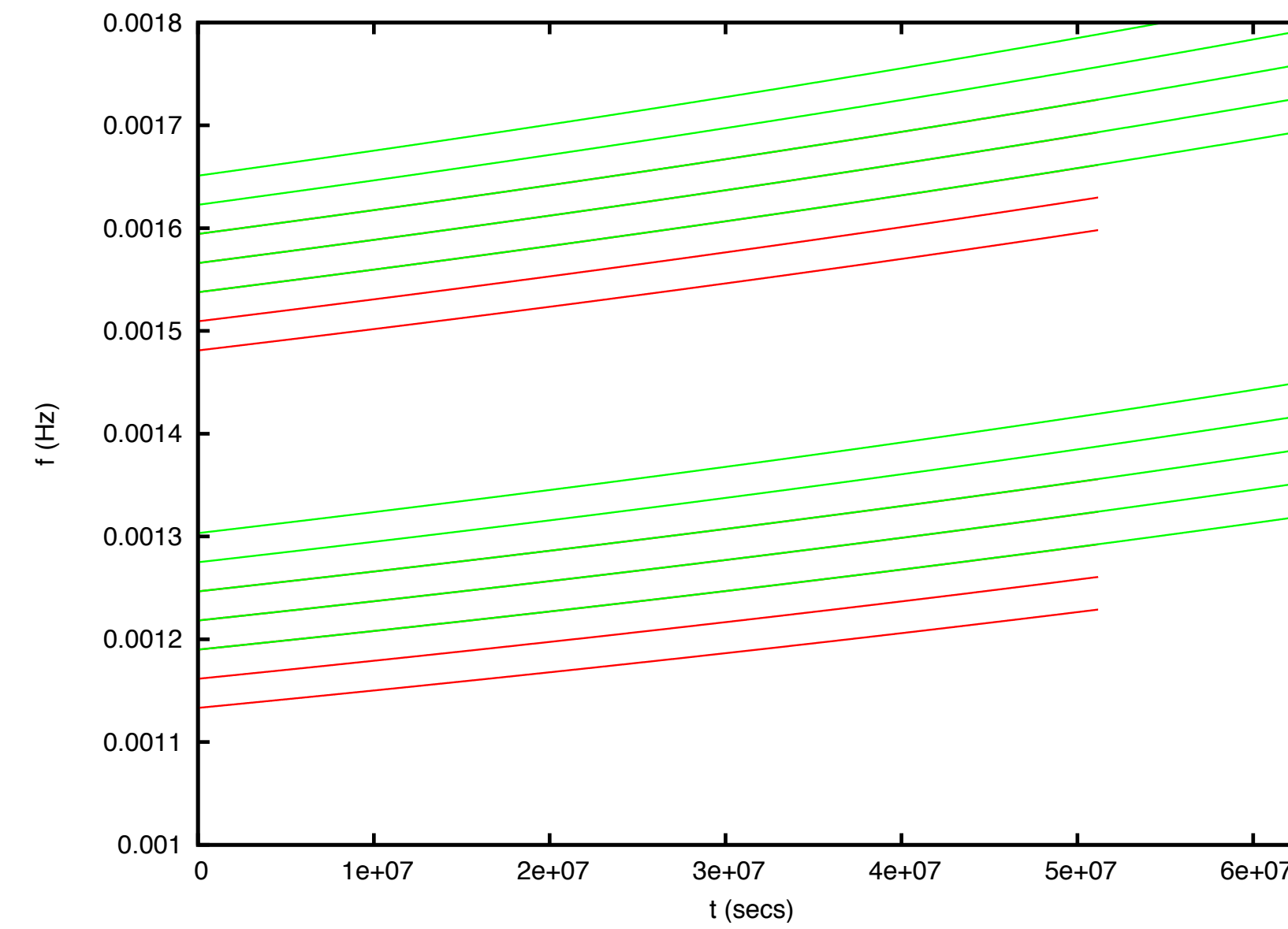
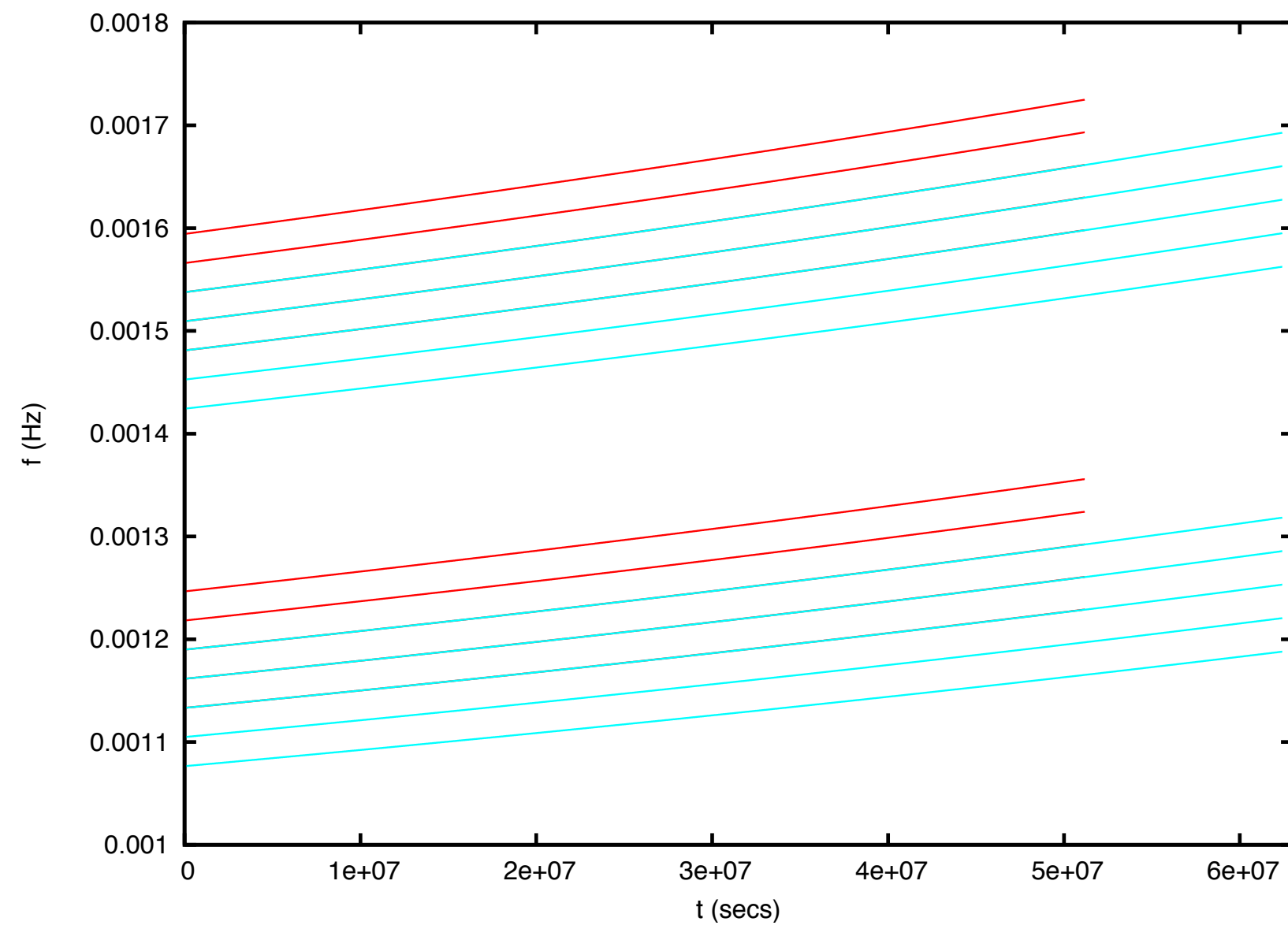
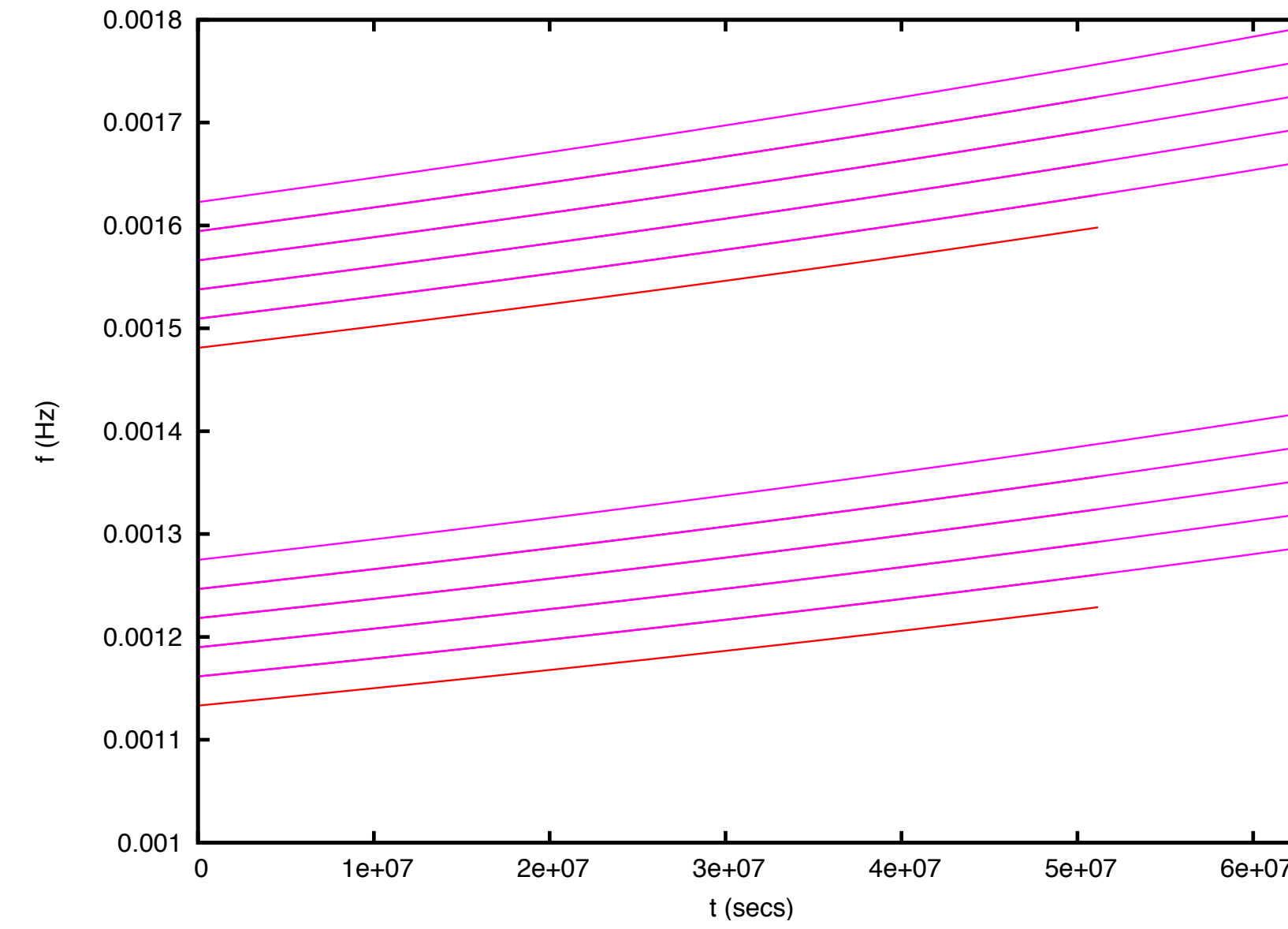
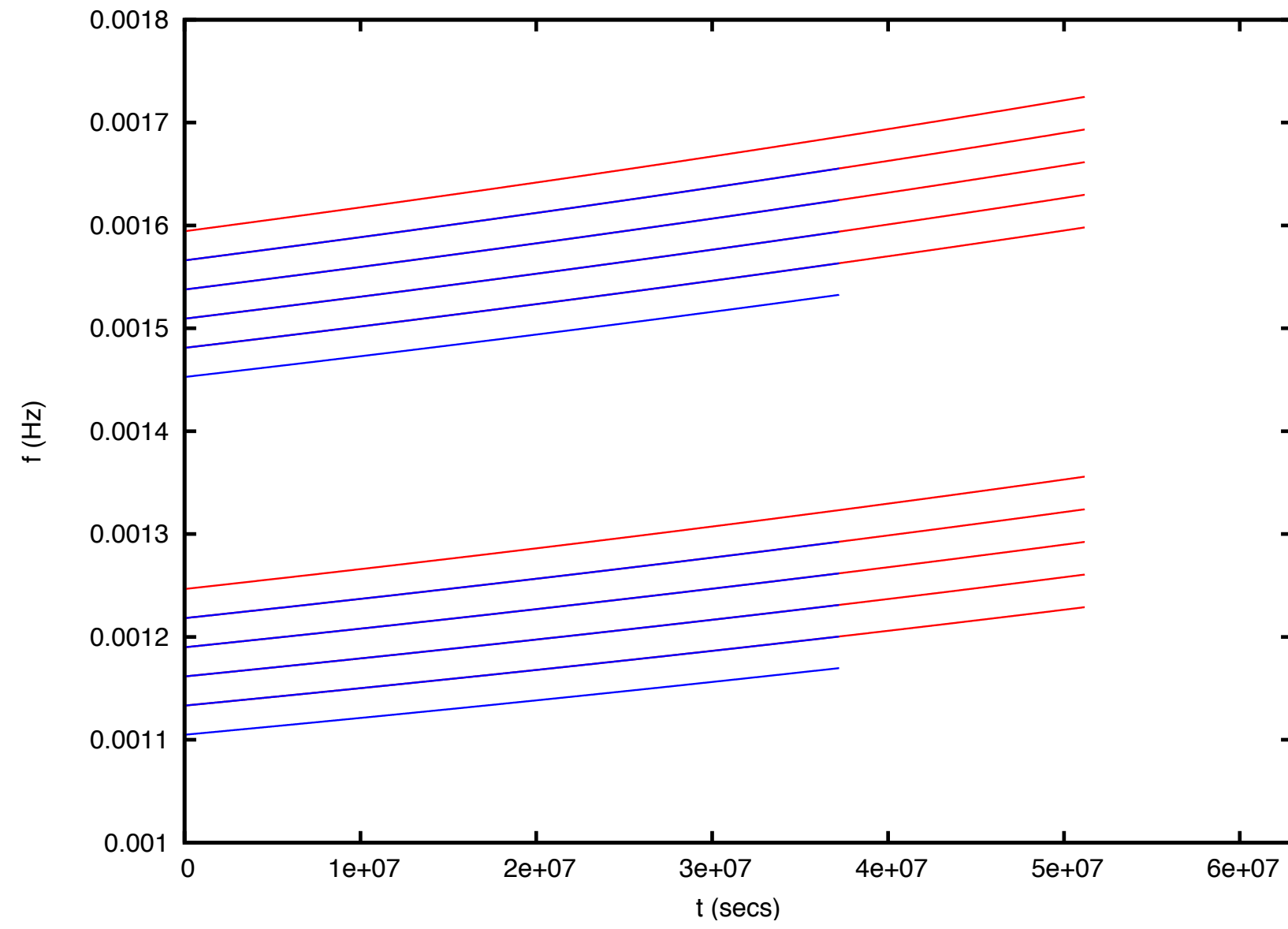
$$f_{\alpha} = 2\nu(S/M^2)(2\pi M\nu)(1 - e^2)^{-3/2}$$

harmonic mismatch

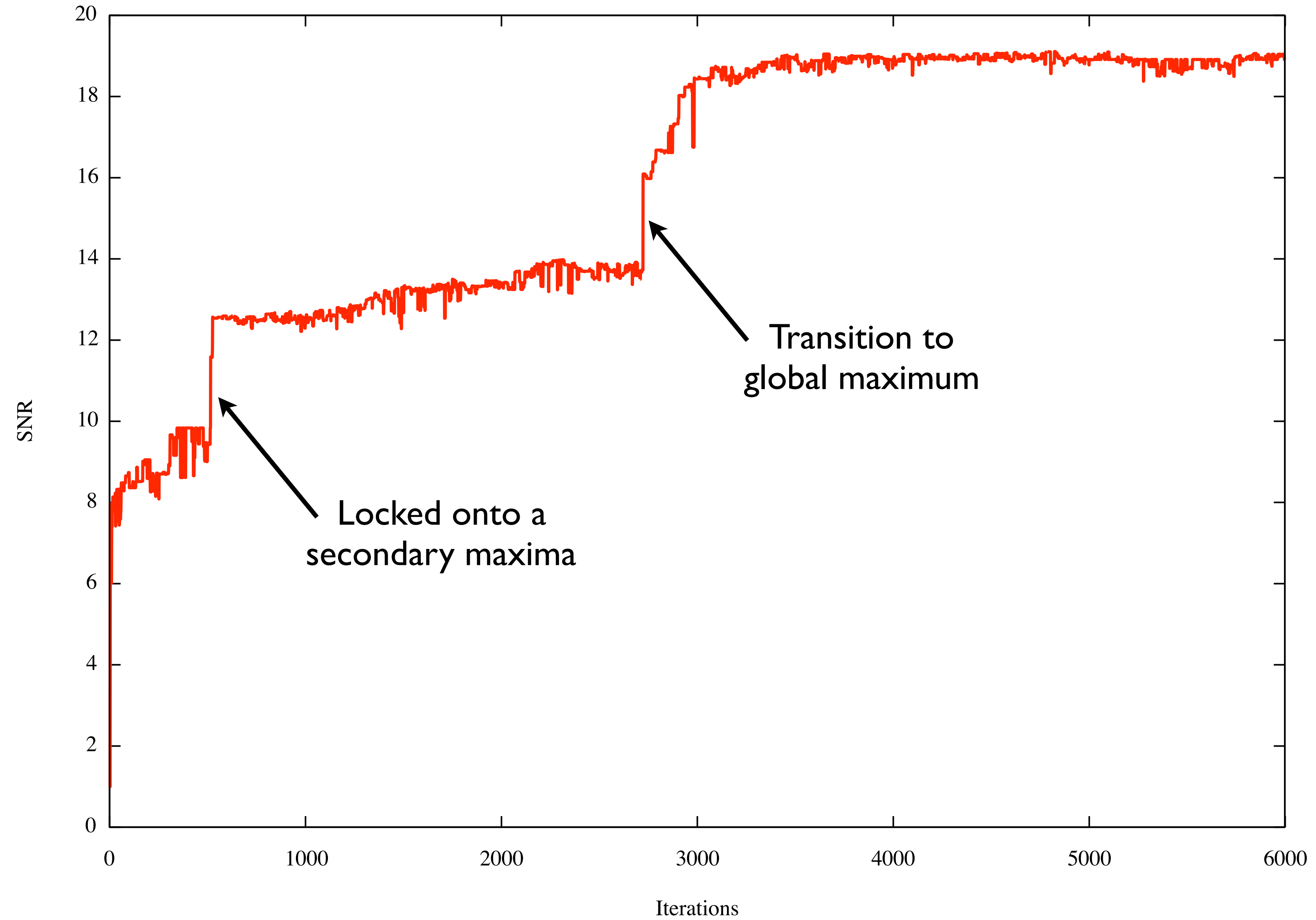
$$f_{n2k} = f_{n'2k'} \\ \dot{f}_{n2k} = \dot{f}_{n'2k'}$$



# Sideband Secondaries



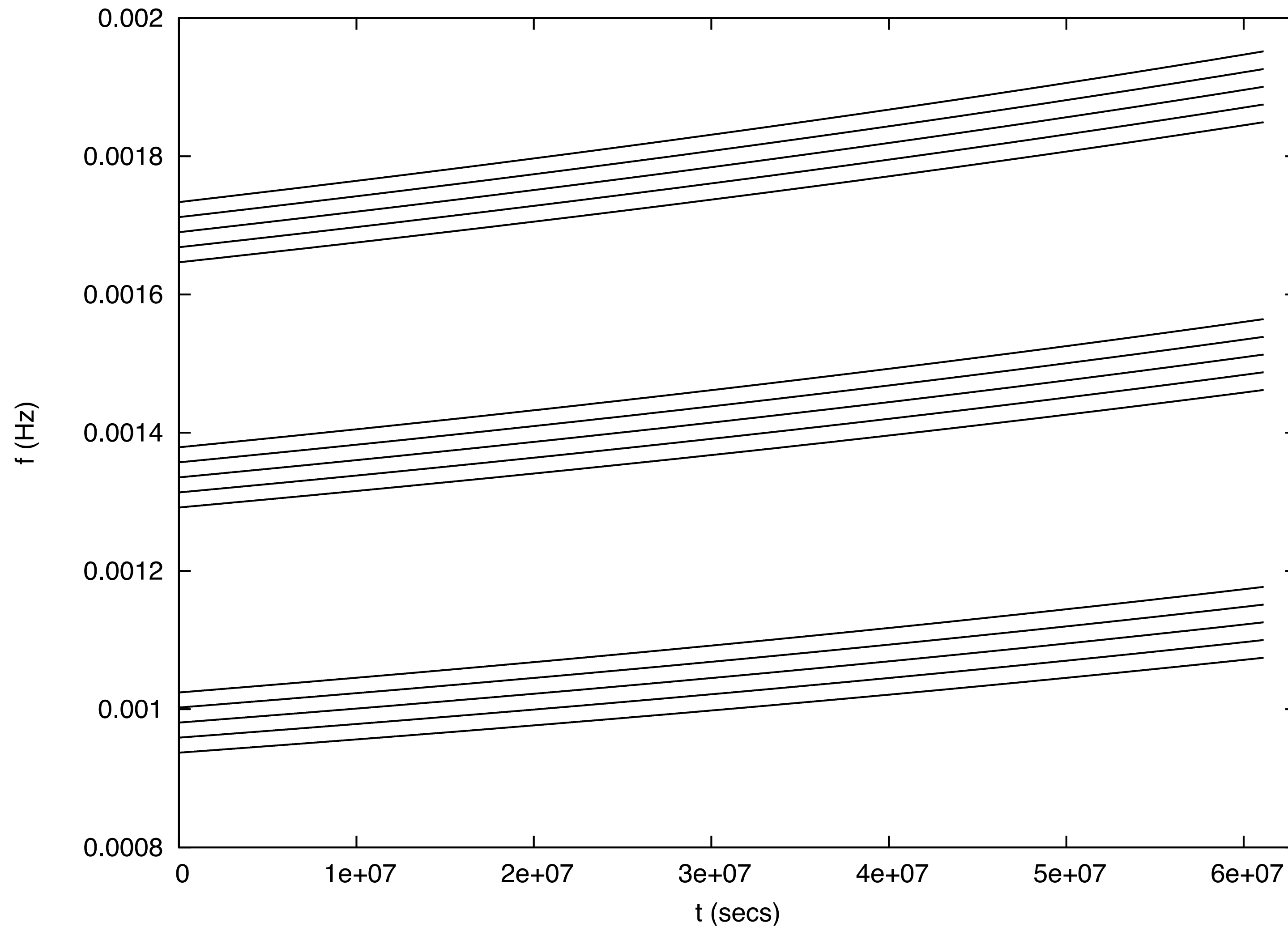
# Detecting Extreme Mass Ratio Inspirals





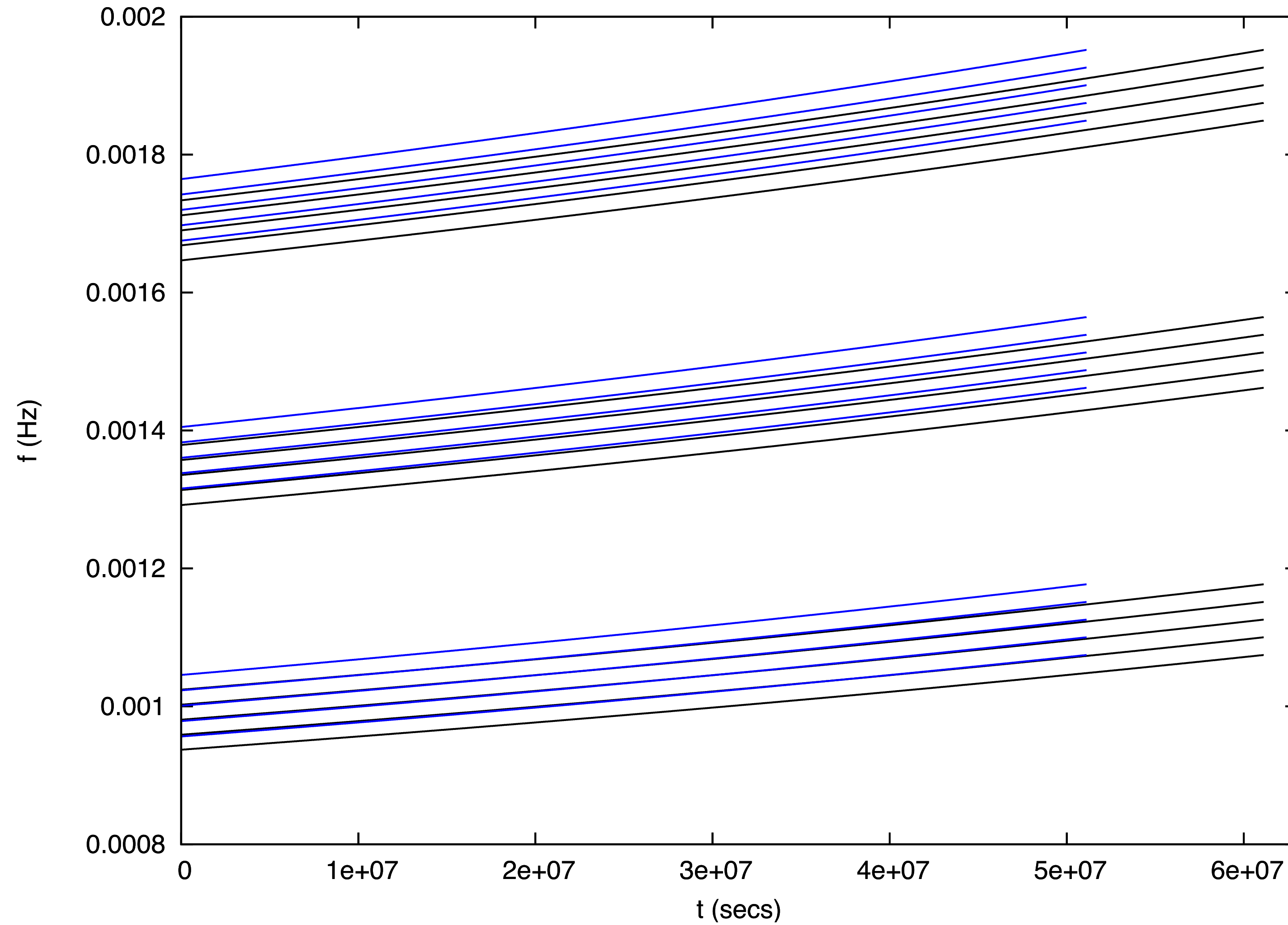
# Analytic Maximization

$$\{t_p, \phi_0, D_L\}$$



# Analytic Maximization

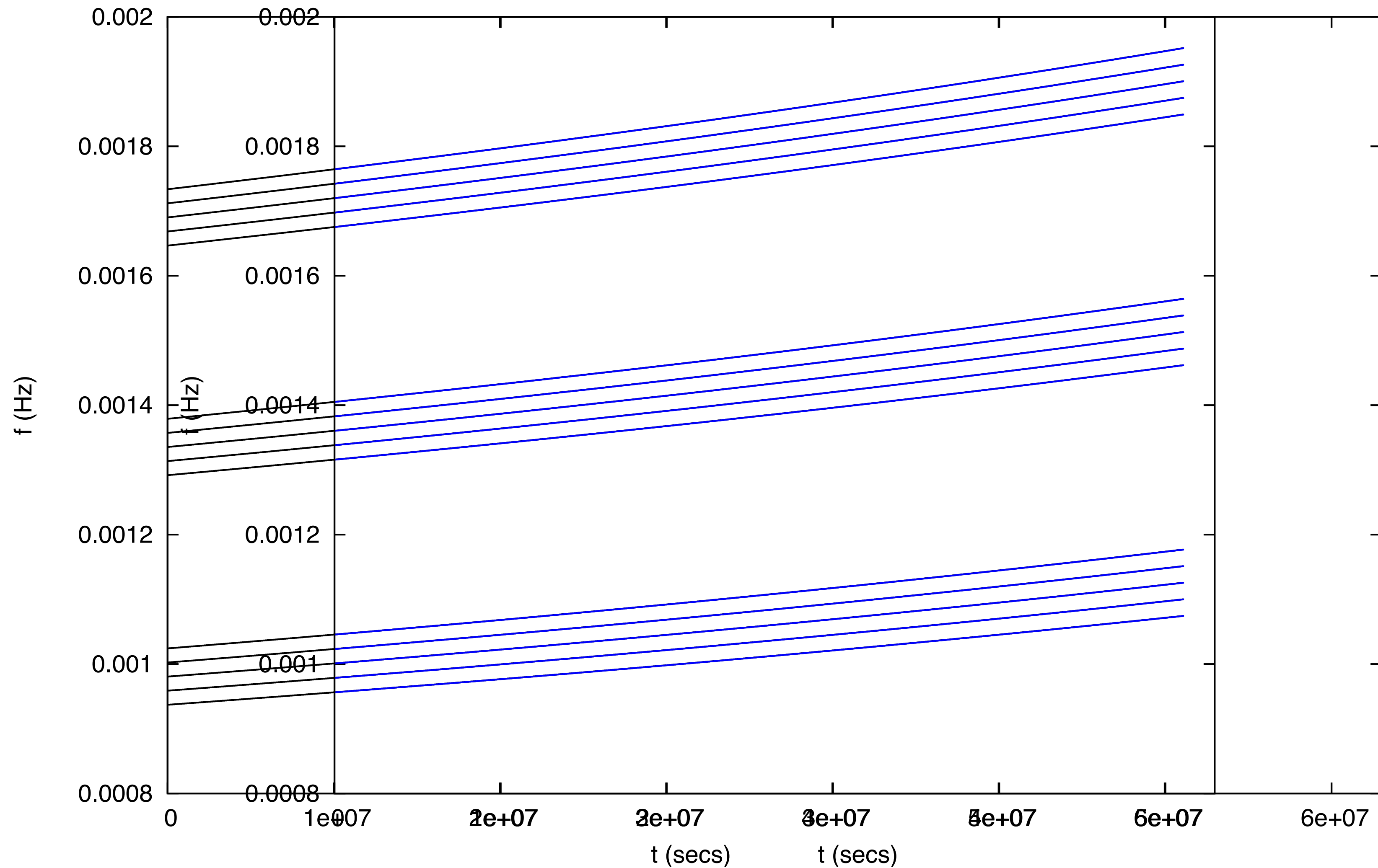
$$\{t_p, \phi_0, D_L\}$$



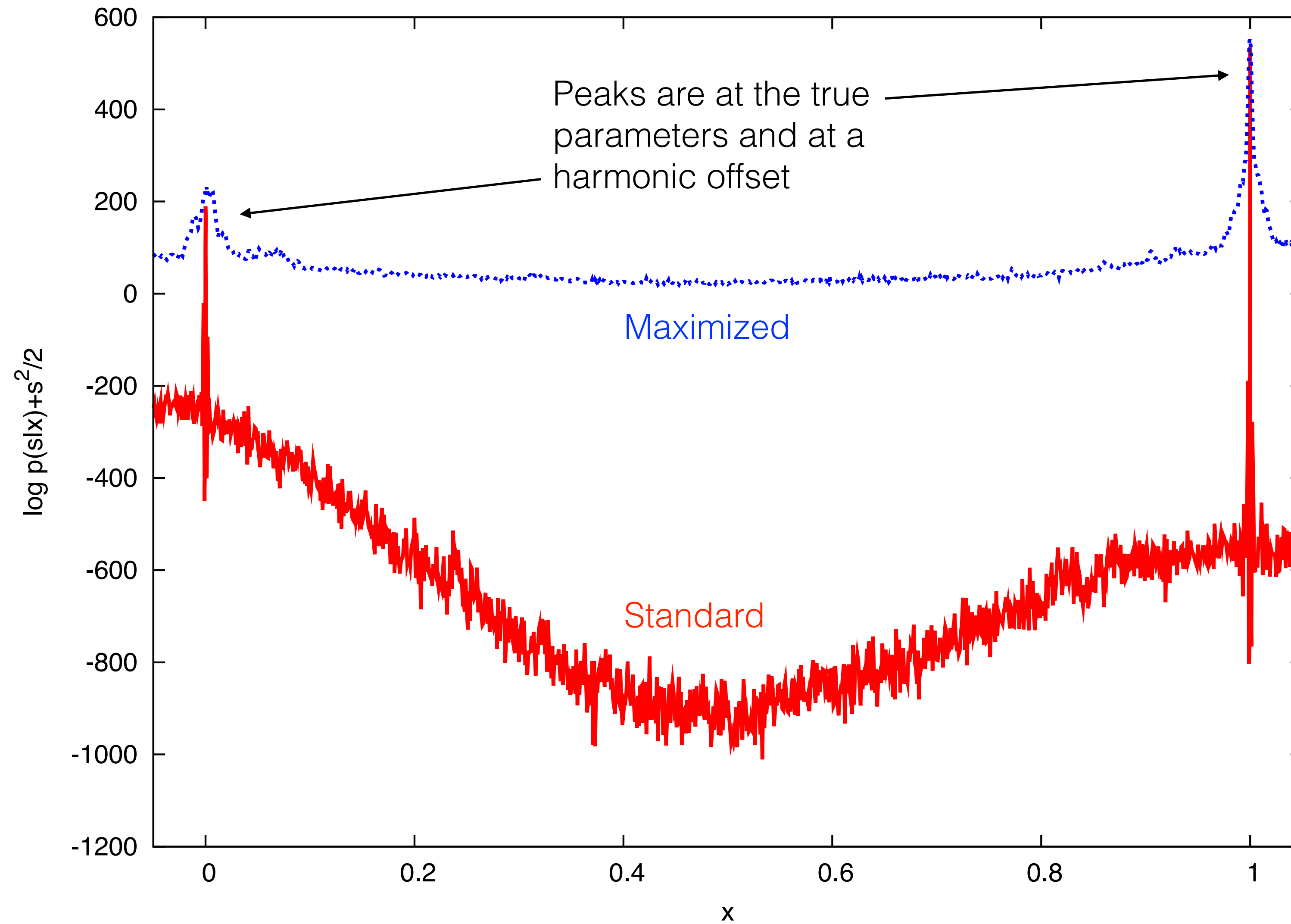


# Analytic Maximization

$$\{t_p, \phi_0, D_L\}$$



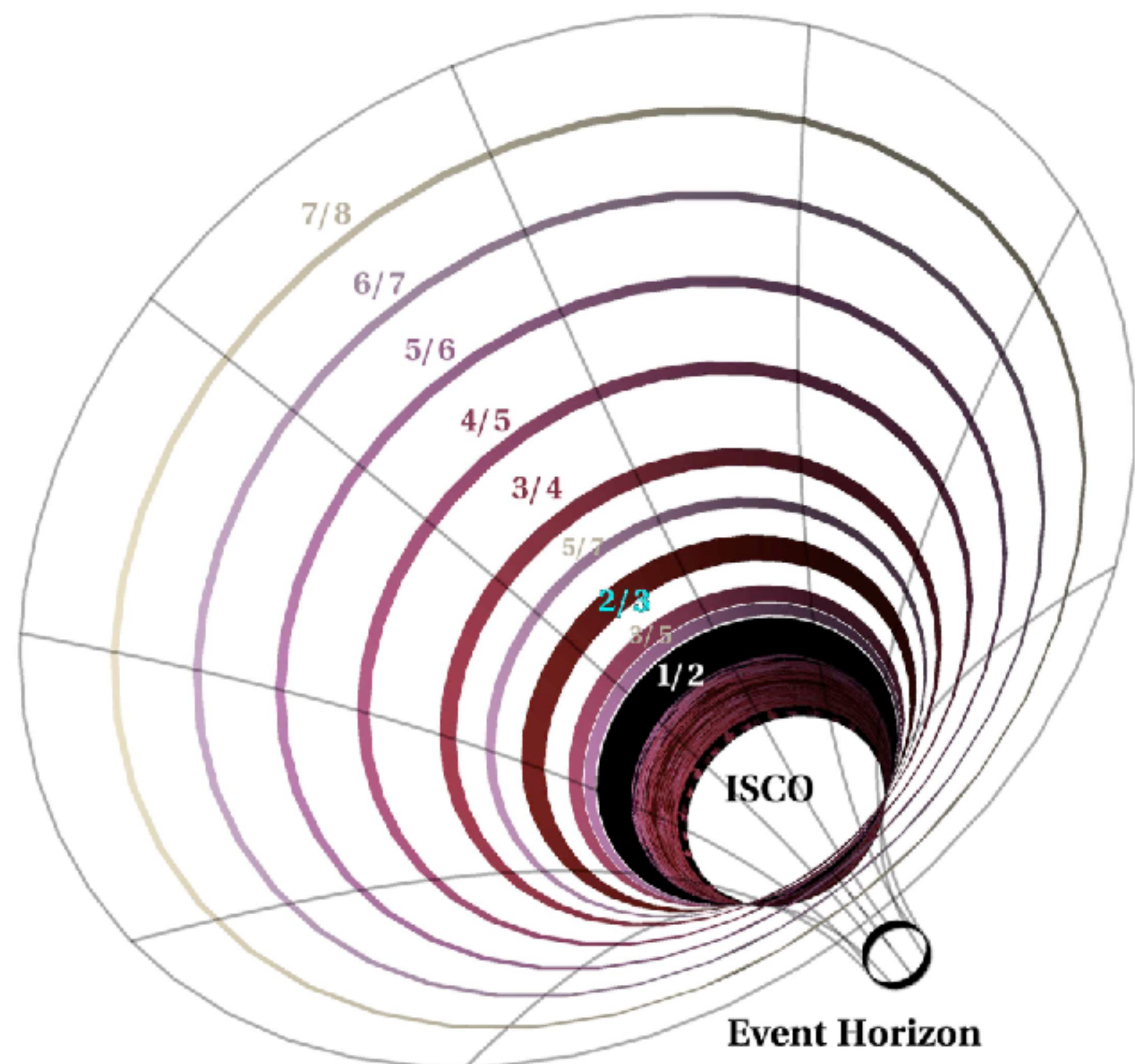
# Analytic Maximization of the Likelihood



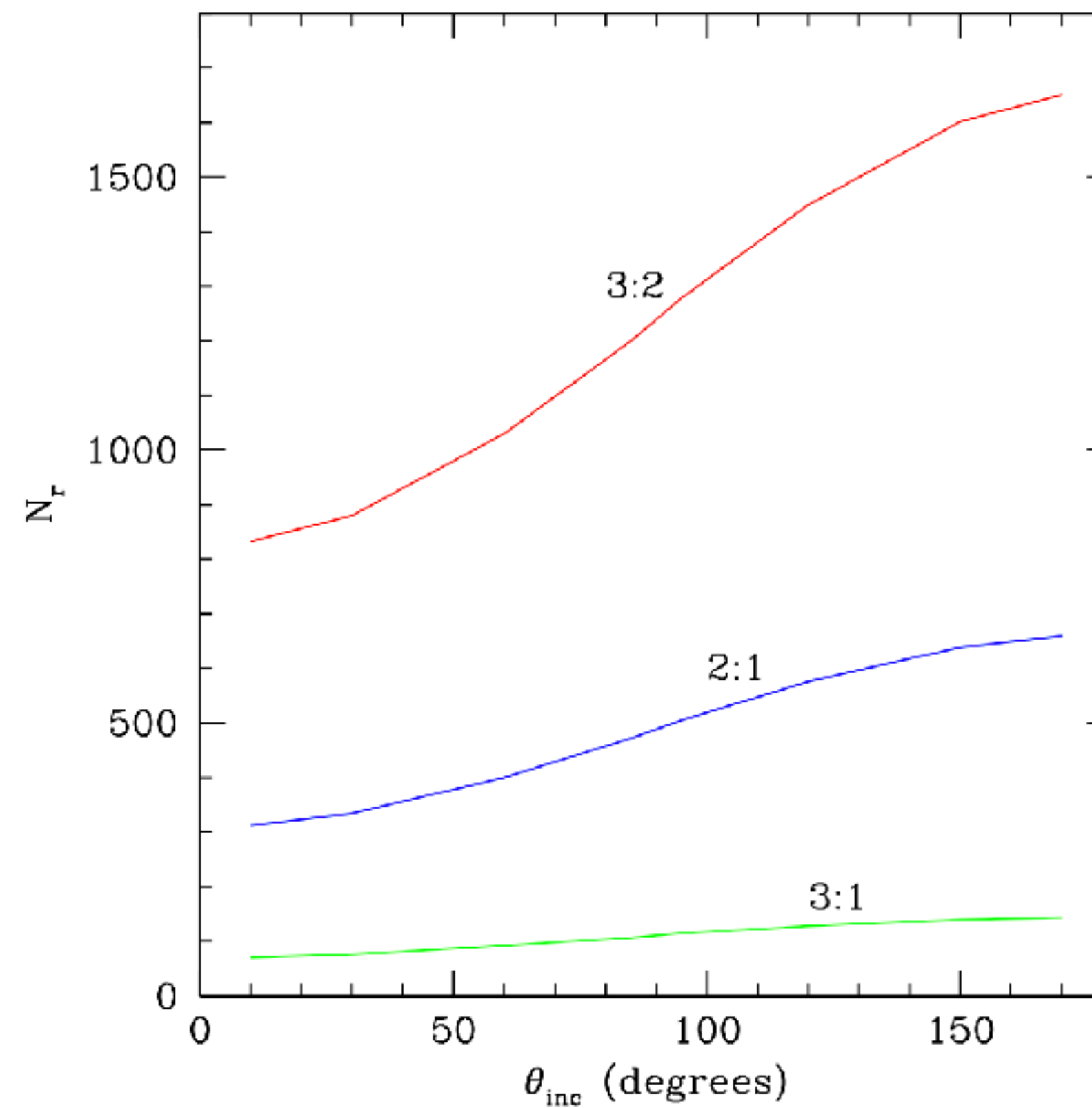


Extras

# Other challenges for EMRIs: Resonances

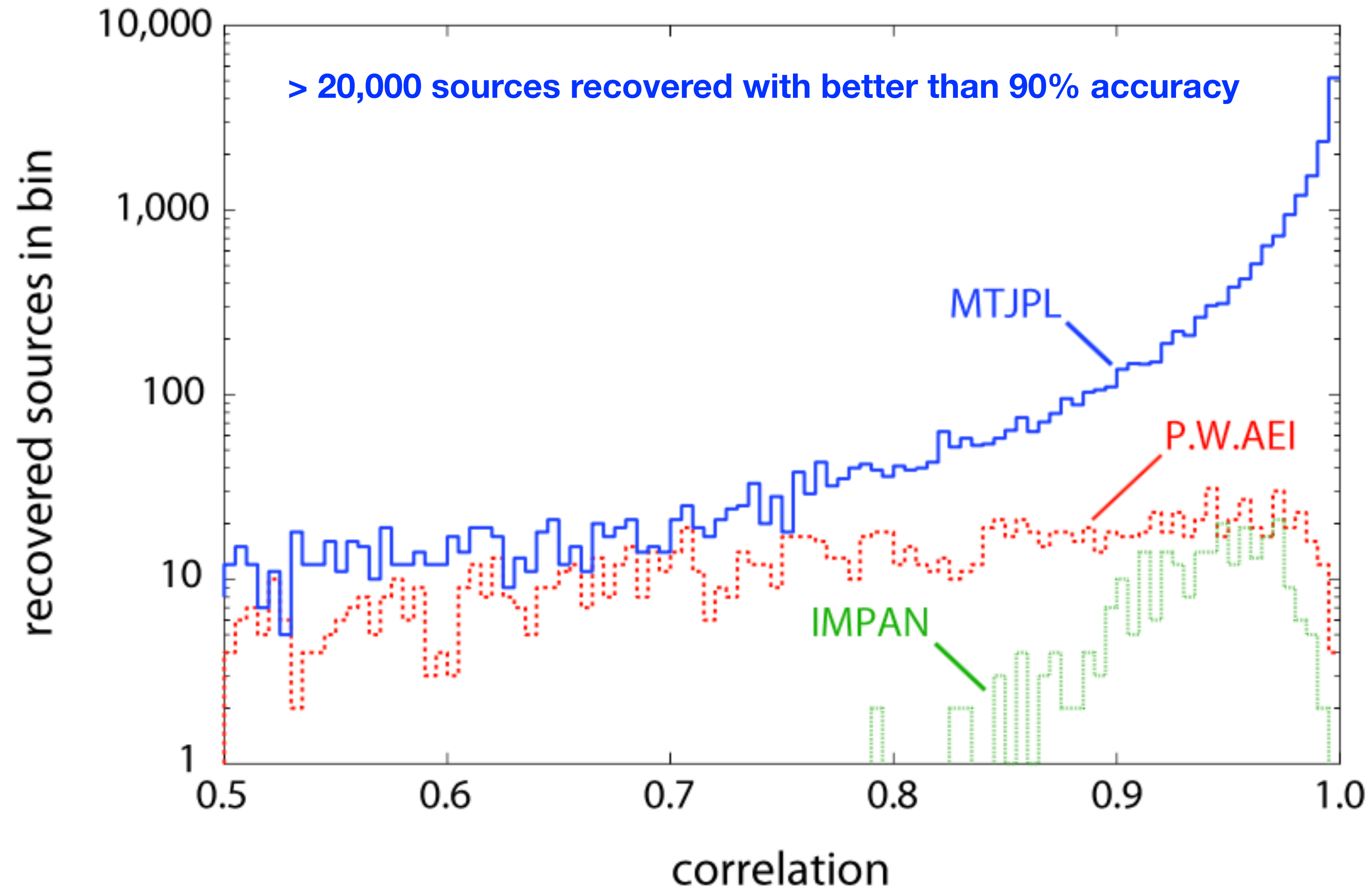


[Brink, Geyer, Hinderer 13]



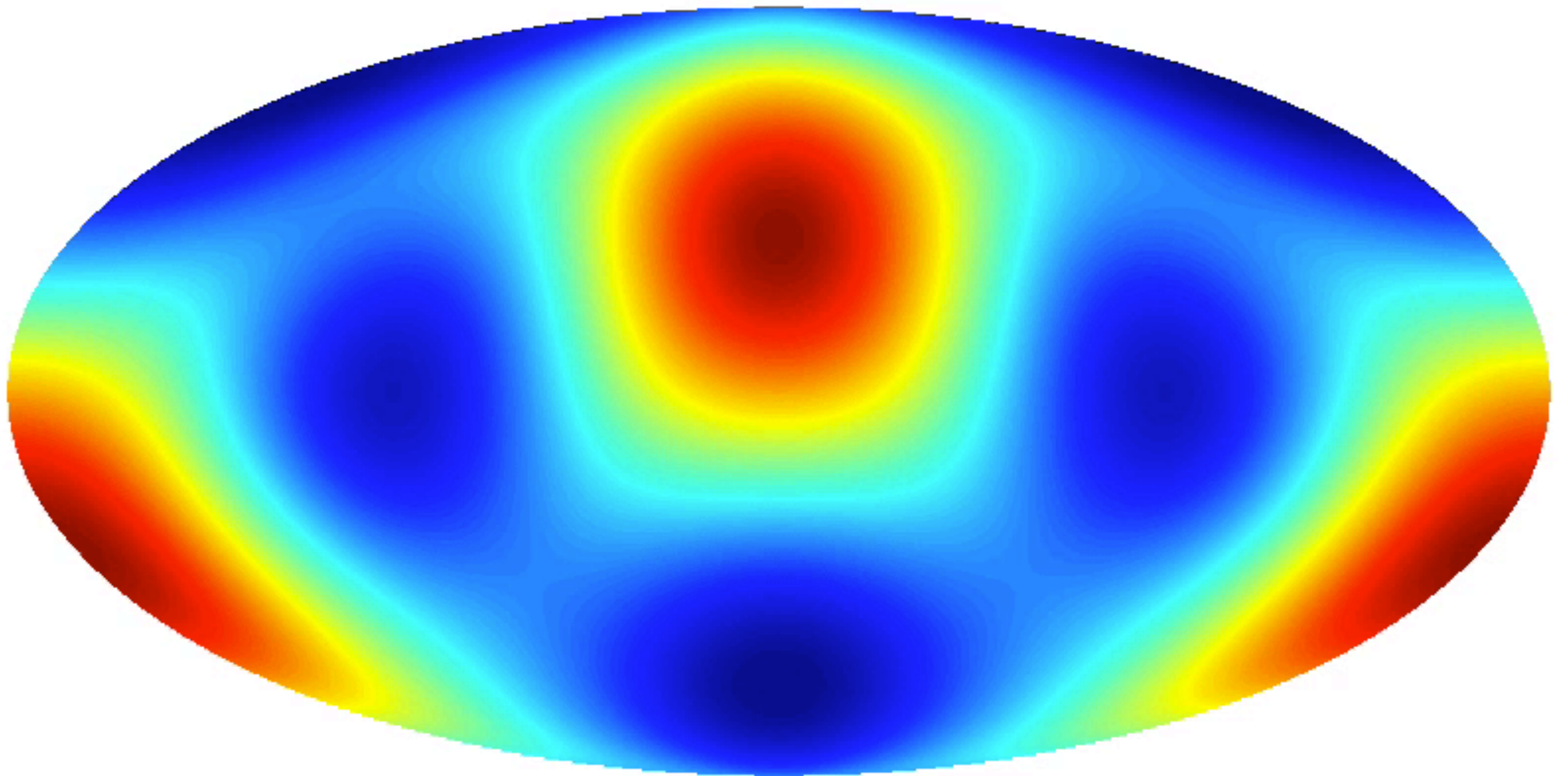
[Ruangsri, Hughes 14]

# Galactic Binaries in past Mock LISA Data Challenges



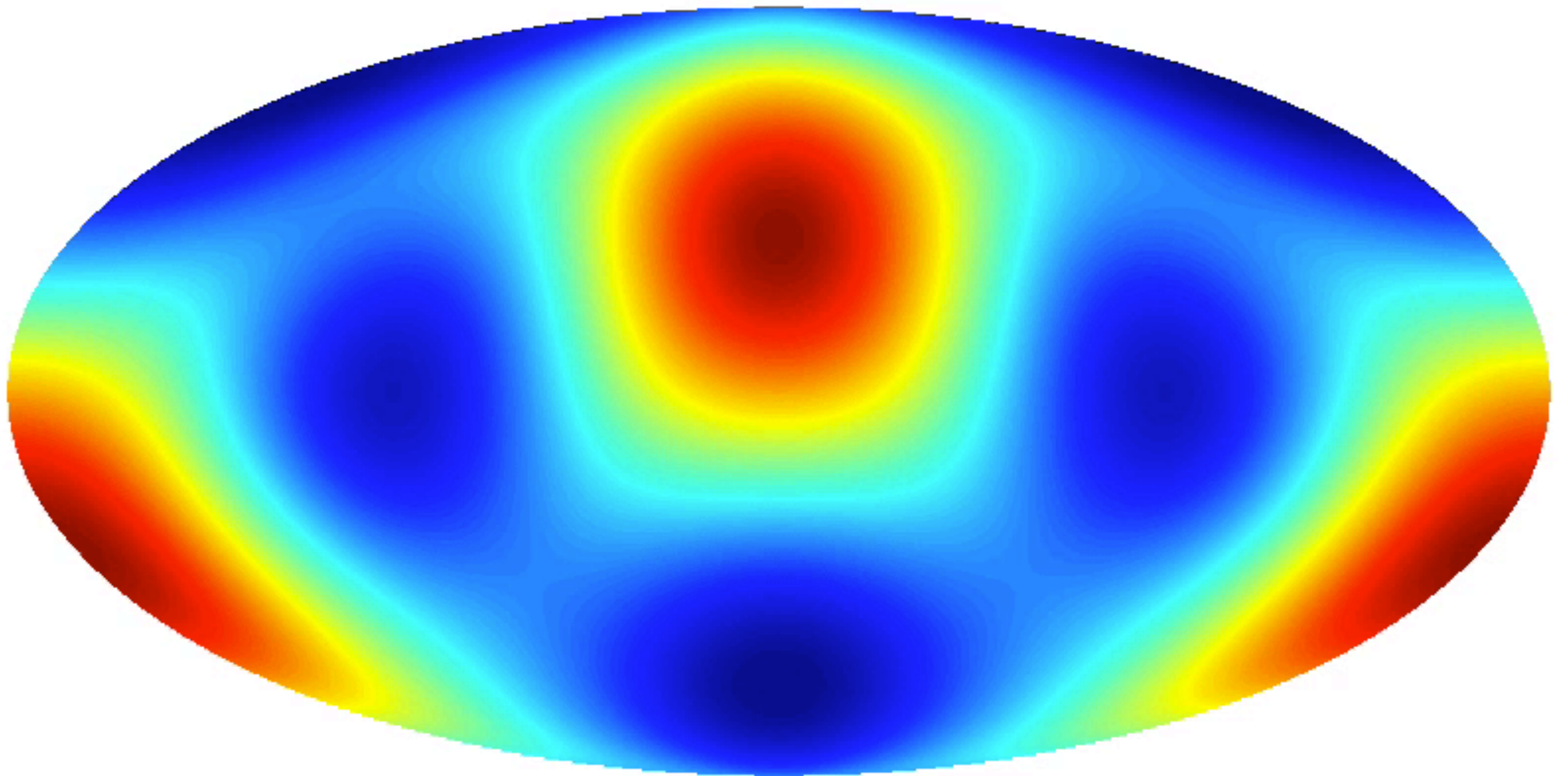


Major Challenge: White Dwarf Foreground



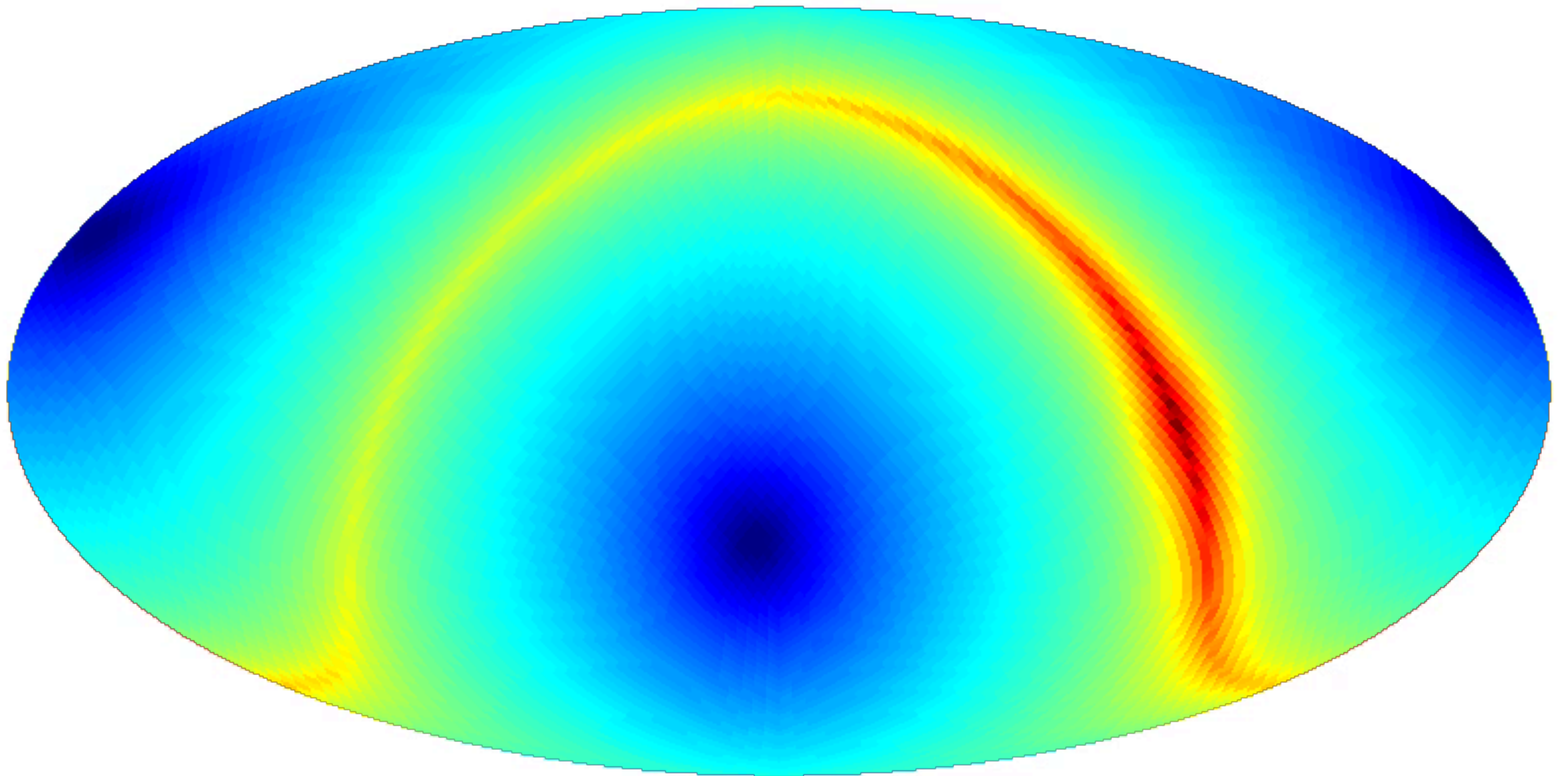


Major Challenge: White Dwarf Foreground



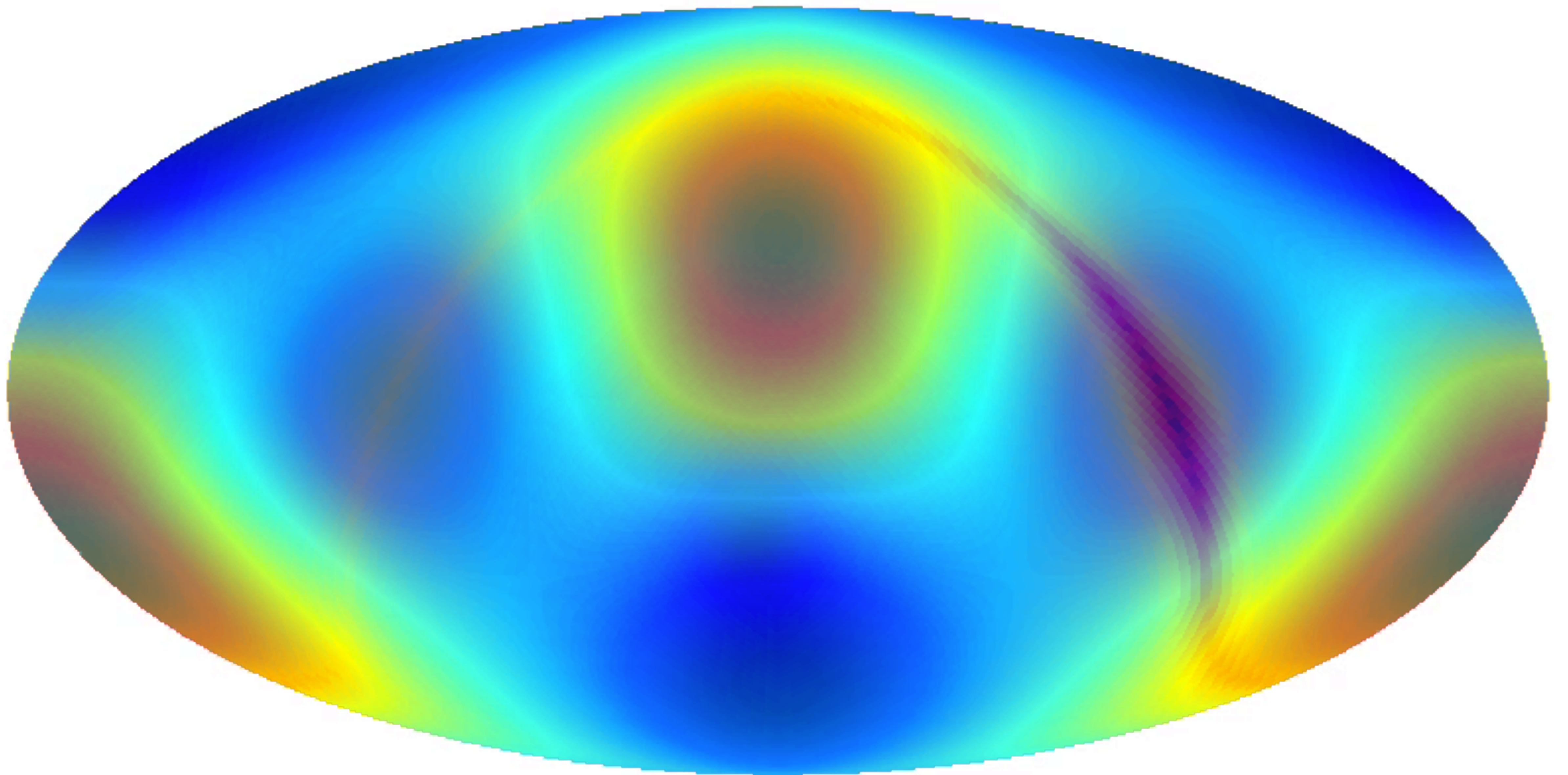


Major Challenge: White Dwarf Foreground



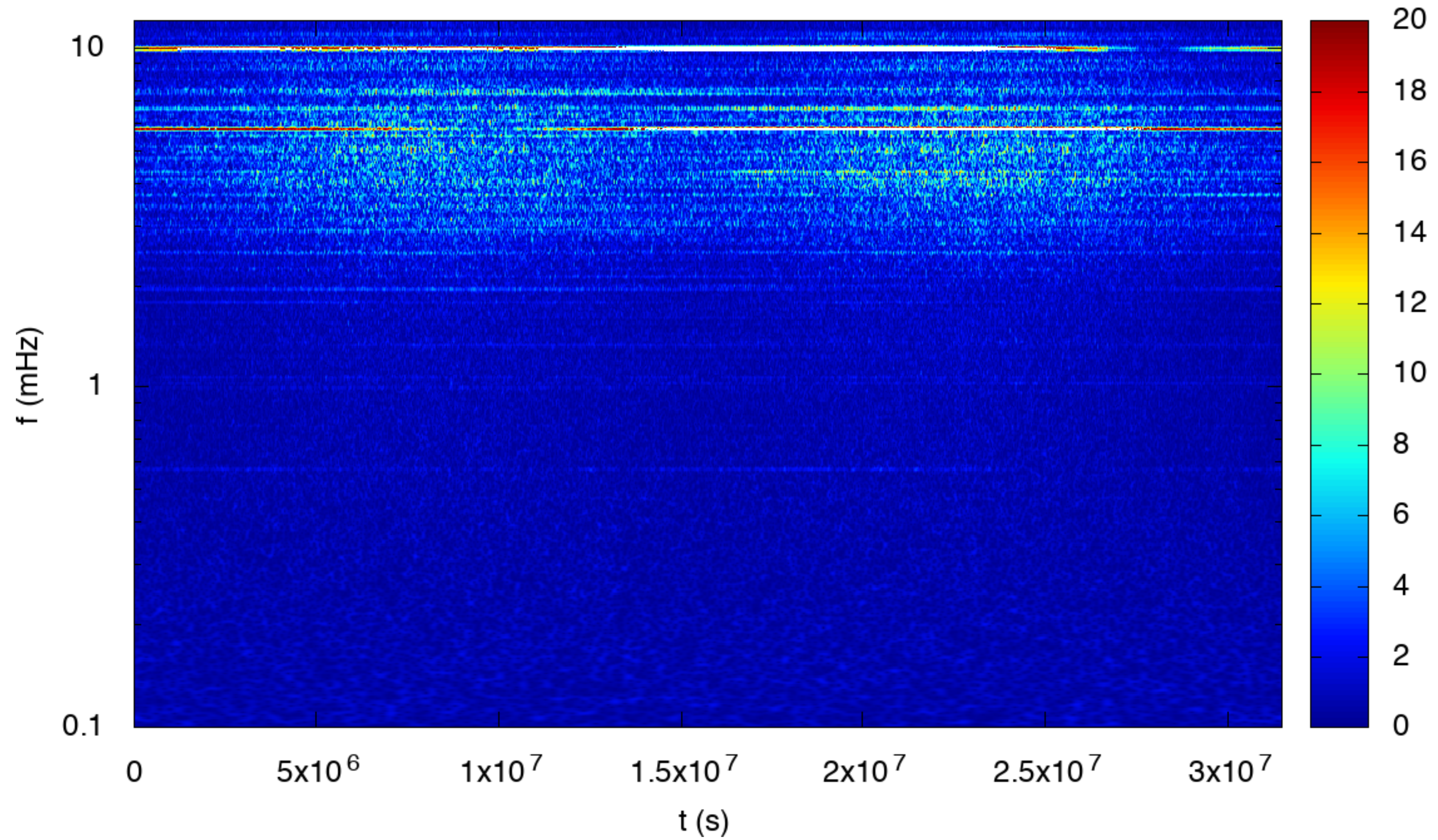


Major Challenge: White Dwarf Foreground



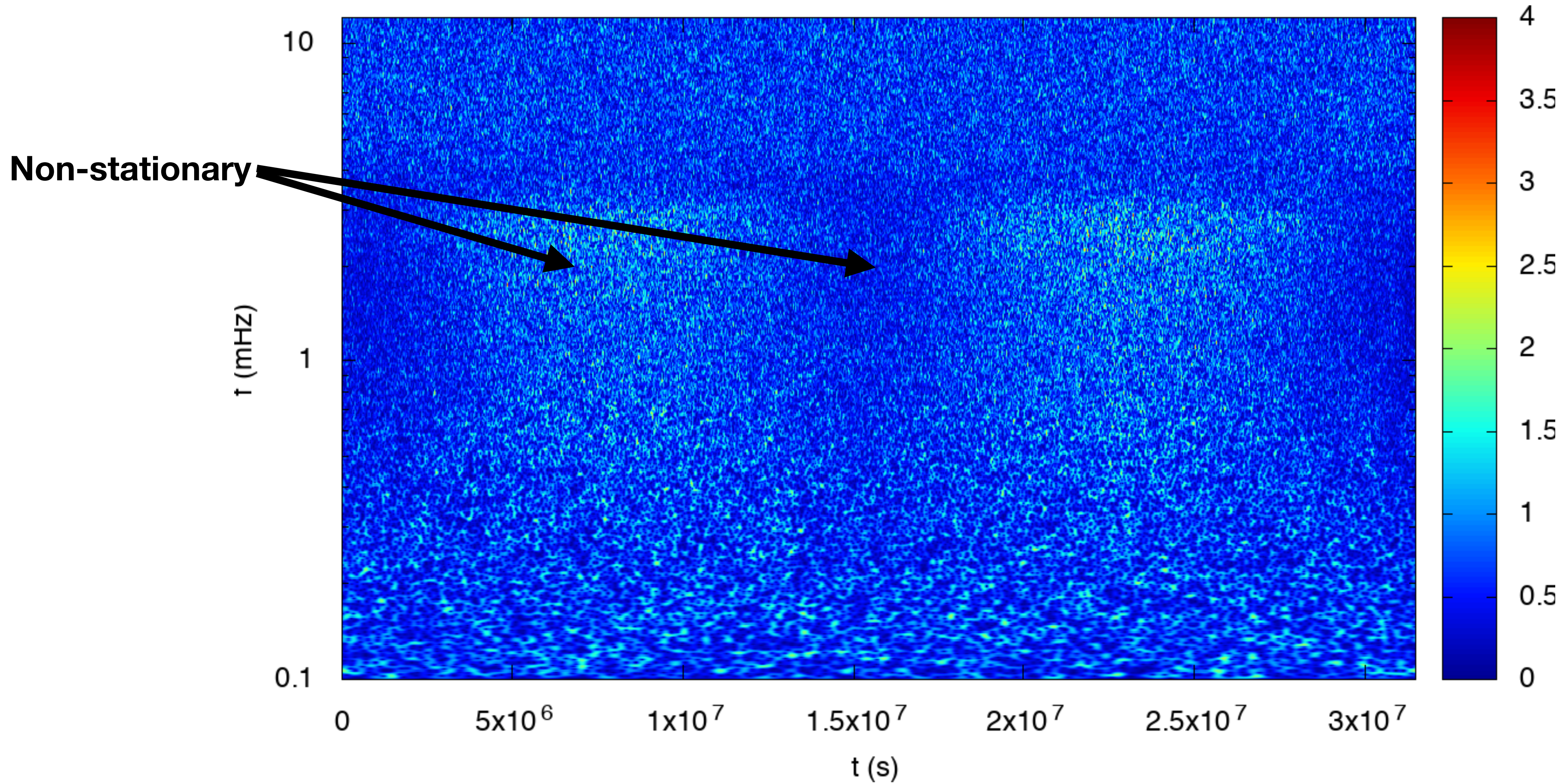


# Whitened Galaxy + Instrument noise spectrogram, 1 year





# Whitened Galactic Confusion + Instrument noise spectrogram, 1 year





# Galaxy + BH + Instrument noise spectrogram, 1 year

